



4DSpace



UiO

Short-term Regional Ionosphere Imaging at Mid- and High-Latitudes: A four-Dimensional Ensemble-based Variational Approach

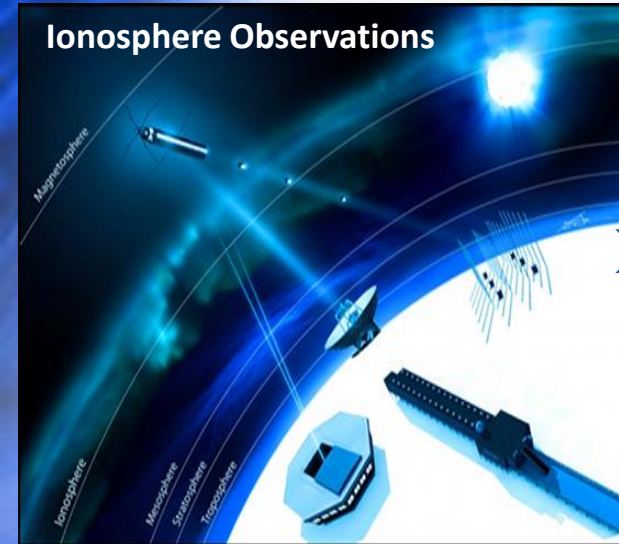
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Ionosphere Observations



DATA ASSIMILATION TECHNIQUE

- **Goal: Resolve time-evolving structures in 3D**
- **Observations are irregular in Space and Time**

← Model (Prior)

Data

- **Ground GNSS data**
- Radio occultation Data

Base - Starting point!

- ISR data
- Ionosonde data

- To avoid averaging ionospheric dynamics use
4D-Variational (Var) techniques
4D => Spatial (3D) and Time

Incremental Strong constraint 4D Var approach (SC4DVar-INC)

Strong constraint 4D-Ensemble Var approach (SC4DEnVar)

DATA ASSIMILATION TECHNIQUE

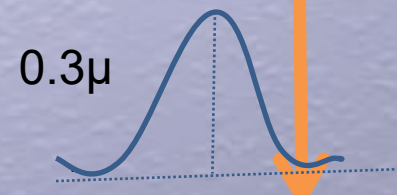
Initialize from IRI-2016

Strong constraint 4D-Ensemble Var approach (SC4DEnVar)

Sensitivities

$$\tilde{\mathbf{M}}_k \times \frac{\partial h_k}{\partial \bar{\mathbf{X}}_k}, \quad \tilde{\mathbf{H}}_k = \frac{\partial h_k}{\partial \bar{\mathbf{X}}_k}$$

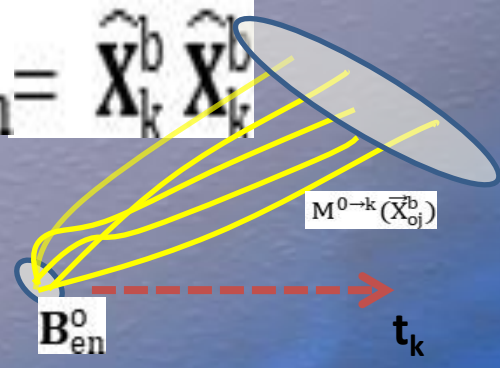
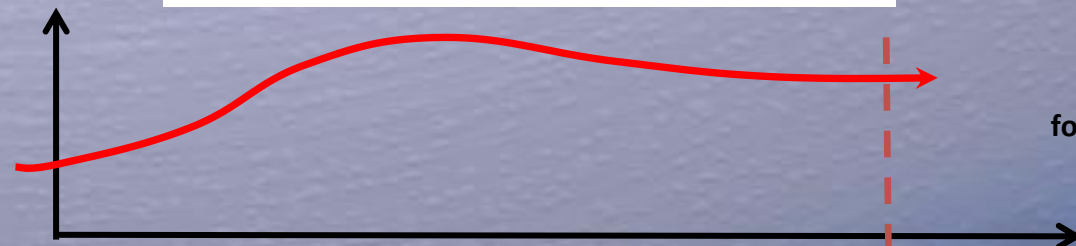
Use Ensembles: Perturb IRI inputs
e.g: Rz12, IG12, F10.7 daily, hmF2, Kp :- 30 Members



$$\mathbf{B}_{en}^k = \hat{\mathbf{X}}_k^b \hat{\mathbf{X}}_k^b$$

$$\vec{\mathbf{X}}_{k+1} = \vec{\mathbf{X}}_b^{k+1} + (\vec{\mathbf{X}}_k - \vec{\mathbf{X}}_b^k) * \exp(-dT/\tau)$$

