

SWARM

10

YEAR ANNIVERSARY  
SCIENCE CONFERENCE

Not Swarm - a reassessment of possibilities with a lower quality mission

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Swarm 10 Year Anniversary & Science Conference 2024

# Introduction

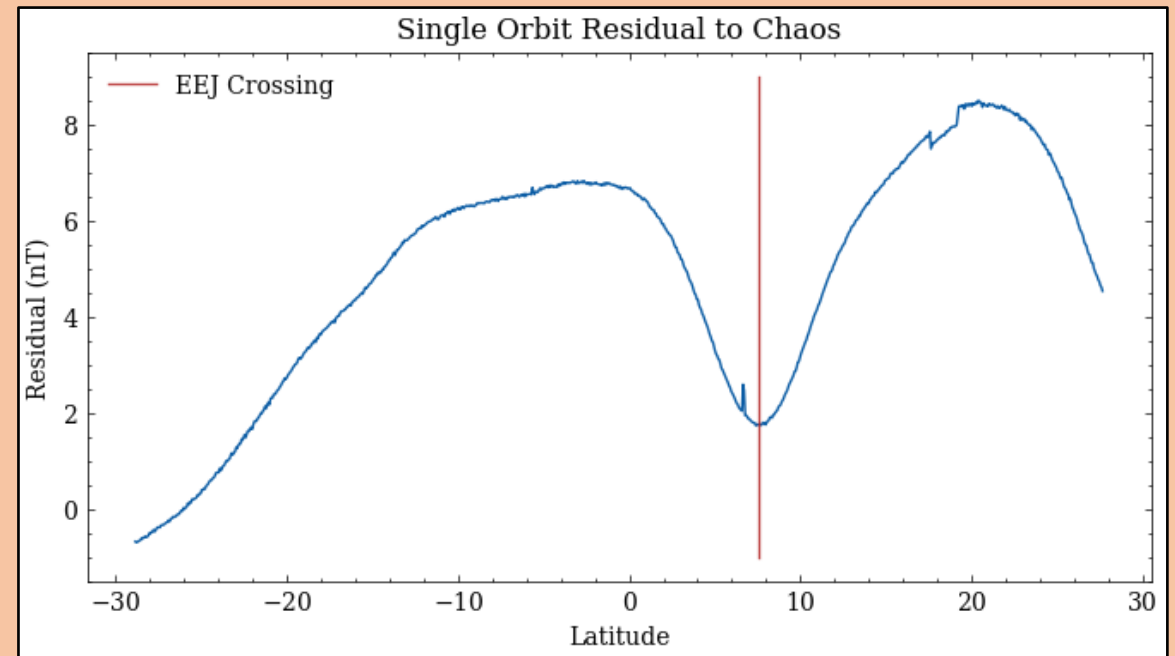
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- What if we only had intensity data – no directions
- Non-uniqueness (Backus effect)
- Feature of dayside data - EEJ (Equatorial Electrojet)
- Intensity data are provided by the Chinese CSES satellite
- Focus on March 2019 – a string of solar quiet days 21-26
  - Vector data also available to compare
- Can we use the position of the EEJ as a sufficient constraint as to alleviate the Backus effect?
- Spoiler – not well enough, but useful if only have intensity data

# Finding the EEJ

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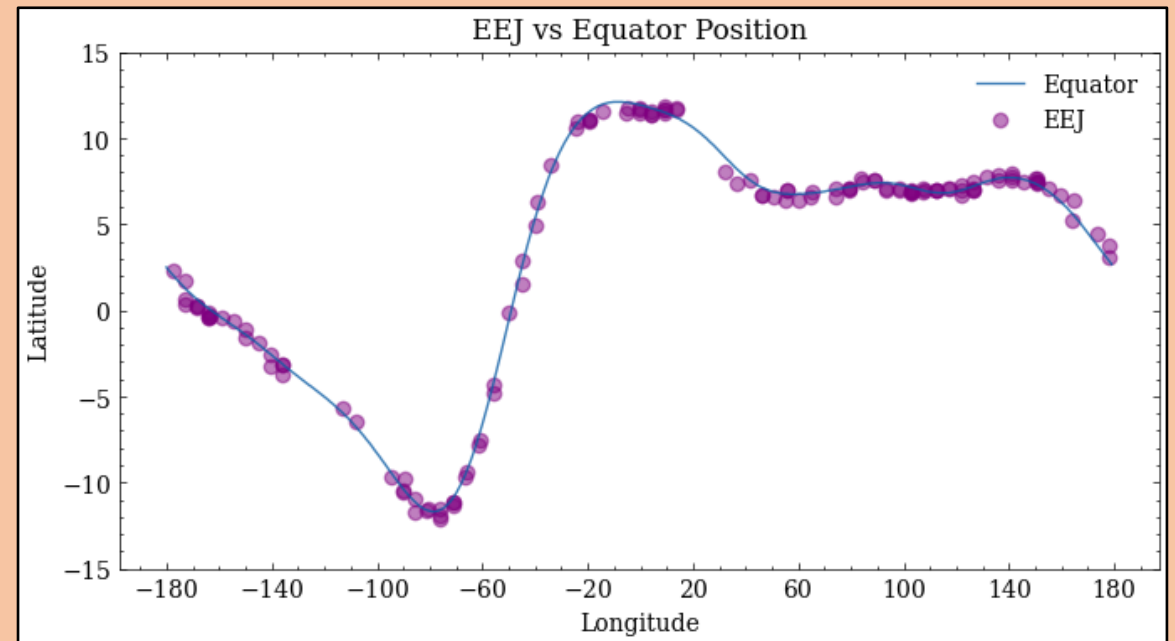
- Dayside reduction in total field intensity along the EEJ
- Residual of the dayside data to Chaos model – Polynomial shape as spacecraft crosses over the EEJ
- Take position of crossing at the minimum



