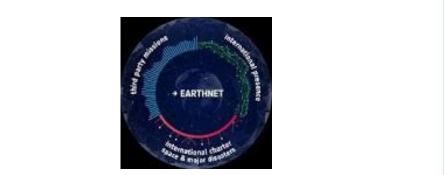
KARIOS : A fast & efficient open source tool for geometric deformation analysis.



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The Earthnet Data Assessment Project (EDAP+) continues the work of its predecessor (EDAP 2018 – 2021) and is responsible for assessing the quality and suitability of candidate missions being considered for ESA's Earthnet Programme as Third Party Missions (TPM). Early data assessments are publicly disclosed to the community ([RD-1]). Based on its own infrastructure ([RD-2]), Telespazio is responsible for the analysis of Very High Resolution optical data, including assessment on geometry, radiometry and image quality ([RD-3]). In most cases, inherited from design tradeoffs in the new space domain, the geometry remains a critical aspect. Main outcomes from various workshops ([RD-4]) point out the needs regarding openly available reference data and openly available data assessment processing tools. In this context, a new tool dedicated to geometric assessment has been created: Kanade Lucas Tomassi (KLT) based Algorithm for Registration of Images from Observing System' (KARIOS)





Functionalities

The main driver of KARIOS initiative is to support operator for following quality control assessments

- <u>Multi temporal geolocation</u> to evaluate the geolocation stability of the mission,
- Absolute geolocation to evaluate the geolocation accuracy of an input image grid against a well-controlled absolute reference image,.
- Band-to band registration to evaluate co-registration between image band grids, all within a same product.

The KARIOS tool has been designed to **compare** two image grids (matching) and output consistent mapping accuracy analysis statistics,

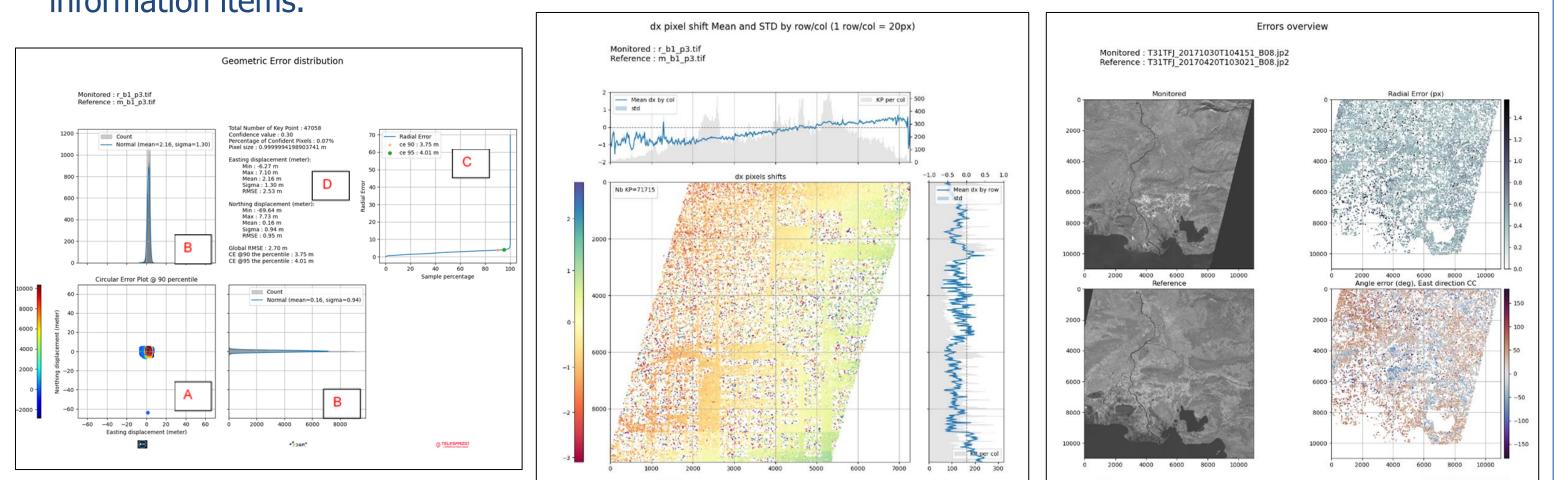
Key features of KARIOS are:

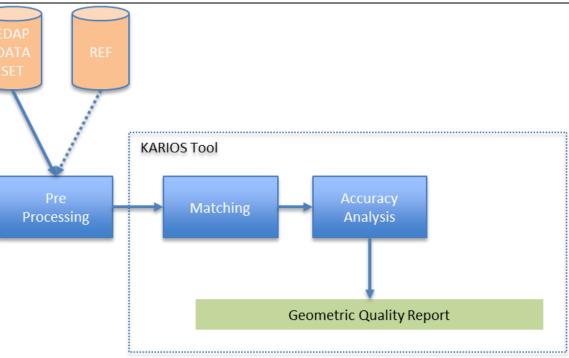
- Free and Open-Source licensing policy (GPL)
- > Multi Missions capabilities; Optical / Radar, Medium Resolution / High Resolution image data
- \succ Python Code (3.10)
- > Increased processing performance
- > Reduced Uncertainties

Unlike commonly shared approach in the domain,

Scope of KARIOS Tool the matching process relies on tracking algorithm initially used for motion analysis: the KLT (Kanade-Lucas-Tomasi Tracking) algorithm.