3D



forecast

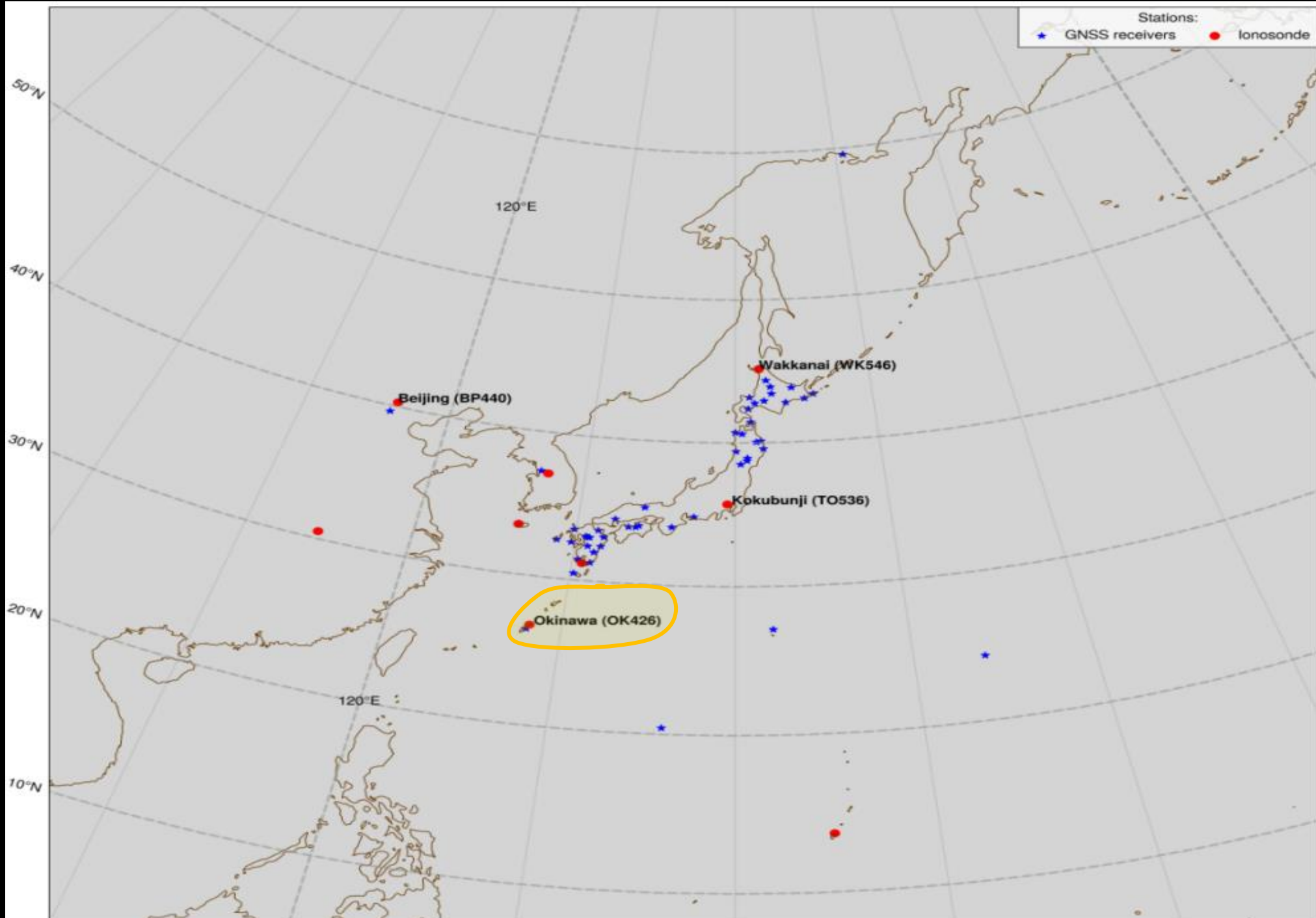
t_k

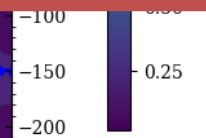
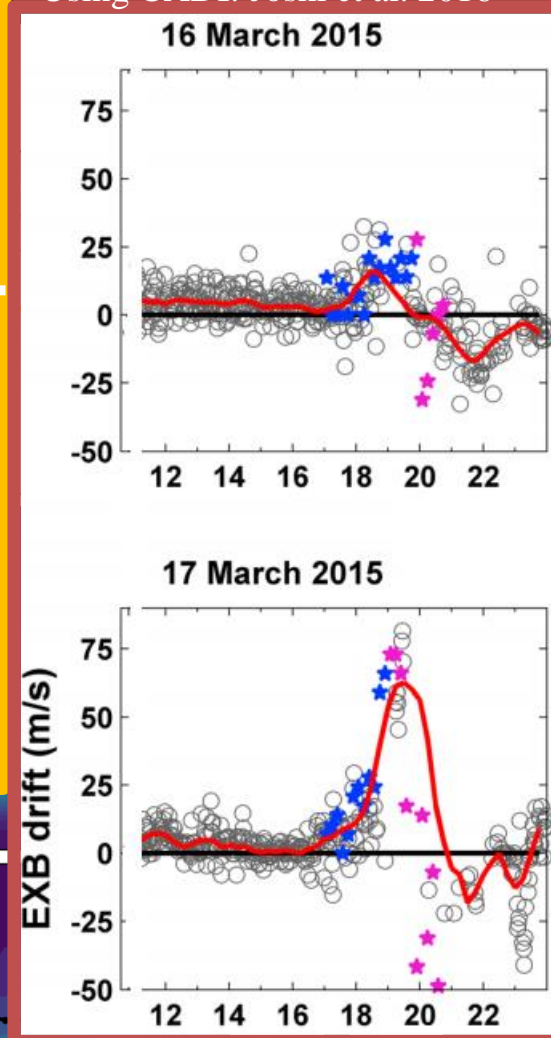
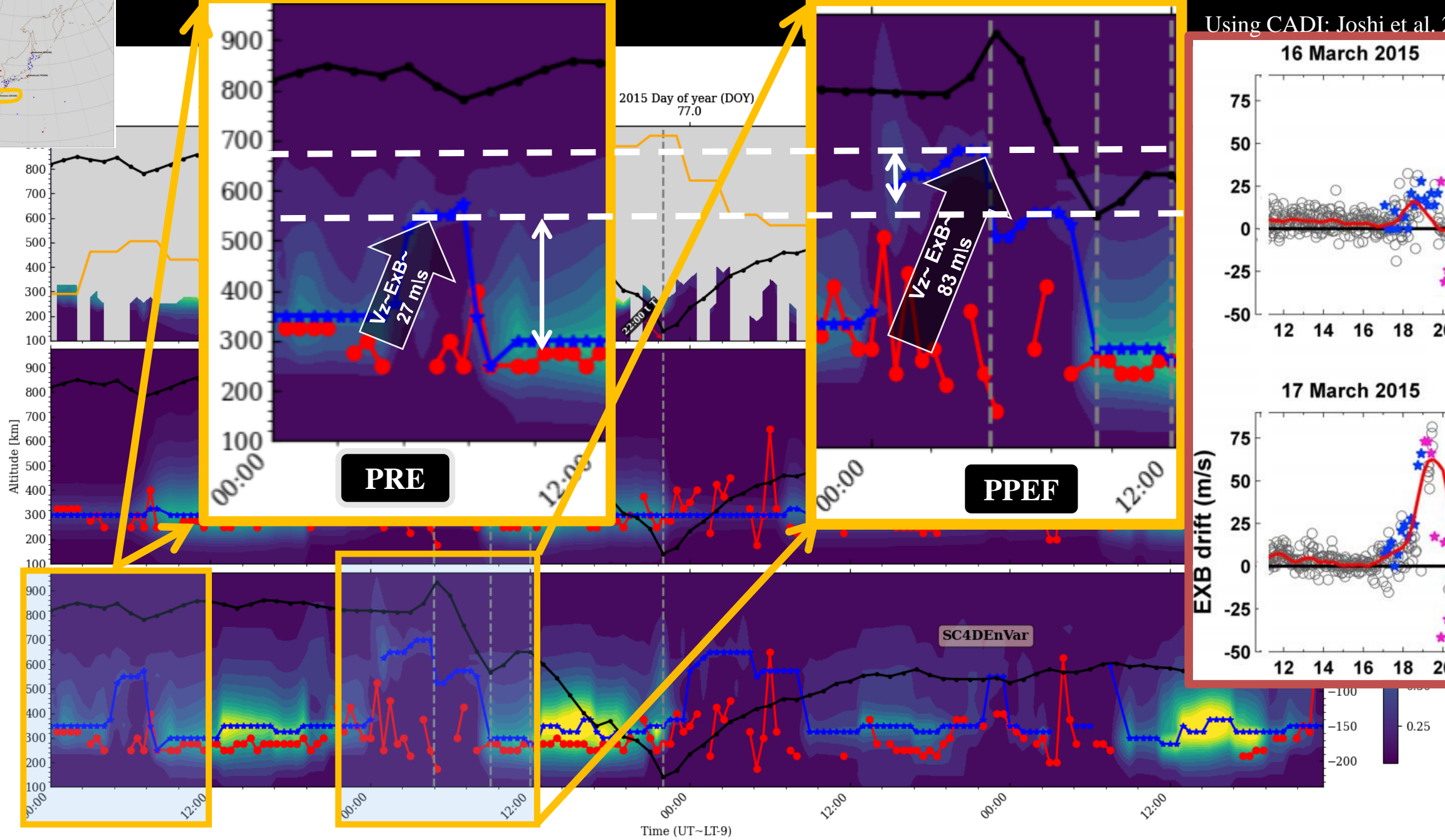
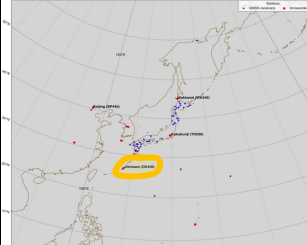
Assimilation window (30min)

Real Observations (Mid-Low Latitudes)

St. Patrick's Day 2015 Geomagnetic Storm

IONOSONDE COMPARISON





Summary: SC4DVar-INC Vs. **SC4DEnVar**

Comparison factor	SC4DVar-INC	SC4DEnVar
Height Variation	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>
Density estimation: Areas populated with data	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>
Remote Areas	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>
During chaotic conditions	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>
Integration through the 3D structure	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>
Computation expense	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>
Maintainance	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>
Parallelization	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>
Under-sampling and rank deficiency	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>

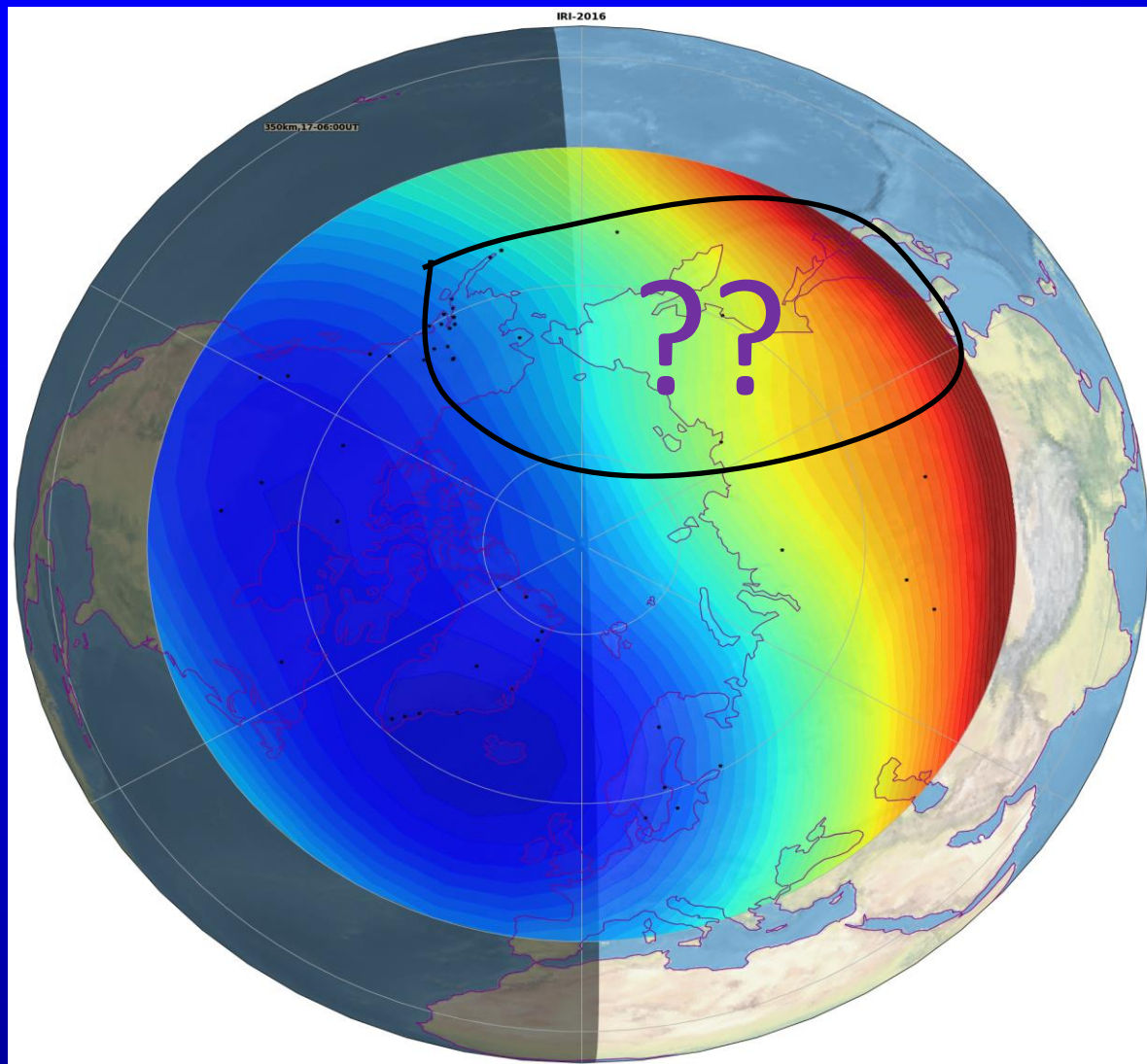
*This makes **SC4DEnVar** a favourable candidate for real-time applications and remote areas