# Comparison to Magnetic Equator

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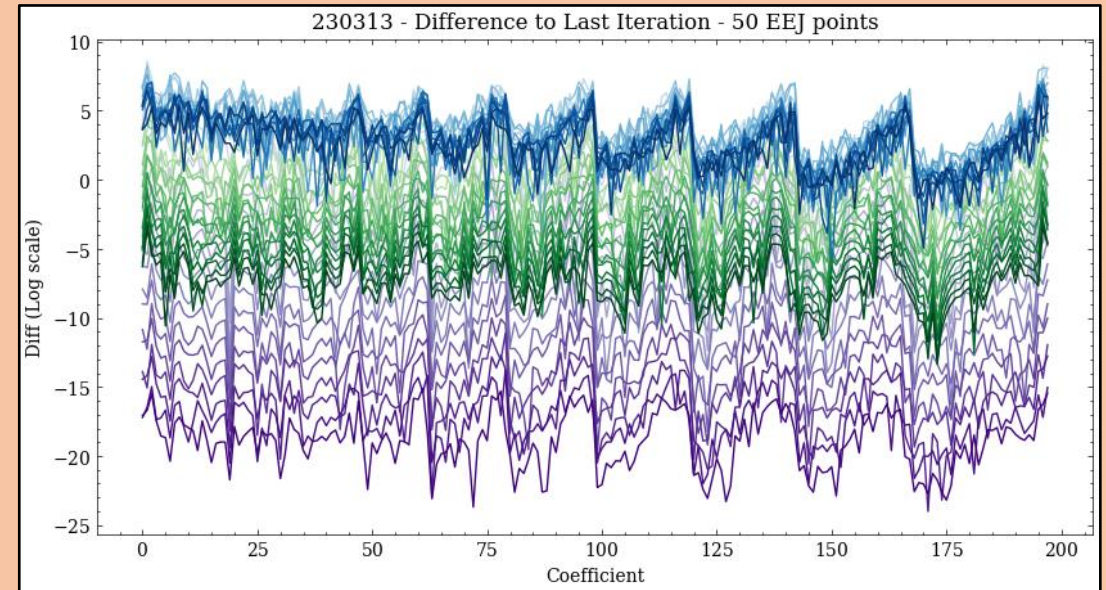
- The EEJ follows the magnetic equator
- Compare our measured points against equator
- Assume zero radial component at these points
- Additional constraint – Resolves non-uniqueness