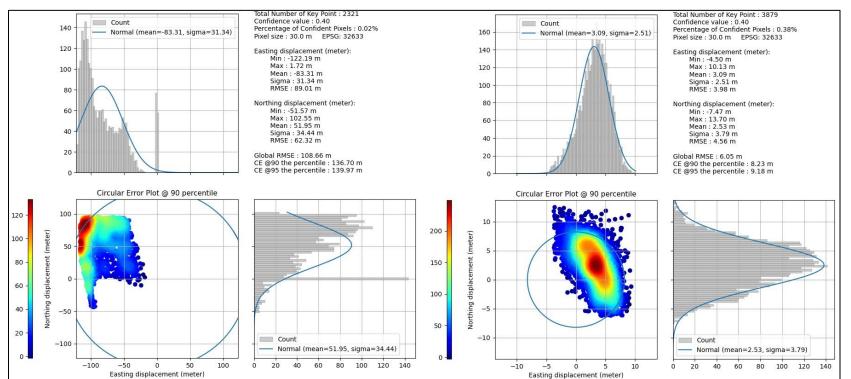
The displacement measurement sample is large and so that, in most cases, representative of image geometry deformation, it enables full characterization of image geometry. Through accuracy analysis module, the KARIOS tool process matching results and provide systematically key accuracy information items.





Product Geometric Quality Control

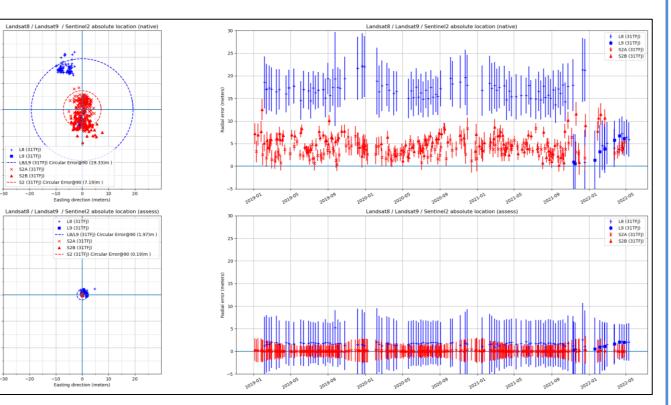
> KARIOS is used to validate geometric processing of Sen2Like ([RD 8]) in particular **PRISMA** L1C georeferencing.



Validation L1C processing (before Sen2Like (left / after (left) registration

Multi temporal analysis

- > KARIOS can be orchestrated to perform multi temporal analysis over large dataset.
- Small changes in Processing Baseline can be easily detected, notably systematic shifts between Landsat and Sentinel 2 products and improvements (end of the period) as show in right figure (upper graphics).
- KARIOS is also used to validate Sen2Like processing results (right figure (lower graphics)).

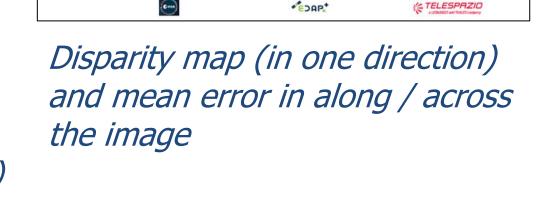


Validation L1C processing (before Sen2Like (left / after (left) refinement)

DY mean=-1.08 med=-1.21 std=0.44

> Image warping into

Geometric error distribution figure; Circular Error (A), Histogram for each direction (B), 2D Error Cumulative functions (C) and statistics (D)

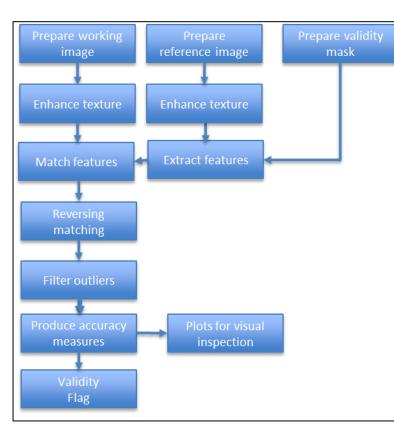


Error overview images: Input *images (right) and radial / angle* error (left), South of France area (Salon de Provence)