FINAL TARGET :-

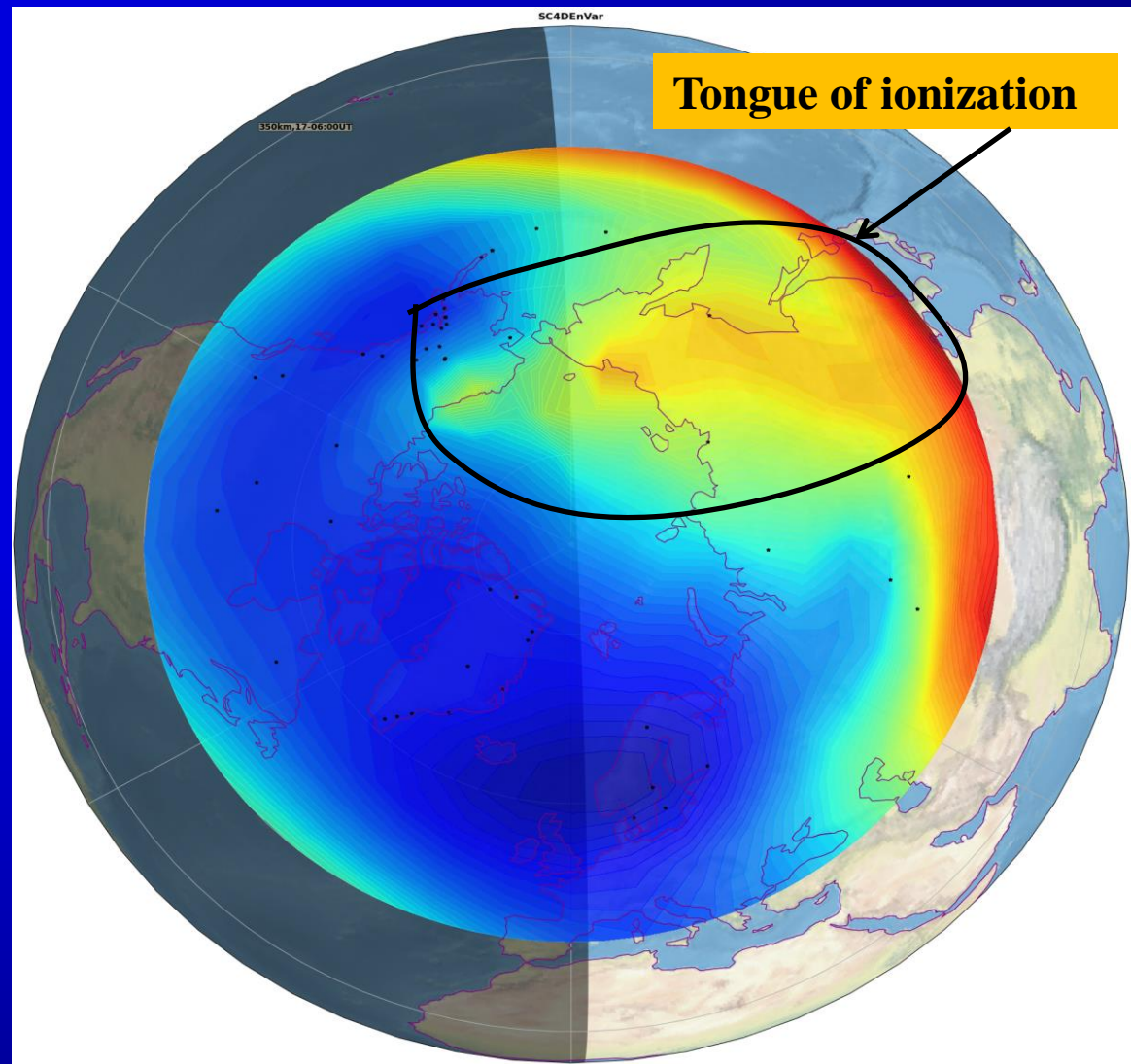
**Transfer the technical know-how to
High Latitudes
and track 4D Evolution of Polar cap Structures**

Slice at Altitude: 350km

Background (IRI-2016): 2015-03-17



SC4DnVar: 2015-03-17



$10^{11} \times \text{el}/\text{m}^3$



SWARM Satellites (A, B) in situ electron densities

Impact

$$= \left(\frac{\text{IRI2016_squared deviations} - \text{SC4DEnVar_squared deviations}}{\text{IRI2016_squared deviations}} \right)$$

Negative impact

Positive impact



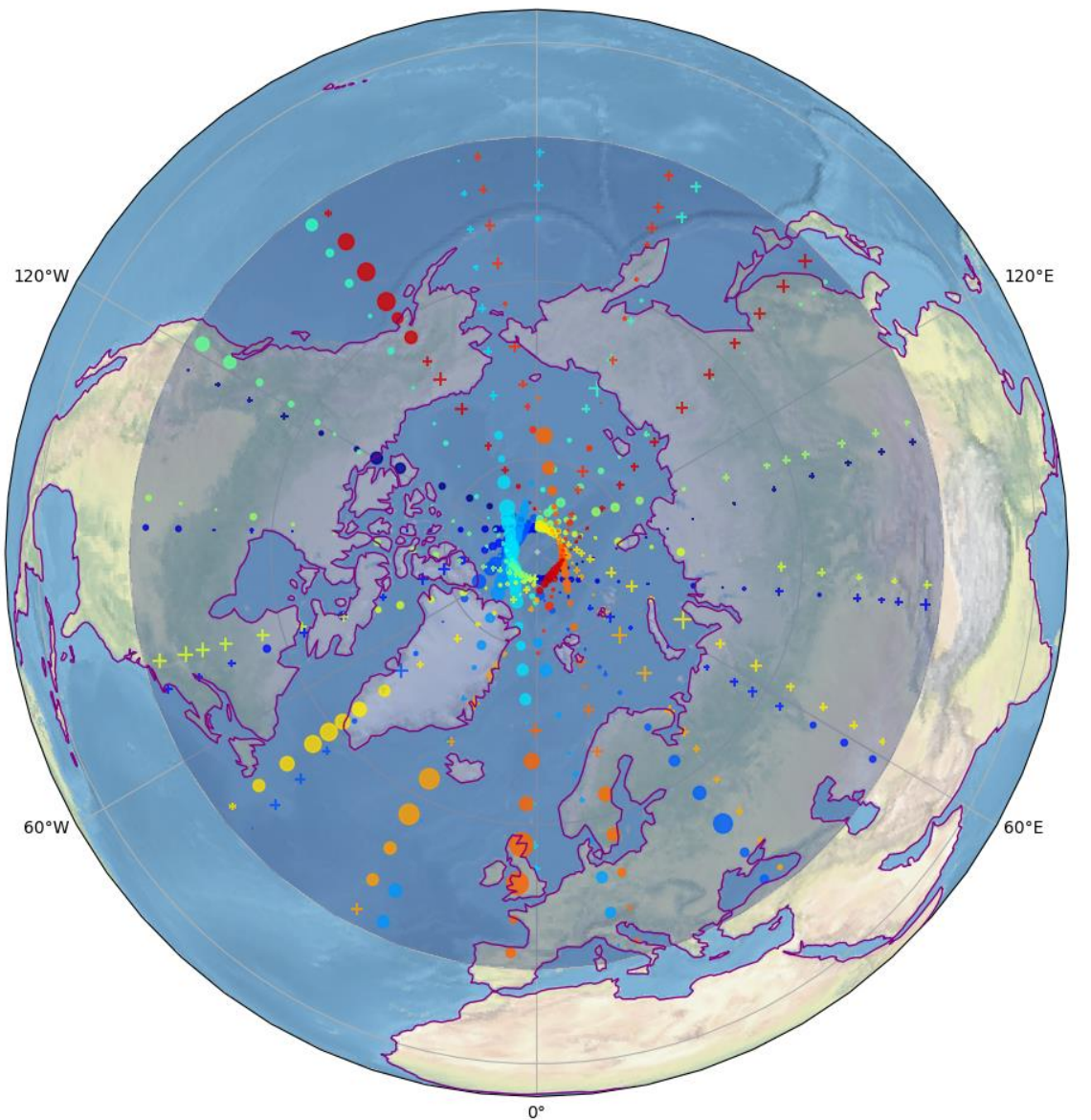
Negative impact



Positive impact

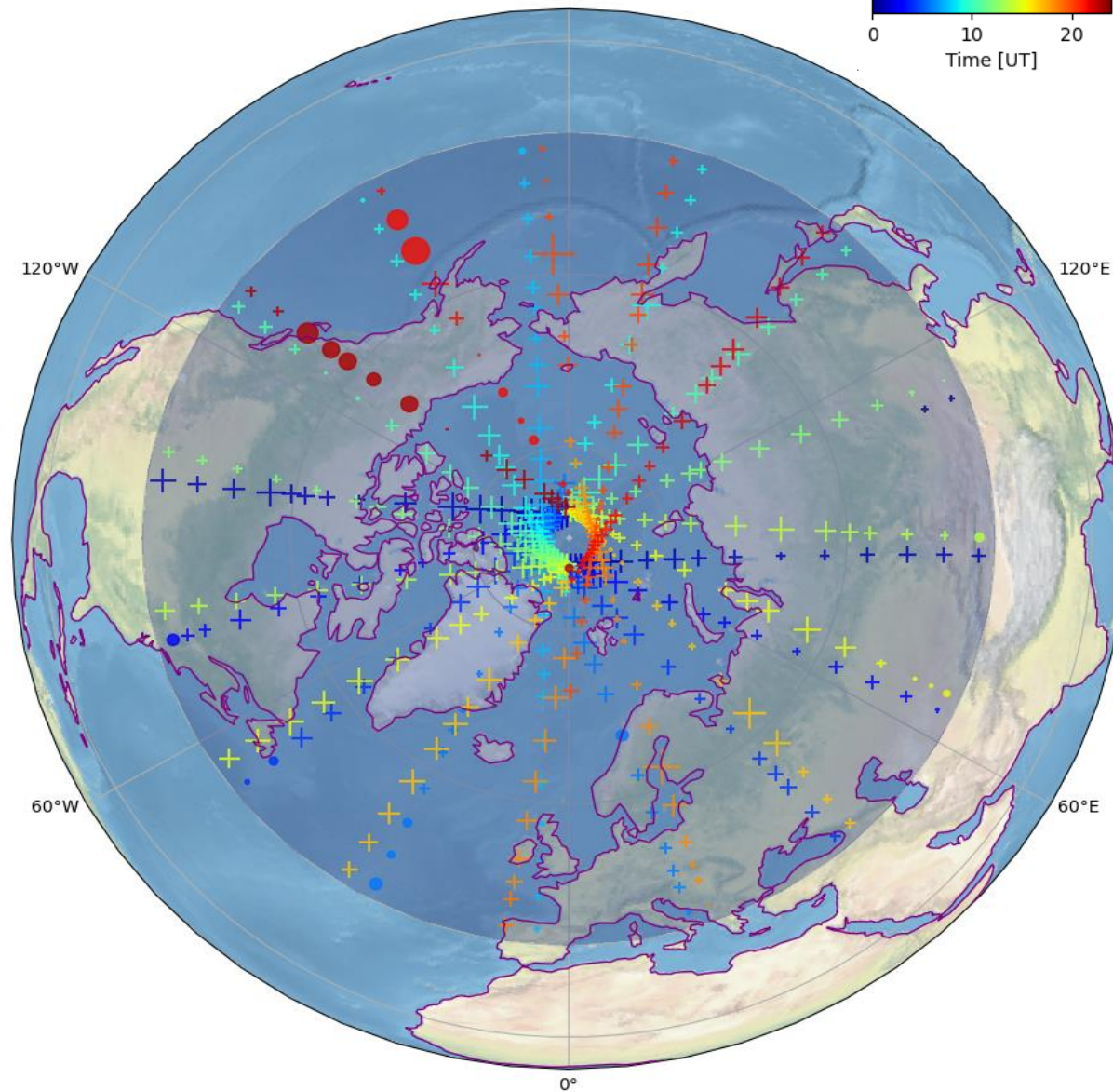
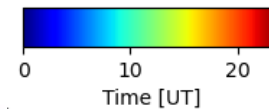
Quiet Period: 2015-03-14