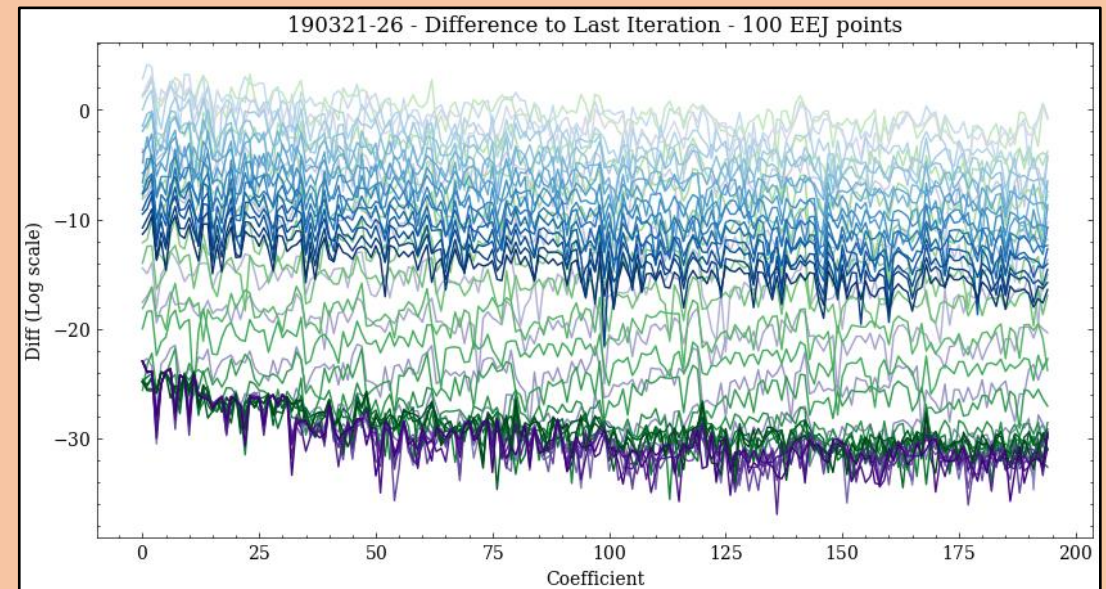
# Convergence

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- Plot difference in each coefficient to last iteration
- Measure of convergence
- Iteration number increasing from light to dark color (15 total)
- Data alone (Blue), EEJ (Green), Perfect Eq (Purple)
- Benefit to convergence is clear



Single day (2023/03/13)

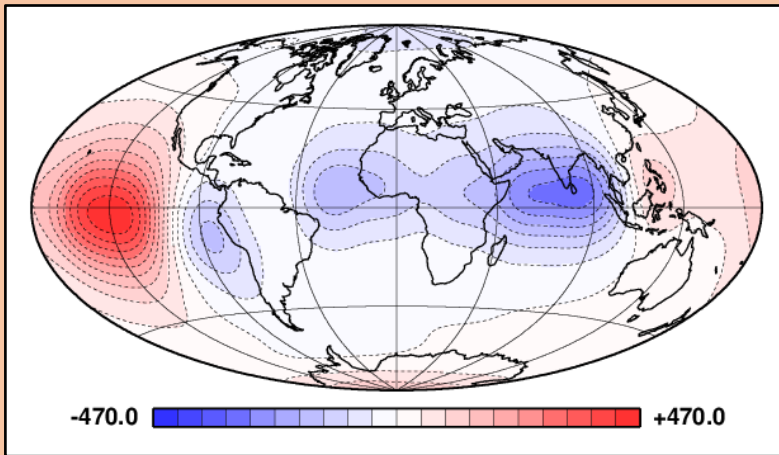


String of 6 days (2019/03/21-26)

