

Koninklijk Nederlands Meteorologisch Instituut Ministerie van Verkeer en Waterstaat

### Rayleigh-cloudy winds

Gert-Jan Marseille - KNMI



- Motivation
  - Until recently we have not been able to produce a high quality Rayleigh-cloudy wind product
- Introduction on Rayleigh channel winds in clear air conditions Rayleigh-clear
- Procedure to retrieve high quality Rayleigh-cloudy winds
- Rayleigh-cloudy winds statistics
- Conclusions

#### Rayleigh winds in clear air conditions



# • Rayleigh Response $RR_0 = \frac{N_A - N_B}{N_A + N_B}$

• The Rayleigh Response value is a function of temperature, pressure and the Doppler shifted frequency:  $RR_0 = RR_0(T,P,\Delta f)$ 



Available as a 3-dimensional table

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#### Rayleigh winds in cloudy/aerosol conditions



• Rayleigh Response 
$$RR = \frac{N_A + n_A - N_B - n_B}{N_A + n_A + N_B + n_B}$$

 RR = RR(T,P,Δυ,ρ); the scattering ratio, ρ, is a measure of Mie scattering relative to Rayleigh scattering in the atmosphere:

$$\rho = \frac{\beta_m + \beta_p}{\beta_m}$$

- This would require a 4-dimensional table
- Instead: alternative approach (next slide)

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#### Impact of Mie return on Rayleigh Response

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#### Make use of NWP data



$$H_{\text{NWP}}(u, v) = -u \sin(\psi) - v \cos(\psi)$$
$$v_{\text{LOS}} = H_{\text{NWP}}(u, v) \sin(\theta)$$

 $\Delta f_{\text{NWP}} = v_{\text{LOS}}/(-\lambda/2)$ 

 $\psi$  is the azimuth angle  $\phi$  is the incidence angle  $\lambda$  is the laser wavelength



•  $HLOS_{NWP} => \Delta f_{NWP} => RR_0$  (clear air conditions)

- $\Delta RR = RR_{meas} RR_0$
- ΔRR is a combination of (i) Mie contribution, (ii) instrument noise and (iii) NWP model error
- Averaging over a long time period reduces noise and model error contribution
- ➤ What is left is Mie contribution => curve fitting

$$\Delta RR(\rho) = a \left( 1 - e^{-b_0(\rho - 1)} \right)$$

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It turned out that parameter a is a function of the Doppler shifted frequency:

 $a = a_0 + a_1 \Delta f$ 

Rayleigh Response model, including Mie contribution

 $RR(P, T, f_0 + \Delta f, \rho) = RR_0(P, T, f_0 + \Delta f) + \Delta RR(\rho, \Delta f)$ 3D RR<sub>0</sub> table (assuming  $\rho=1$ )

with  $\Delta RR(\rho, \Delta f) = (a_0 + a_1 \Delta f) (1 - e^{-b_0(\rho - 1)})$ 

(parameters  $a_0, a_1, b_0$  are obtained with the use of NWP model data)

Solve  $\Delta f$  from  $RR(P, T, f_0 + \Delta f, \rho) = RR_{\text{meas}}$ (by linearizing  $RR_0$ )

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 Aeolus Rayleigh-channel winds in cloudy conditions

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RR

submitted to QJRMS

#### Aeolus data coverage - 15 August 2019 ~02:53 UTC \_\_\_\_\_ D1





- Rayleigh-cloudy winds are similar to Mie-cloudy winds (visually)
- Rayleigh-cloudy winds have lower resolution, but are more representative to model winds (resolution)
- Both winds are complementary for NWP

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#### Rayleigh-cloudy winds statistics – FM-A period

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#### Rayleigh-cloudy winds statistics (ctd.)

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without parameterization





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with parameterization

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#### Rayleigh-cloudy monitoring; FM-A period



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- Parameters estimated on a weekly base; stable!
- Overall biases of Rayleigh-cloudy winds are very small after 16 February 2023 and will be in forthcoming reprocessing activities





- We have a procedure in place to retrieve good quality Rayleigh-cloudy winds
  - Bias-free with a random error slightly larger than for Rayleigh-clear winds
- Improved Rayleigh-cloudy winds are available in the operational data set since 16 Febuary 2023 and will come available for the complete mission in forthcoming reprocessing activities
- The impact of Rayleigh-cloudy winds for NWP is to be assessed; first results will be presented by Michael Rennie



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## backup

#### **Standard Rayleigh-clear statistics**





- 1-7 Dec. 2022
- (o-b) bias: 0.00 m/s
- (o-b) SMAD/STDEV: 4.24/4.82 m/s
- Better than Rayleigh-all (as expected, because Rayleighcloudy is worse than Rayleighclear)
- But note the different sample (510K vs. 845K observations)



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-300 -250 -200 -150

Doppler shift (MHz)



 $HLOS_{NWP} => \Delta f_{NWP} => RR_0$ 

 $\Delta RR = RR_{meas} - RR_0$ 

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- $\Delta RR$  is a combination of
  - Mie contribution \_\_\_\_
  - Instrument noise \_\_\_\_
  - NWP model error \_\_\_\_
- > Averaging over a long time period reduces noise and model error contribution
- $\blacktriangleright$  What is left is Mie contribution => curve fitting

(P,T) from NWP



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