SWARM(A): 2015-03-14
180°

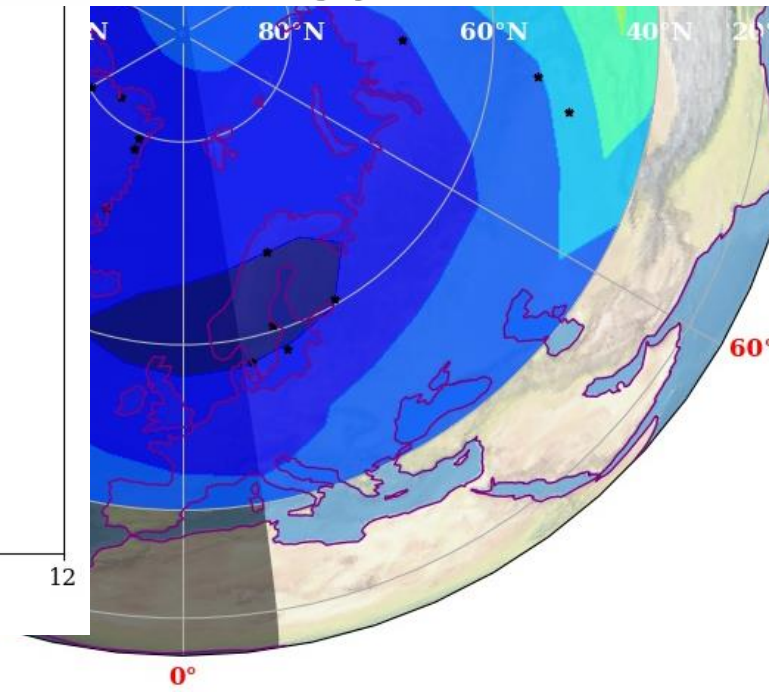
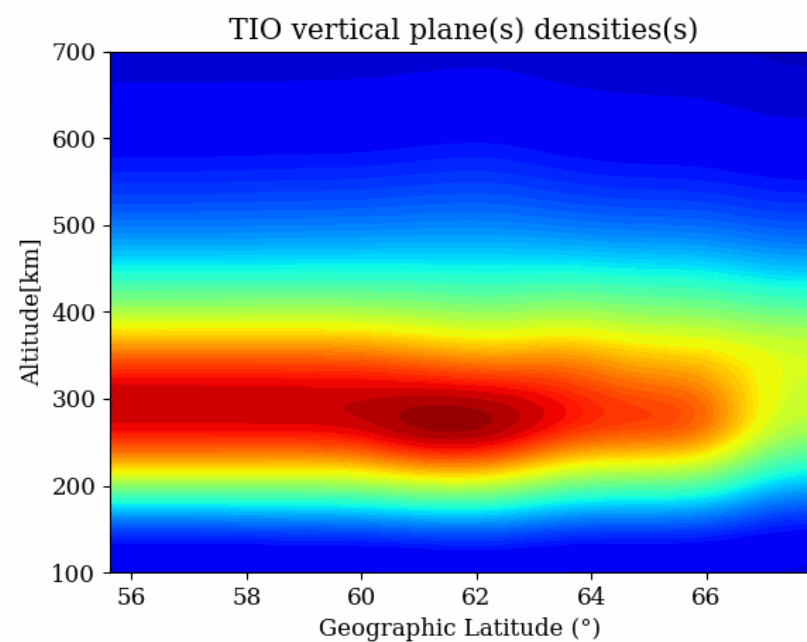
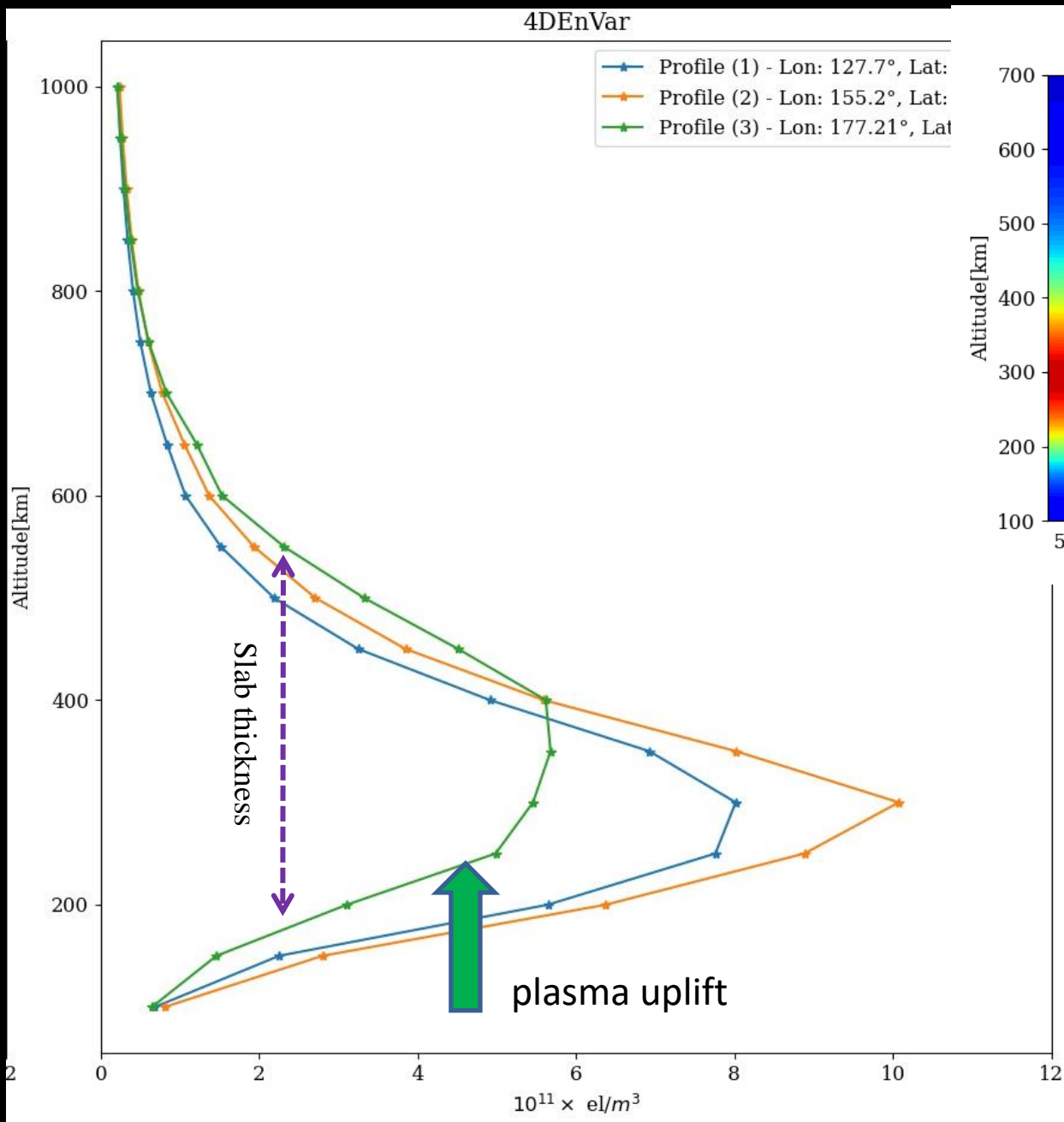
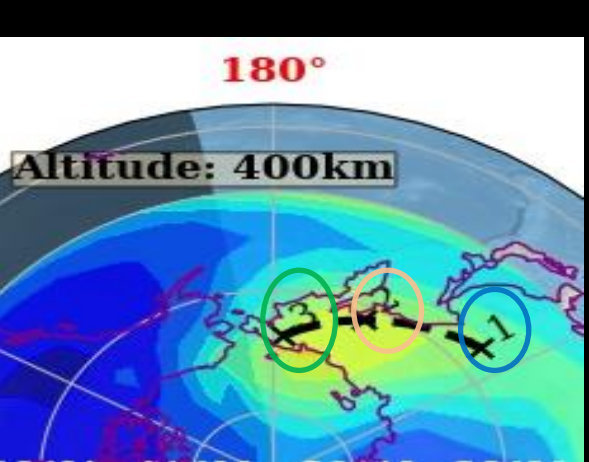
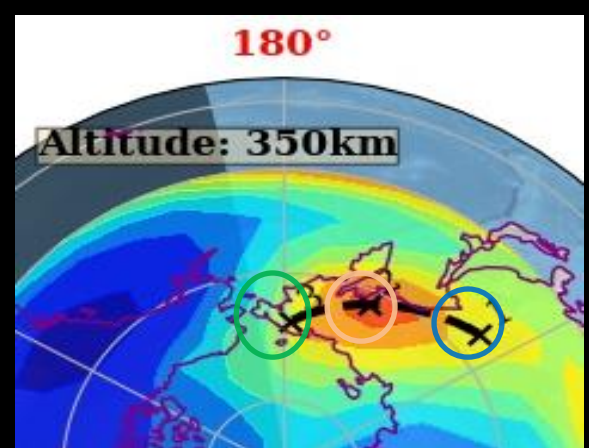
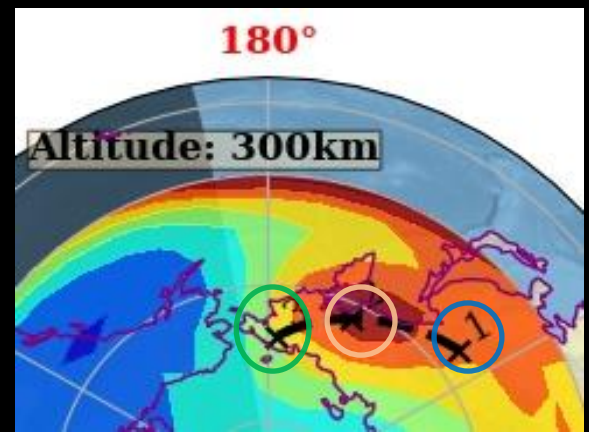