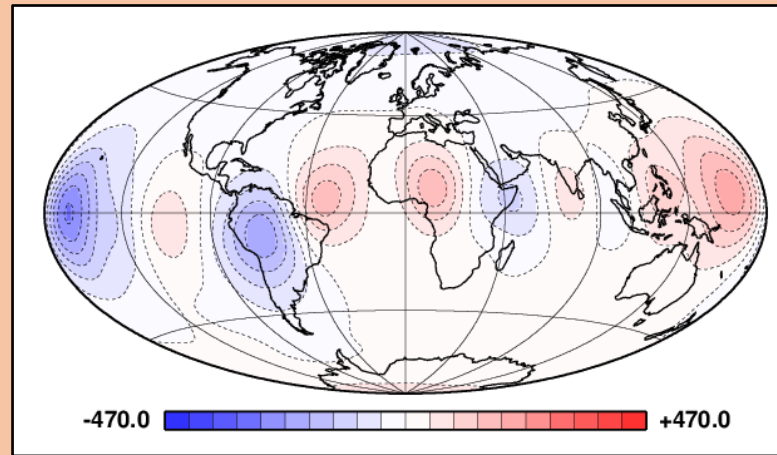
# Field Residual Maps

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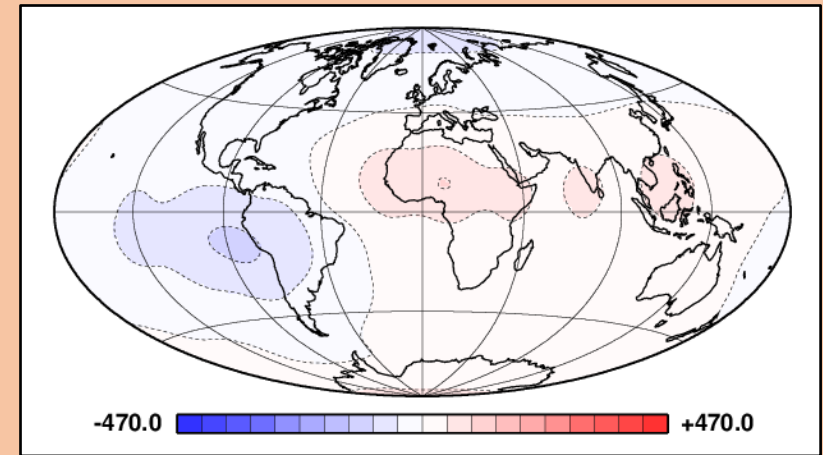
- Mapping the residual of our models to Chaos
- Compare EEJ to perfect equator – Calculated from Chaos for – 180 → 180 in 1-degree steps (360 points)



Data alone



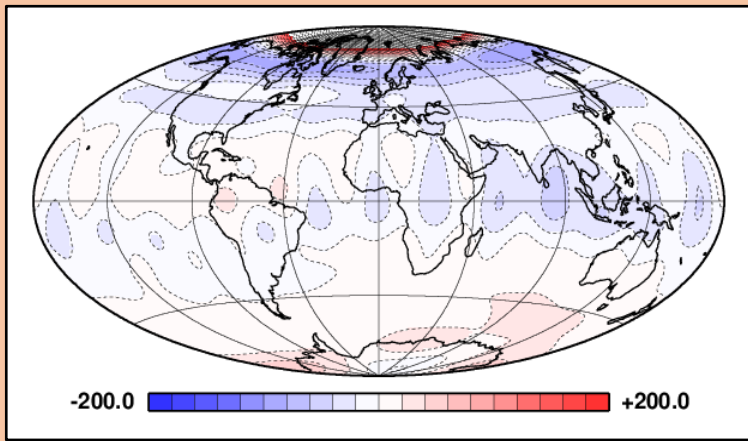
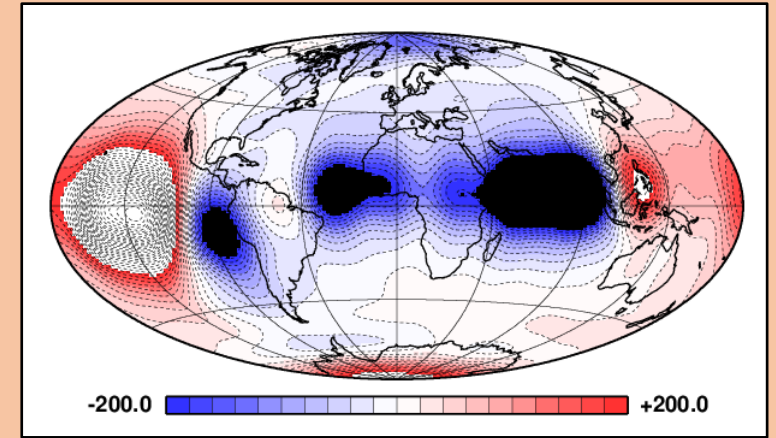
98 EEJ points



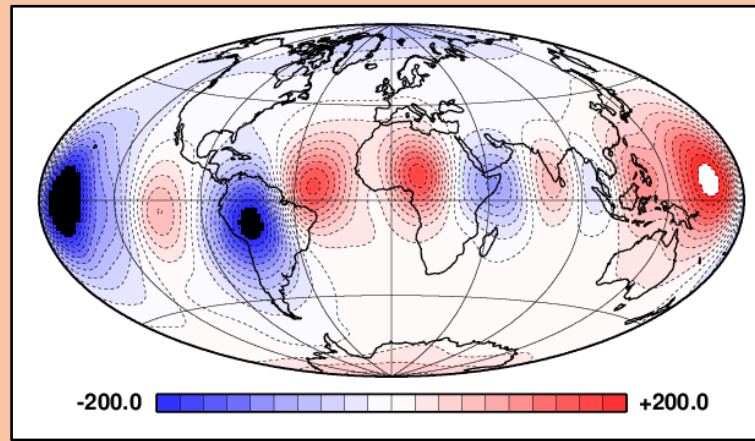
360 Equator points  
(calculated from Chaos)