cesa

Algorithms

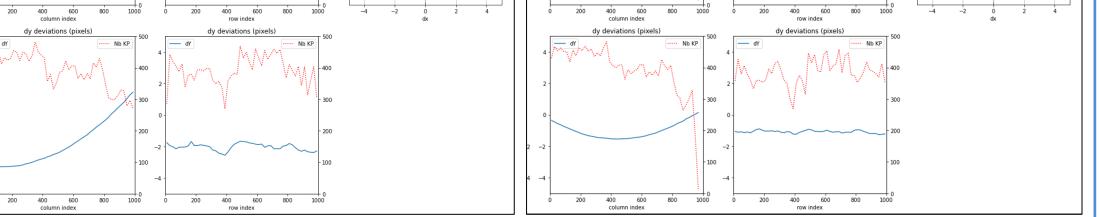
- > A similar method has been previously used for the matching of MSG SEVIRI and AVHRR image series ([RD 5]).
- > Mathematical formulation of algorithm is given in ([RD 6], ([RD 7])) and their implementation is part of OpenCV libraries. There are basically two steps; candidate point selection and matching with optical flow.
- > Dedicated filtering is used to enhance image textural information.
- > Statistical outlier detection for eliminating false matches from the results is performed
- > A statistical confidence value is attached to every pixel
- > Beside disparity maps and mean displacement along with image line, image column, different statistics are provided to appreciate to check product compliance compliance with respect to the National Map Accuracy Standard (NMAS) horizontal accuracy standards,



instrument grid and matching are used to estimate Line of Sight parameters.

PRISMA Geometric

Model Calibration



Monitored : B3.img Reference : Sigma0_VV_1s.tif Radial Error
ce 90 : 0.68 m
ce 95 : 0.73 m Min : -0.79 m Max : 0.80 m Mean : 0.01 m Sigma : 0.33 m RMSE : 0.33 m rthing displacemen Min : -0.80 m Max : 0.80 m Mean : -0.01 m Sigma : 0.32 m RMSE : 0.32 m bal RMSE : 0.46 m @90 the percentile 40 60 80 Sample percentage

S1 / S2 Image grid comparison

Geometric Model calibration in instrument grid; before (left figure), after (right figure)

Different types of sensor / mission KARIOS can be used to compare image grids from > Optical / Radar Instrument > LR, MR, VHR Image sensors

Visible / Thermal infrared channels

Conclusions and Future Plans

An additional tool enabling geometric assessment is now available for the community. The use of this tool is straightforward and processing fast / efficient. The algorithm accommodate with various configurations, The reports are self explaining and support accuracy analysis.

In the context of EDAP+ / Copernicus, shared with data provider, it will be used for cross validation; based on the same dataset & the same tool.

References

> [RD-1] ESA/EDAP VHR, HR and MR Optical Missions Webpages, https://earth.esa.int/eogateway/activities/edap/vhr-hr-mr-optical-missions

Image matching algorithm

Comparison with existing tools

- > Based on same dataset, KARIOS results have been compared with those from other tools as MEDICIS (M. Cournet 2016) or AROSICS.
- \succ Results agree together (refer to Fig A)
- > Differences exist regarding the number of Key Points (KP) and spatial distribution (refer to Fig B)

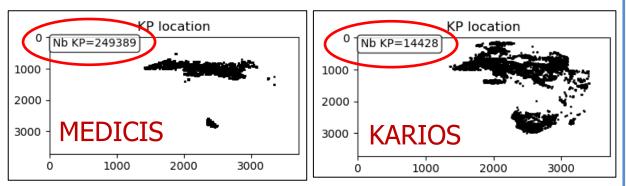
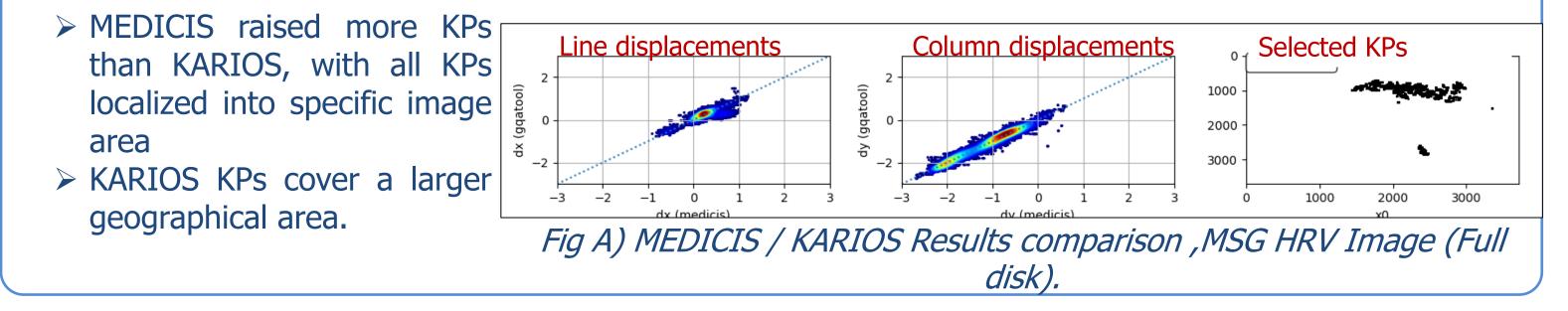


Fig B) Number of KPs and Geographic distribution, MSG HRV Image (Full disk)



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