Storm Period: 2015-03-18

SWARM(A): 2015-03-18
180°



Slice at different altitudes: 300km, 350km, 400km and 450km



New-Additions

- Revised - prognostic model to add some physics (ExB drift)

$$\vec{X}_{k+1} = \vec{X}_b^{k+1} + (\vec{X}_k - \vec{X}_b^k) * \exp(-dT/\tau) \quad + \quad \frac{dN}{dt} = P - L - \vec{\nabla} \cdot (N\vec{v}_{||}) - \vec{\nabla} \cdot (N\vec{v}_{\perp})$$

*Assumptions
(30 minutes window):*

$$P - L \approx 0$$

$$-\vec{\nabla} \cdot (N\vec{v}_{||}) \approx 0$$

Perpendicular contribution
 $= -\vec{v}_{\perp} \cdot (\vec{\nabla} N) - (\vec{\nabla} \cdot \vec{v}_{\perp}) N$

Here:
 $X_k = N$

New-Additions

➤ Revised - prognostic model to add some physics (EXB drift)

$$\vec{X}_{k+1} = \vec{X}_b^{k+1} + (\vec{X}_k - \vec{X}_b^k) * \exp(-dT/\tau) \quad + \quad \frac{dN}{dt} = P + L - \vec{\nabla} \cdot (N\vec{v}_{||}) - \vec{\nabla} \cdot (N\vec{v}_{\perp})$$

Perpedicular contribution

$$= -\vec{v}_{\perp} \cdot (\vec{\nabla} N) - (\vec{\nabla} \cdot \vec{v}_{\perp}) N$$

Assuming a dipole field in spherical (r,θ,φ):

(Bittencourt et al, 2007; Datta-Barua et al, 2009)

$$\vec{v}_{\perp}$$

$$= v_{exb} \cos I \hat{r} - v_{exb} \sin I \hat{\theta} + v_{\phi} \hat{\phi}$$

❖ field lines are assumed nearly vertical

- Altitudes 100 ~ 1000 km
- Latitude 50 ~ 90 degrees Northern hemisphere

Where:

$$X_k = N$$

$$X_{k+1} = m(X_k, \alpha_o)$$

$$\alpha_o = v_{exb}, v_{\phi}$$

$$\begin{aligned}
 \mathbf{x}_0 &= \mathbf{x}_0^f + \mathbf{C}_{x_0} \lambda_0, \\
 \theta &= \theta^f + \mathbf{C}_{\theta\theta} \sum_{k=0}^K \mathbf{M}_{\theta,k}^T \lambda_{k+1} \\
 \mathbf{x}_{k+1} &= \mathbf{m}(\mathbf{x}_k, \theta),
 \end{aligned}$$

New-Additions

- Use strong-constraint-Lagrange 4DVar to estimate \mathbf{v}_{exb}

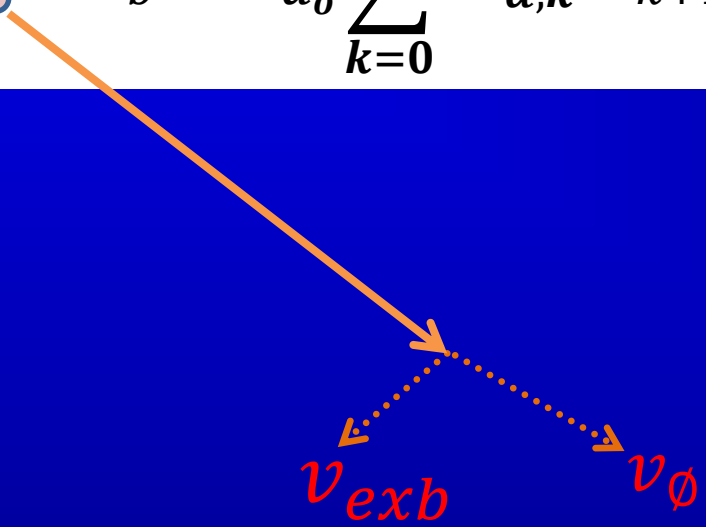
Error Covariances (B)

For densities $\rightarrow B_{X_0}$

For \mathbf{v}_{exb} and $\mathbf{v}_\phi \rightarrow B_\alpha$

$$\begin{aligned}
 X_0 &= X_b + B_{X_0} \lambda_0 \\
 \alpha_0 &= \alpha_b + B_{\alpha_0} \sum_{k=0}^k M_{\alpha,k}^T \lambda_{k+1}
 \end{aligned}$$