# Comparison with Vector Data

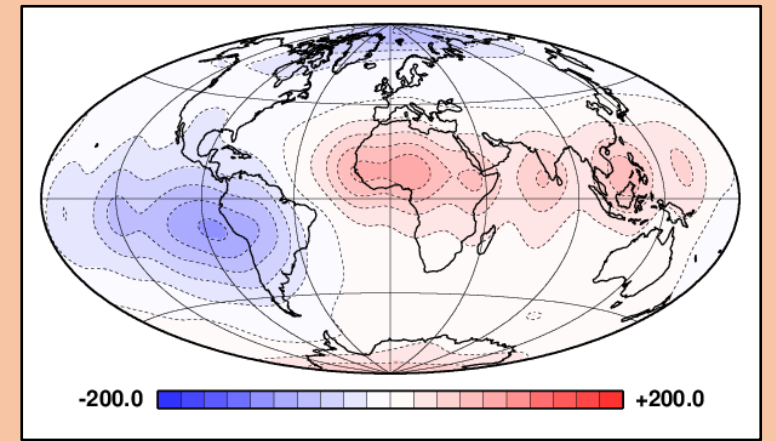
- We also have vector data for March 2019
- Limit to latitude range  $-50^{\circ}$   $\rightarrow$   $+50^{\circ}$
- No Backus effect, but bigger problem of polar gap



