

SWARM

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A geomagnetic field model incorporating Earth's mantle conductivity

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Motivation

Sources of near-Earth magnetic Field

- <u>Magnetic measurements:</u>
 - Core dynamics
 - Lithospheric magnetization
 - Ocean circulation and tides
 - Ionospheric currents and electromagnetic (EM) induction in the Earth
 - Magnetospheric currents and EM induction
 - Ionosphere-magnetosphere coupling currents
- Magnetic field models:
 - Separate different sources by geomagnetic field modeling
 - Those rapidly time-varying magnetospheric primary and Earth induced fields play important role in highresolution geomagnetic field modeling



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Sources of near-Earth magnetic Field

Motivation



- **<u>Spatial</u>**: by spherical harmonic (SH) expansion
- <u>Temporal:</u>
 - <u>CM model series (CM5, CM6)</u>: by a series of 1-hour time bins
 - EM induction equations are not invoked
 - Many parameters are needed (in CM6, magnetosphere/total = 685110/ 734670≈93%)
 - **CHAOS model series**: by a linear function of the external and induced parts of RC index
 - RC index is separated into external and induced parts using a prior mantle conductivity model and EM induction equations
 - Less parameters are needed (in CHAOS-7, magnetosphere/total = 613/31757 \approx 2%)

used to account for induced field

Invert for mantle conductivity model

Construct magnetic field model

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Motivation



Our approach - incorporating Earth's mantle conductivity during geomagnetic field modeling



Advantages:

- Constrain geomagnetic field modeling with equation of physics
- Treat geomagnetic field modeling and mantle conductivity imaging in a more selfconsistent manner

• Given a mantle conductivity model σ , compute EM responses $Q_1(\omega, \sigma)$ by solving Maxwell's equations using a finite-element code (Yao et al., 2022).

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• Separate the RC index into external and internal parts using computed EM responses (Maus and Weidelt, 2004; Olsen et al., 2005)

$$RC(t) = Est(t) + Ist(t,\sigma) = Est(t) + Q_1(t,\sigma) * Est(t)$$

• The time variation of magnetospheric primary and induced fields are expressed by a linear function of the external *Est* and induced *Ist* parts of RC index (Olsen et al., 2005).

Method – Part I: separation of RC index into external and induced parts



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Illustration of EM responses for different Earth's conductivity models (model 1: Grayver et al., 2017; model 2: Yao et al., 2023a; model 3: half-space model)

Method – Part I: separation of RC index into external and induced parts



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Illustration of RC separation using different Earth's conductivity models

 $\mathbf{B} = -\nabla V, V = V^{\text{int}} + V^{ext}$

• Model parametrization: core + lithosphere + magnetosphere (Olsen et al., 2006):

$$V^{\text{int}} = a \sum_{n=1}^{N_{\text{int}}} \sum_{m=0}^{n} (g_n^m(t) \cos m\phi + h_n^m(t) \sin m\phi) \left(\frac{a}{r}\right)^{n+1} P_n^m(\cos \theta)$$
$$V^{\text{ext}} = a \sum_{n=1}^{2} \sum_{m=0}^{n} (q_n^{m,SM}(t) \cos m\phi_{SM} + s_n^{m,SM}(t) \sin m\phi_{SM}) \left(\frac{r}{a}\right)^n P_n^m(\cos \theta_{SM}) + a \sum_{n=1}^{2} q_n^{0,GSM} \left(\frac{r}{a}\right)^n P_n^0(\cos \theta_{GSM})$$

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 <u>Model estimation</u>: we implemented a robust least squares method with Gauss-Newton iteration to minimize the objective function, which includes a data misfit term and two regularization terms (Olsen et al., 2014).

Method – Part II: CHAOS-like geomagnetic field modeling

Validation- reproducing CHAOS-4 model using a new Python code



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Mauersberger-Lowes spectrum of the (a) core field; (b) secular variation; and (c) lithospheric field of the CHAOS-4 model (Olsen et al., 2014) and the model derived with our code

Method – Part III: mantle conductivity imaging

- Correct for the internal field using the derived geomagnetic field model.
- Invert/update for mantle conductivity model using a trans-dimensional Bayesian inversion code (Yao et al., 2023b).

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• Update the magnetic field model using the updated mantle conductivity



Examples of extracted magnetospheric SH coefficients and recovered mantle conductivity model

• <u>Data</u>

 Swarm (2023.01-12) and MSS-1 (2023.05-12, launched on May 21, 2023) vector and scalar magnetic data.

- Only night-time data from geomagnetically quiet times were used
- 18505 scalar data and 80140 vector data

• <u>Modeling parameters:</u>

- A half-space conductivity model (0.2 S/m) was used for the initial RC separation.
- Internal fields were estimated up to degree n=30 (n=1-15 is time varying)
- 1835 model parameters (internal + external + induced)
- Loop convergence condition: the root-mean-square (rms) error of the magnetic field modeling between adjacent loops is less than 10^{-2} .

Magnetic data residuals

The iteration converges after 3 loops, here are the magnetic field residuals at the last loop:

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Magnetic data residuals of geomagnetic field modeling at the last loop (satellite 5-8 denote Swarm A, B, C, and MSS-1, the final Huber-weighted rms is 3.6)

Internal field for different loops



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Relative differences of the estimated internal field coefficients between different loops

Internal field for different loops



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Global maps of internal field (n=1-30, epoch=2023.75) at the Earth's surface and the corresponding differences between different loops

External field for different loops



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Time series of external and induced coefficients describing large-scale magnetospheric ring current and the corresponding differences between different loops

Mantle conductivity models for different loops



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Initial conductivity model used for RC external and induced separation and the recovered mantle conductivity profiles for different loops



• We presented a new method for geomagnetic field modeling that incorporates Earth's mantle conductivity as model parameter.

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- Initial results show that inappropriate treatment of induced field may cause error more than 5 nT in both internal and external field models, while our method can iteratively reduce these errors.
- This method may be extended to incorporate more physical processes into geomagnetic field modeling, such as the large-scale ocean circulation and tidal flows.

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