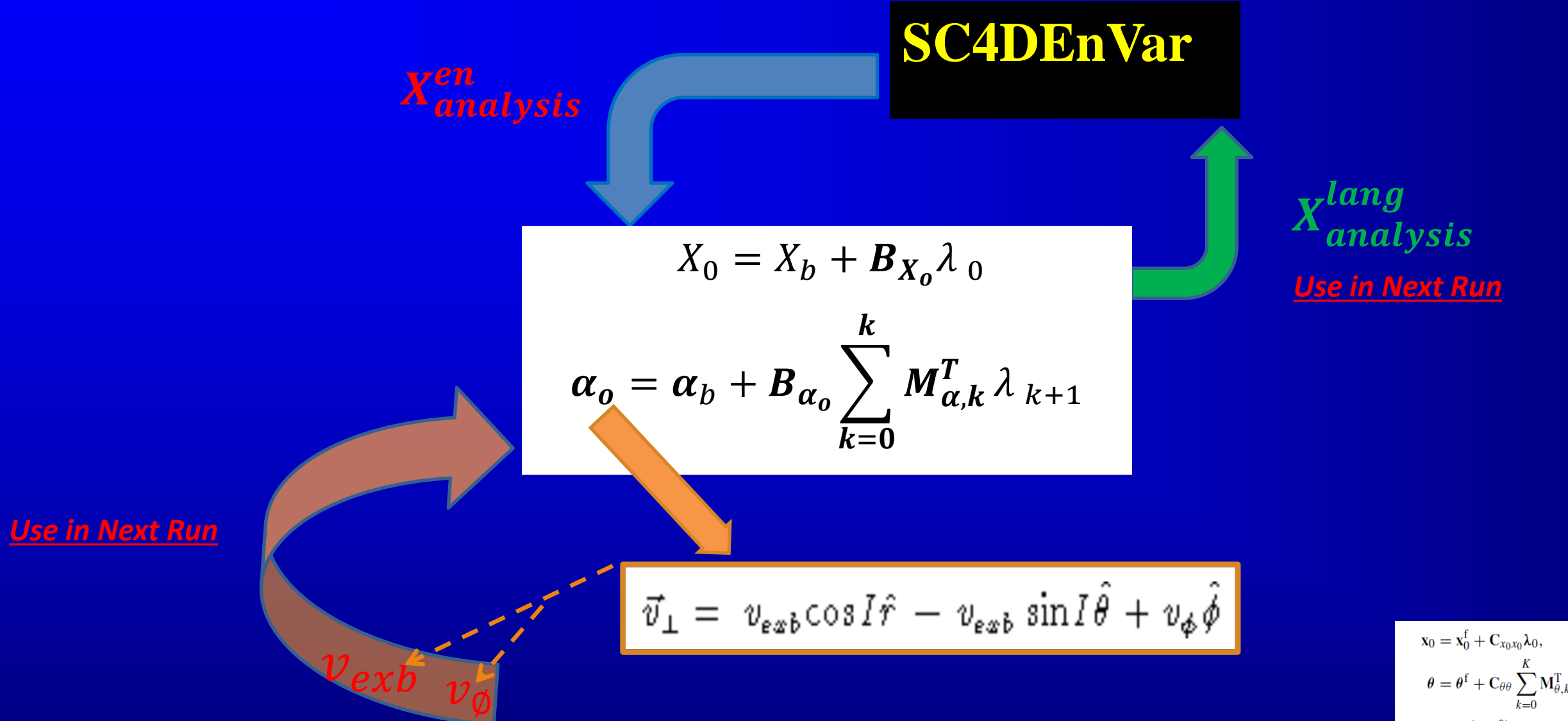
Ground GNSS
STEC



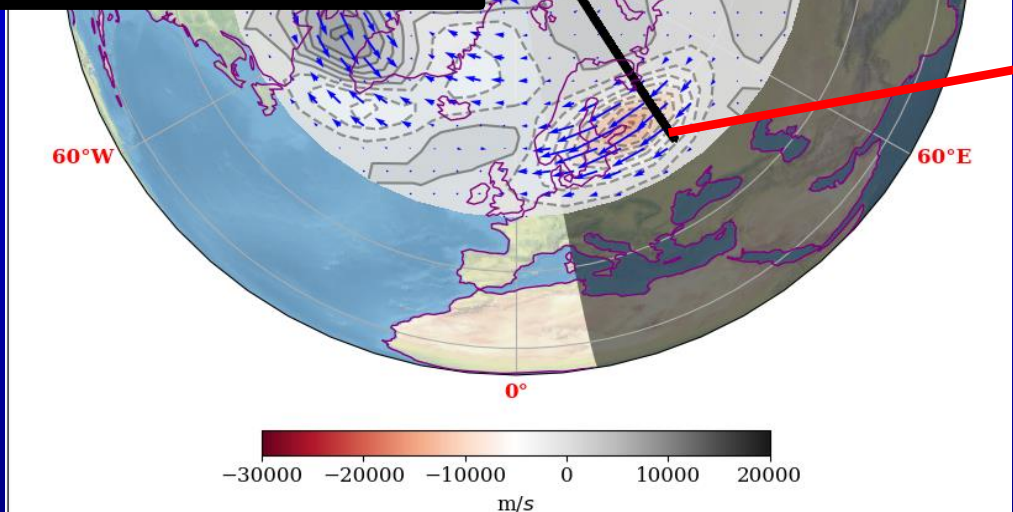
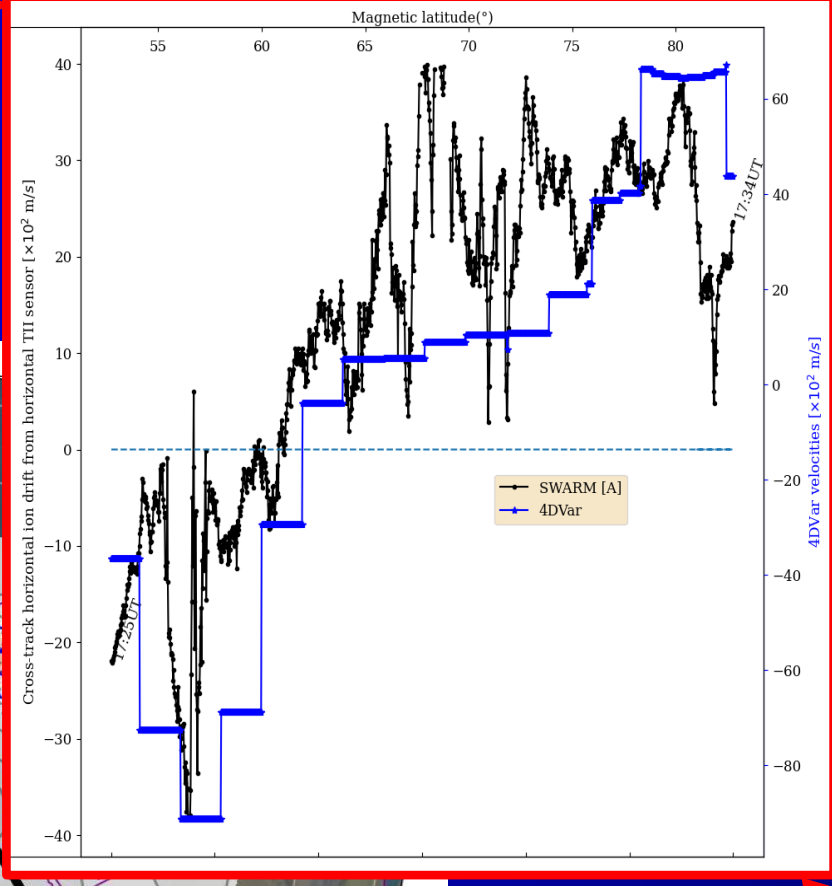
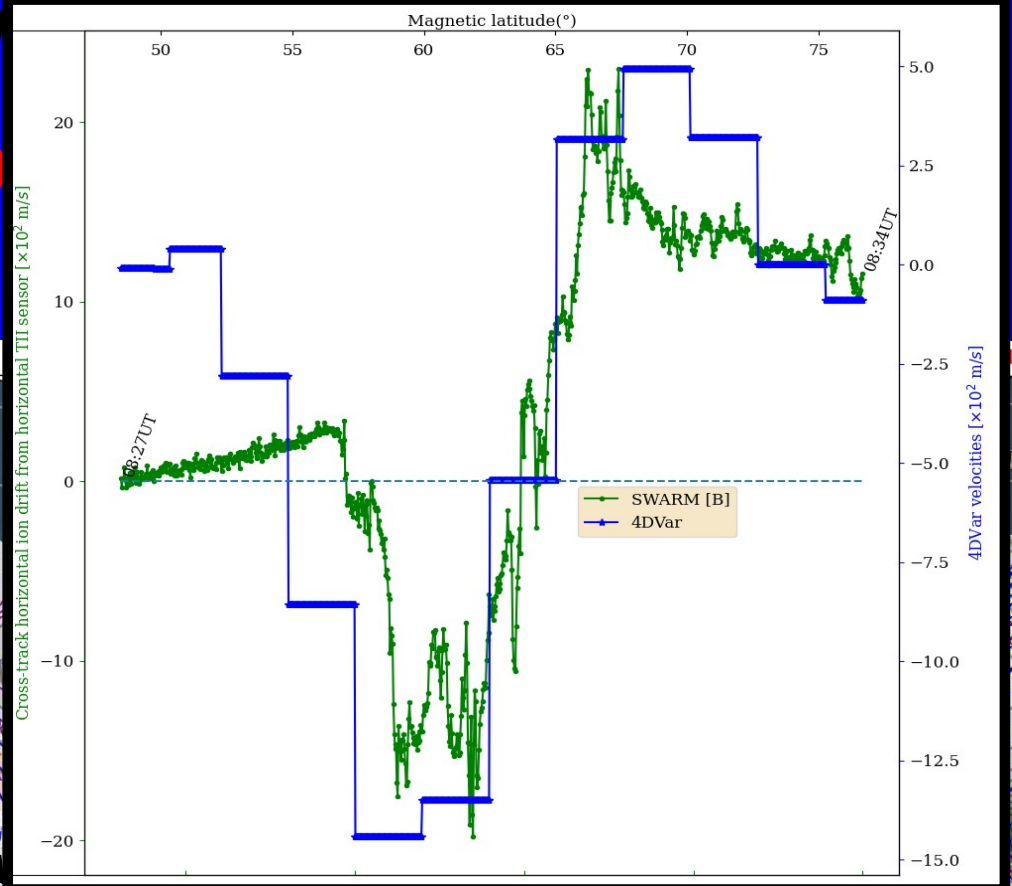
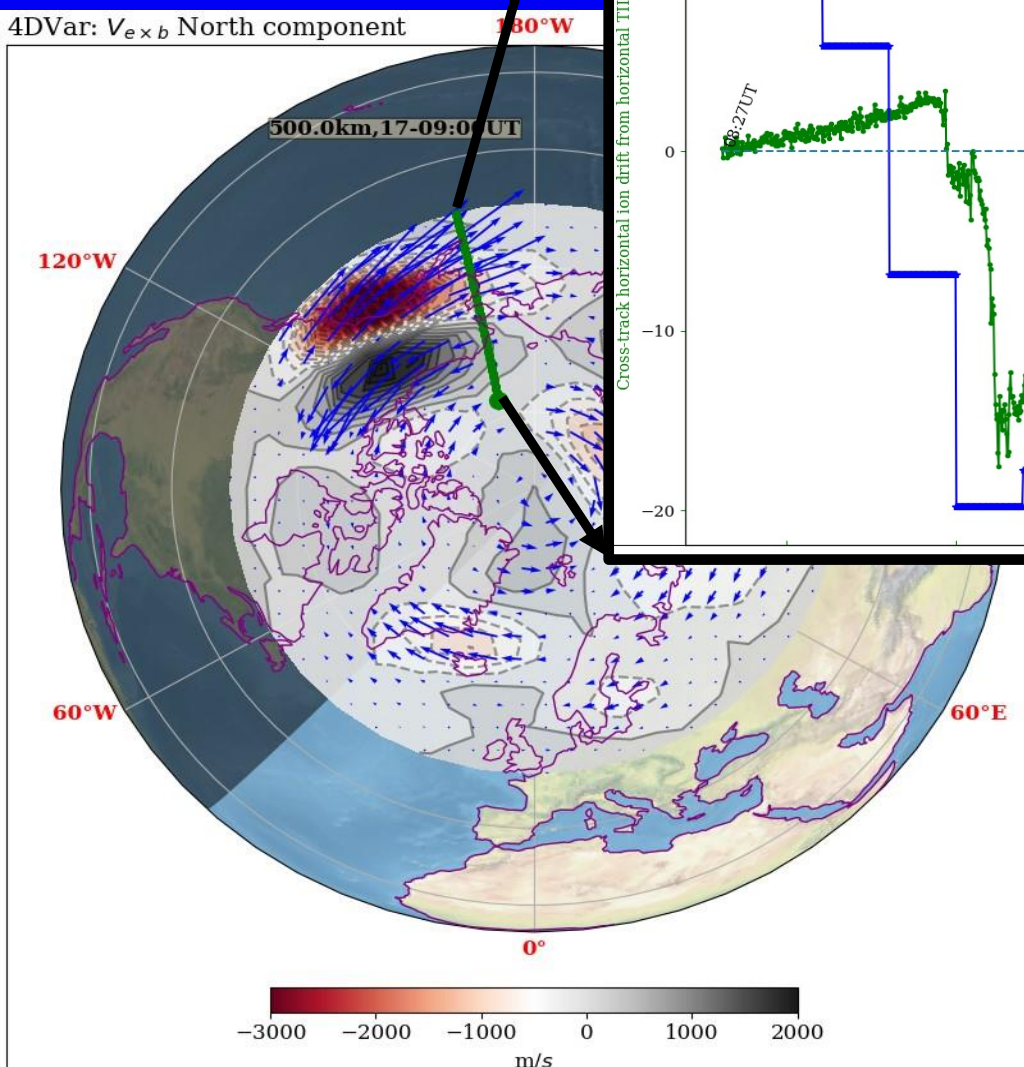
$$\vec{v}_\perp = v_{exb} \cos I \hat{r} - v_{exb} \sin I \hat{\theta} + v_\phi \hat{\phi}$$

New-Additions

- Use strong-constraint-Lagrange 4DVar to estimate v_{exb}



New-Addition



RO density Profiles (COSMIC)

ASSIMILATING OTHER DATA TYPES:

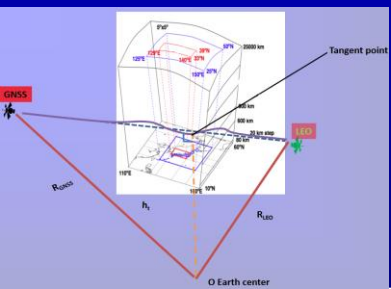
Ground GNSS
STEC

Ionosonde data
(densities)