Vector data



98 EEJ points

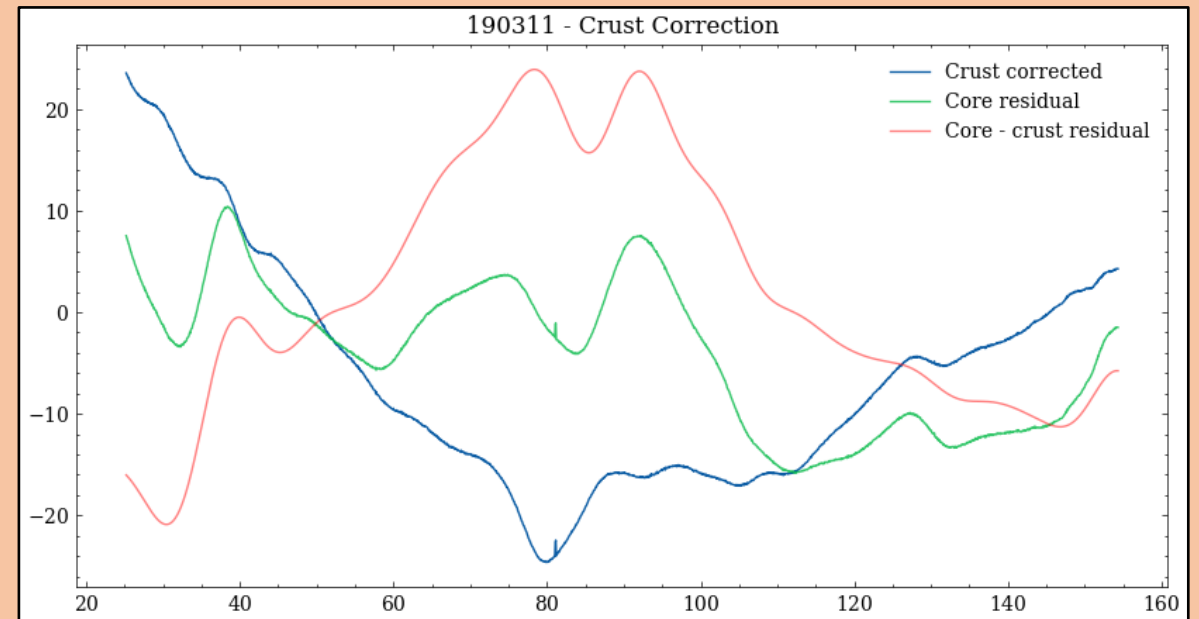


360 Perfect Equator points

# Correcting for the Crustal Field

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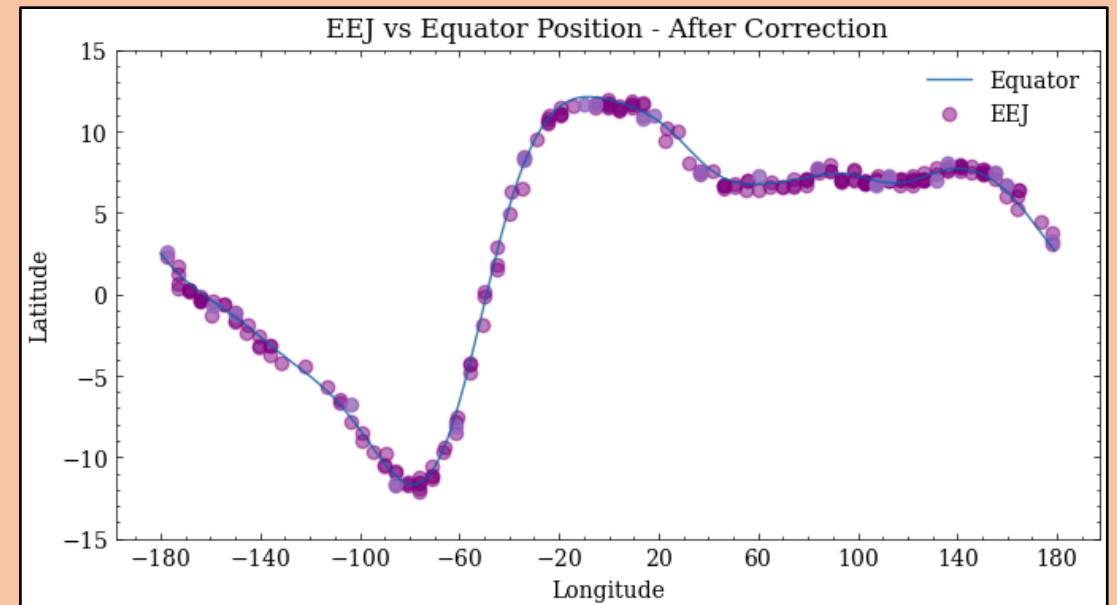
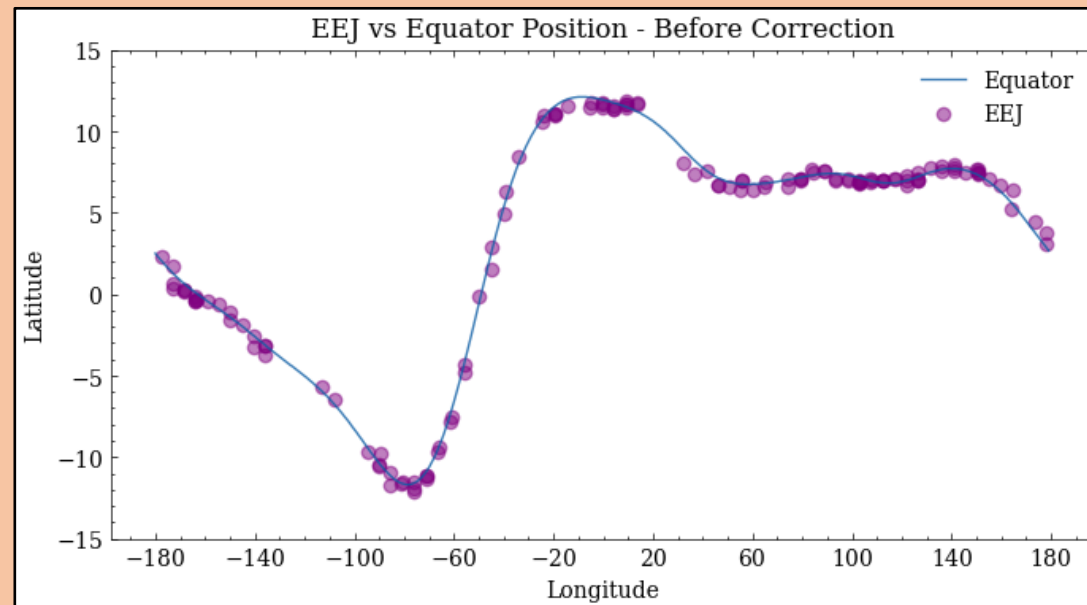
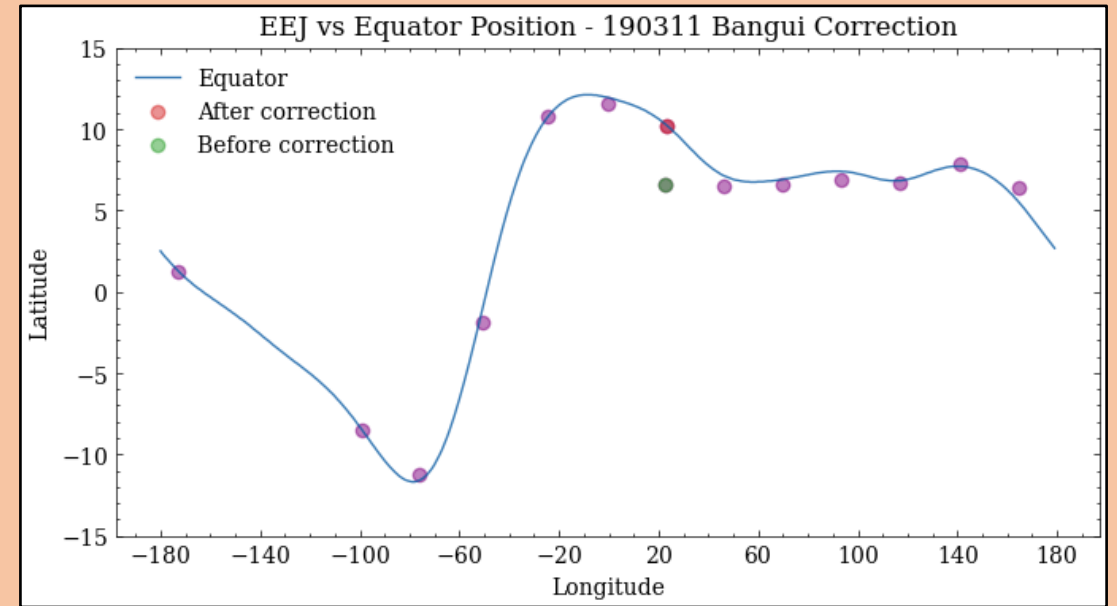
- Static part of field – degree 20–40
- Take residual of data to degree 20 and 40 field
- Look at difference between the two residuals for signals that could influence the minimum of EEJ signal
- Clear signal around 4 degrees latitude, 22 longitude (Bangui)





