RT simulations to assess cloud effects in solar and thermal radiative flux estimation for the EarthCARE BBR instrument

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DESCRIPTION

EarthCARE's top-of-Atmosphere radiative fluxes (**BMA-FLX**) are obtained by applying a radiance-to-flux conversion algorithm to the unfiltered radiances from the Broad-Band Radiometer (BBR). Algorithms for retrieval of solar and thermal fluxes are based in angular dependence models (**ADMs**). The ADMs model the **anisotropy of the atmosphere-Earth system** providing an anisotropic correction factor to the Lambertian assumption when integrating the exiting radiance field. A geophysical

dataset mimicking EarthCARE data is constructed for training the algorithms and build the ADMs.

ALGORITHMS

- Shortwave (SW) models are created per scene type and per angular geometry, and constructed from CERES and MODIS flux and radiance data, and auxiliary surface and atmosphere information, using a feed-forward back-propagation artificial neural network
- Longwave (LW) models are based on correlations between BBR radiance anisotropy and the spectral information provided by the EarthCARE's Multi-spectral Imager (MSI) radiances derived from radiative transfer calculations





CO-REGISTRATION AT REFERENCE LEVEL

Optimizing radiance co-registration at the reference level (RL), the most

FLUX COMBINATION



radiatively significant atmospheric layer, is essential for harnessing the multi-pointing capabilities of BBR

- MSI CTH is a good estimator to co-register the LW BBR radiances. RL is defined as the p90th of the altitude of the highest cloud in the BBR domain
- Co-registration errors at SW are higher when employing CTH compared to the surface. Oblique radiances crossing the optical path between surface and MSI CTH in the BBR nadir observation are selected for flux processing. RL is defined as the atmospheric layer minimizing differences among nadir, aft, and fore flux retrievals

A combined flux is derived from the aft, fore and nadir fluxes derived at the RL. The

SIMULATED EARTHCARE SCENE



algorithm to merge fluxes considers the scene type errors, the unfiltering errors and the 3D effects of the clouds present in the scene



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