**Strong constraint 4D-
Ensemble Var approach
(SC4DEnVar)**

In situ densities
(Swarm)

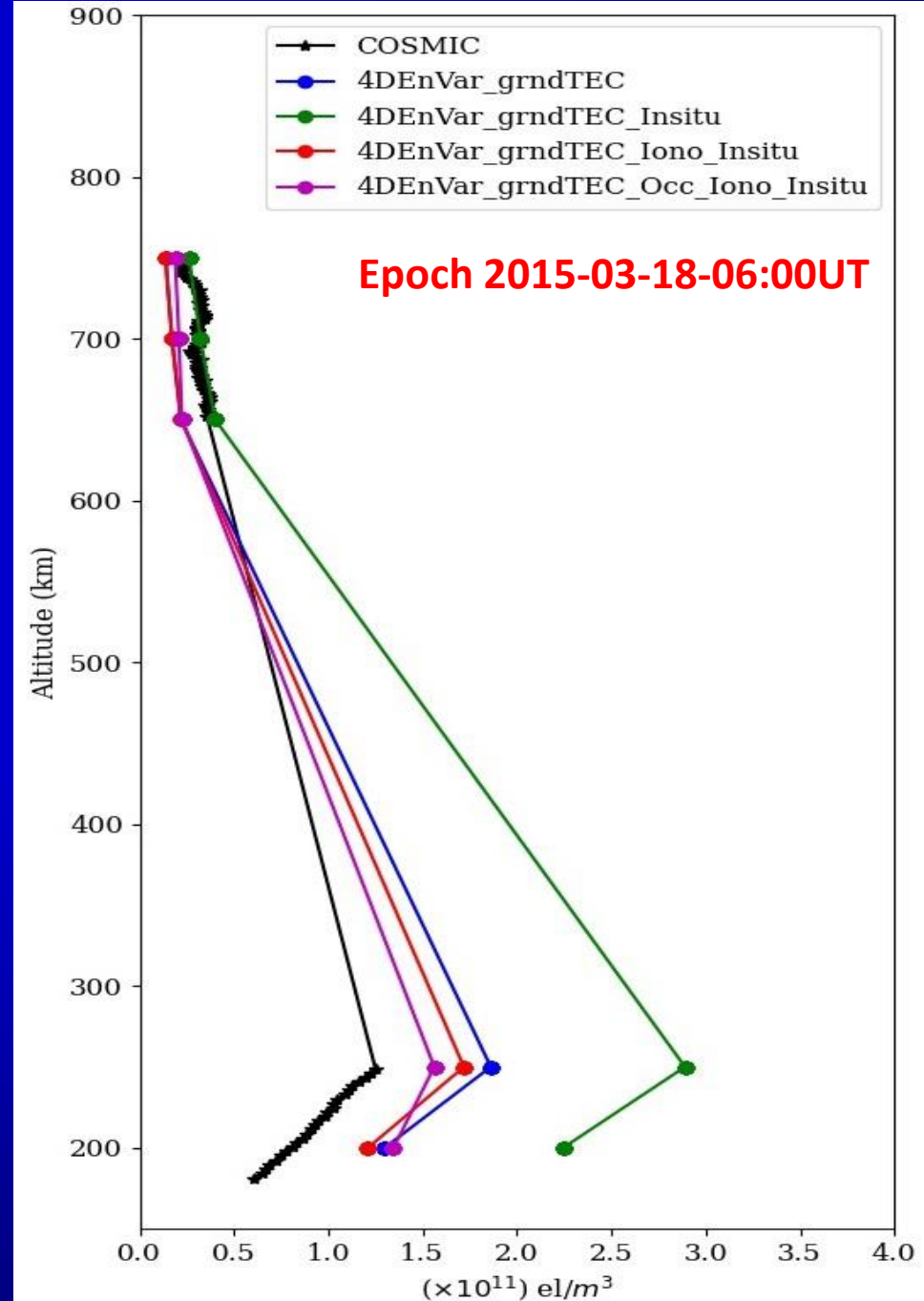
Radio occultation
STEC (OCC)



RO - COSMIC Vs SC4DEnVar

Focus is on the Tangent point in Volume

RO electron density profile(s)

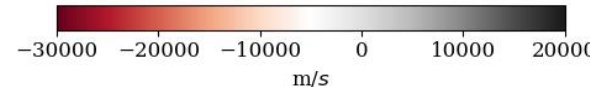
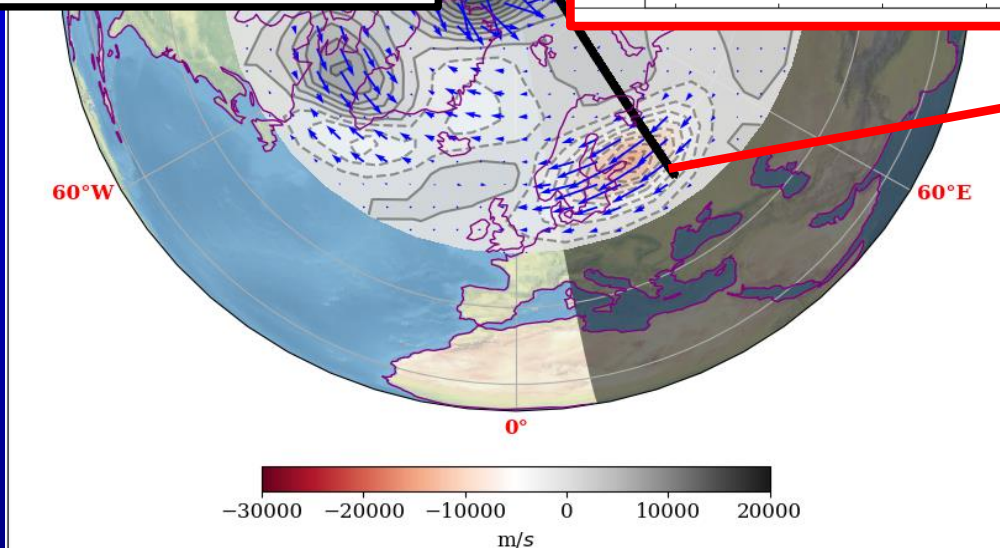
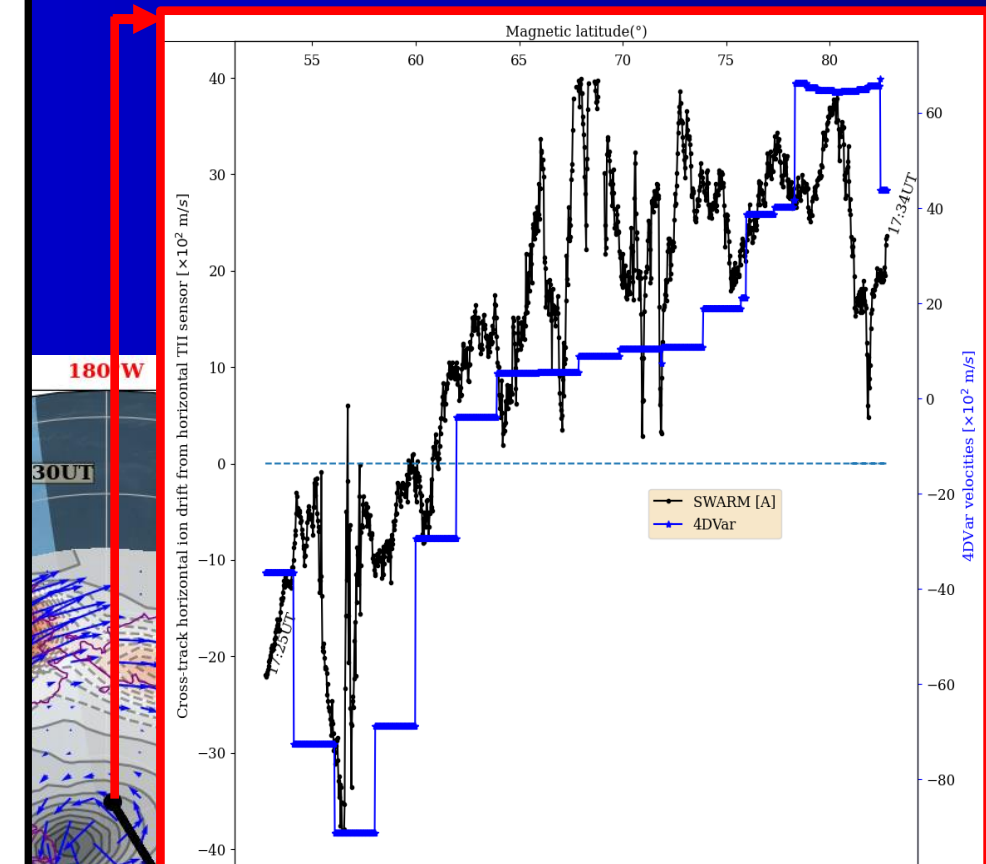
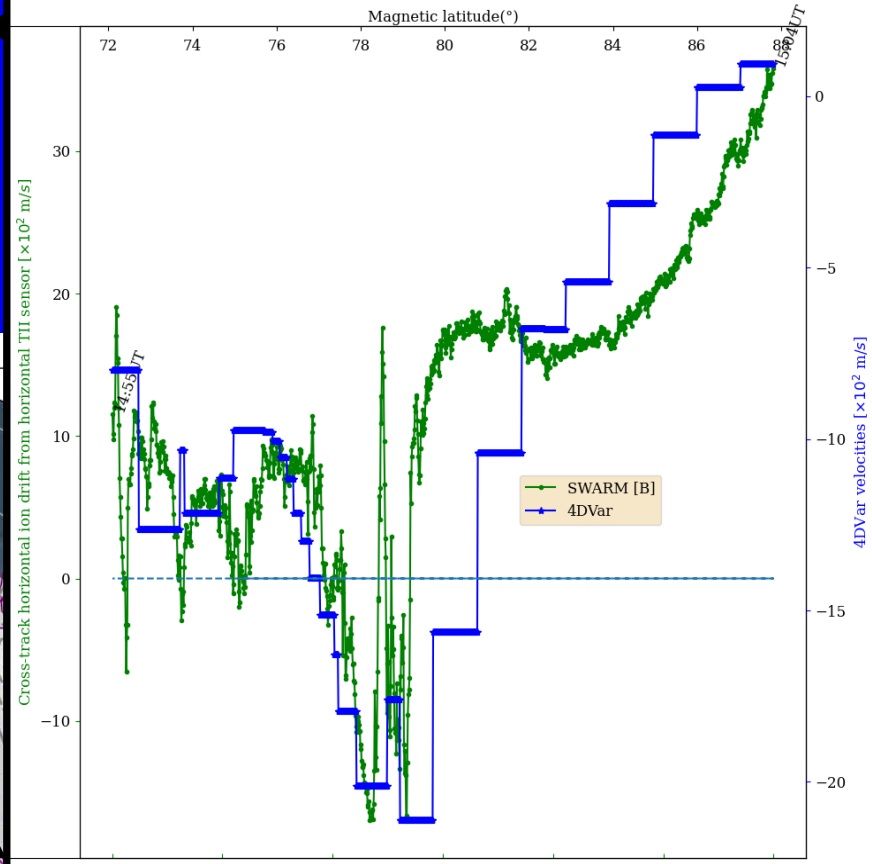
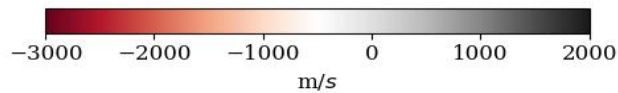
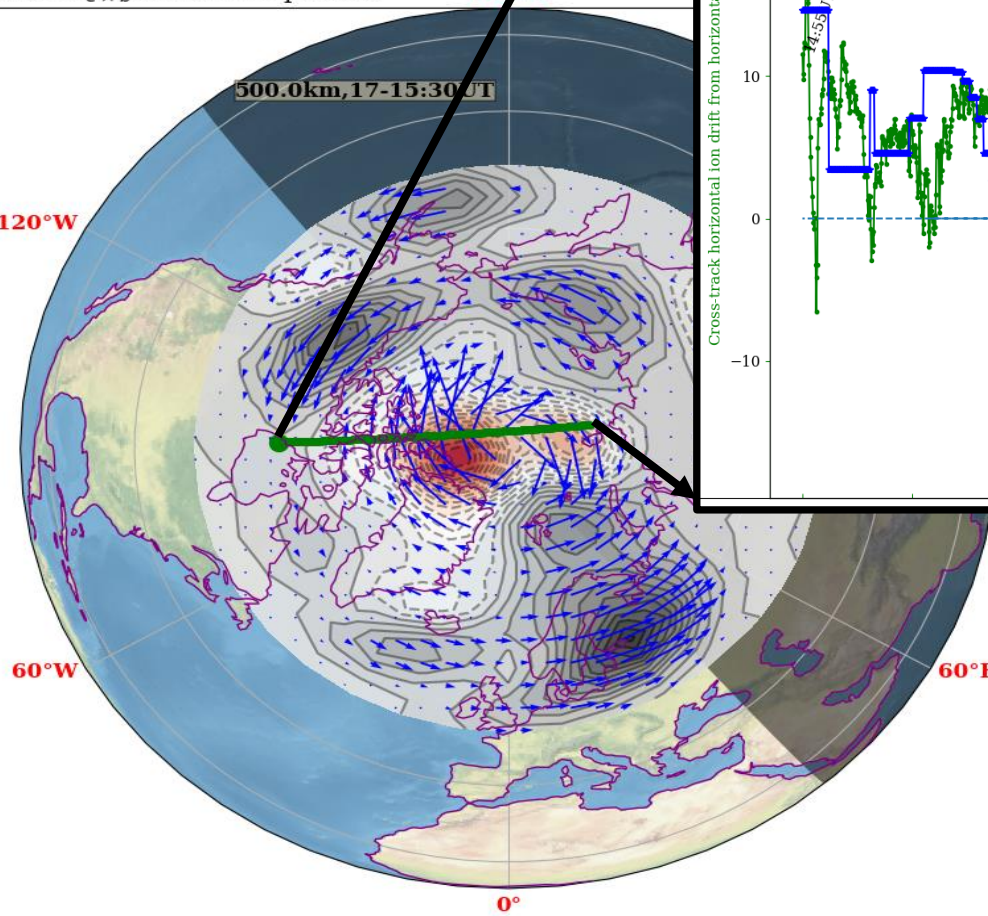