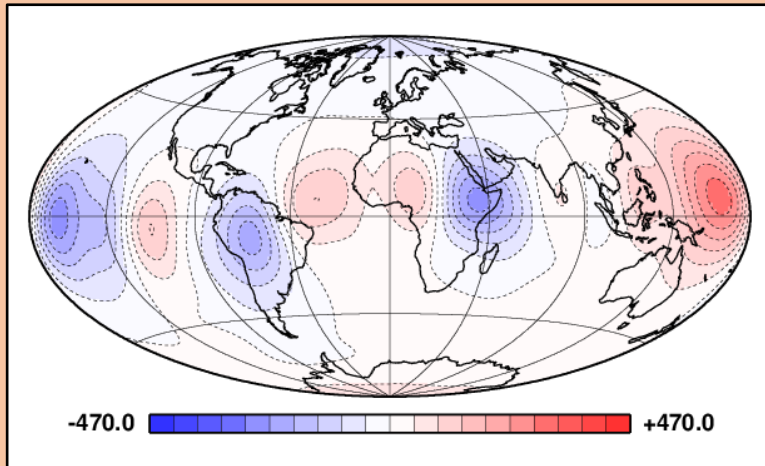
# Correcting for the Crustal Field

- Correction helps fill in gaps in EEJ position along the equator

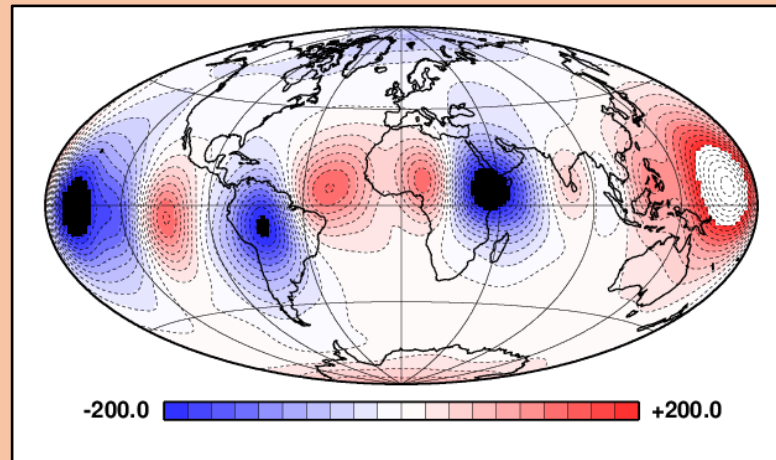


# Maps after Correction

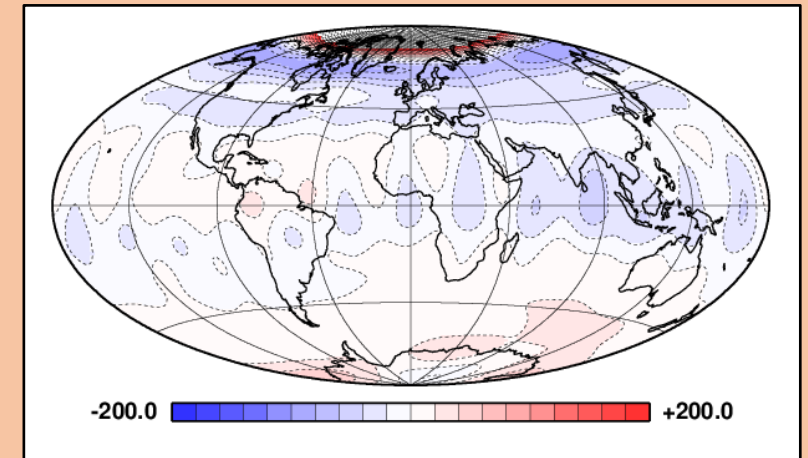
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230 EEJ points



Changed scale

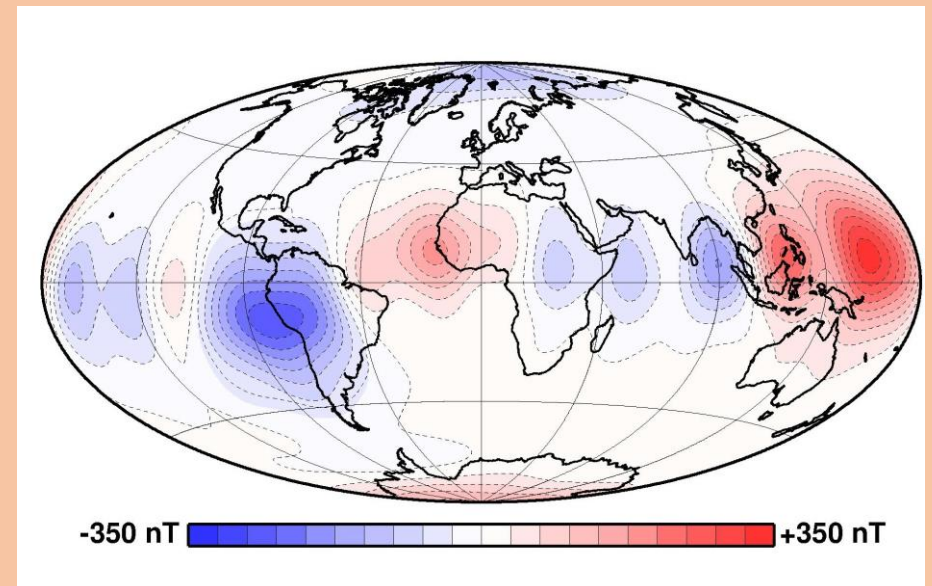
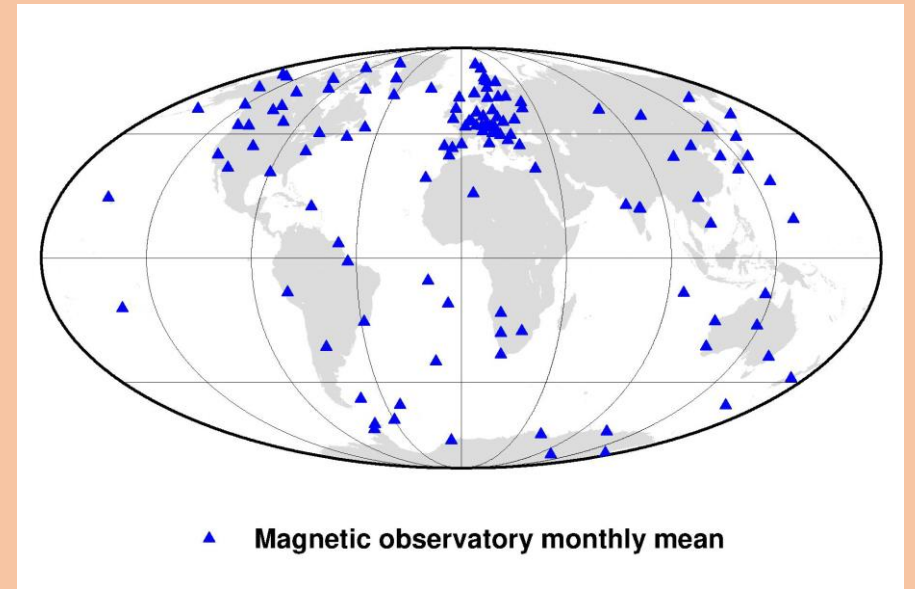


Vector data

# Observatory means

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- Add in available monthly means
- Correct for observatory bias
- Vector data – observatory only – independent starting model
- Much better convergence with electrojet data
- However, closer to Chaos model with these data removed
- Suggests electrojet data very useful but must be correct!



# Reflections

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- Magnetic equator information from dayside data picking electrojet
- Highly sensitive to small picking errors
- Convergence issues – small changes to misfit bring closer to expected model
- Corrected for crustal field – external field as well?
- Provide a stable model, but position errors bias model
- Vector data clearly more reliable for equatorial field
- However, if only scalar data available, careful work will produce a quality model, although vector data are better
- Hopefully, future satellites will be equipped that this method is not necessary!