Thank You!

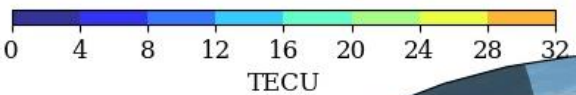
New-Addition

Var: $V_{e \times b}$ North component

180°W

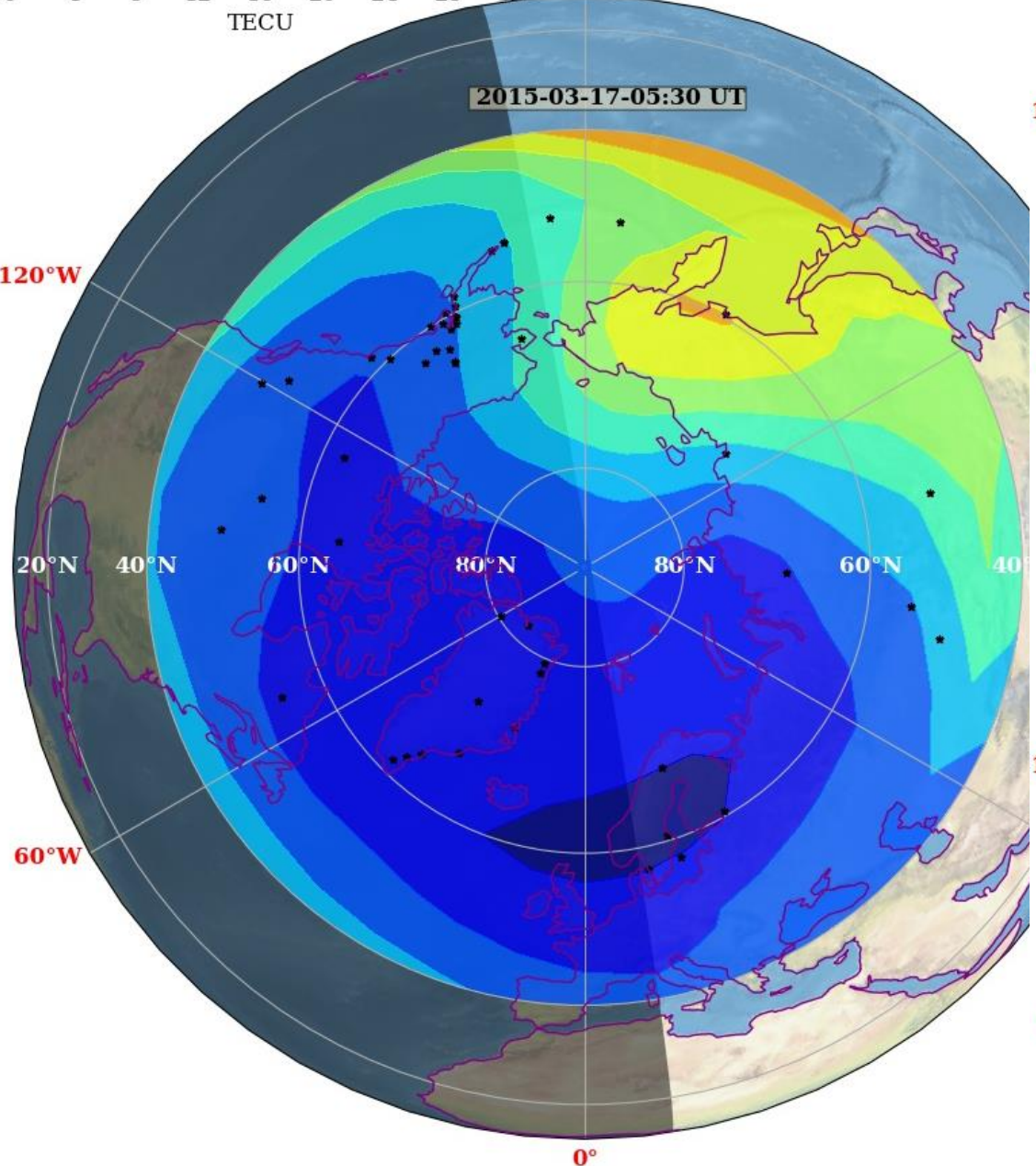


Slice at different altitudes: 300km, 350km, 400km and 450km



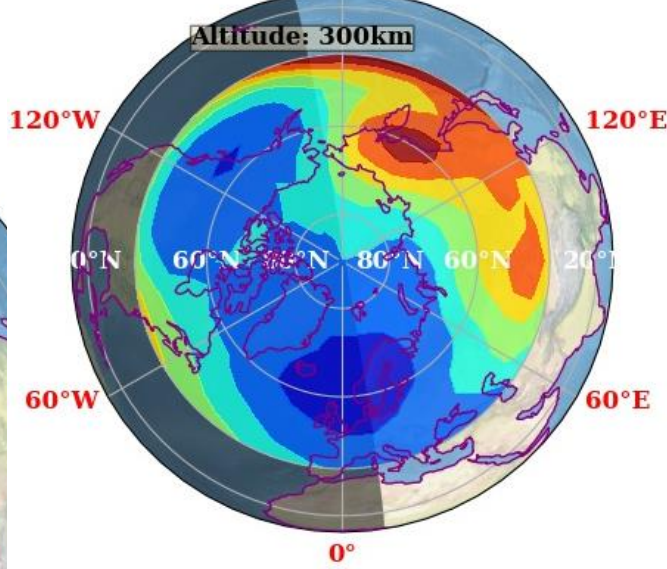
180°

2015-03-17-05:30 UT



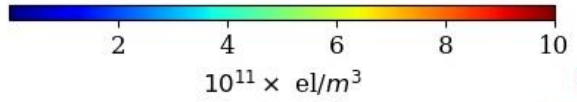
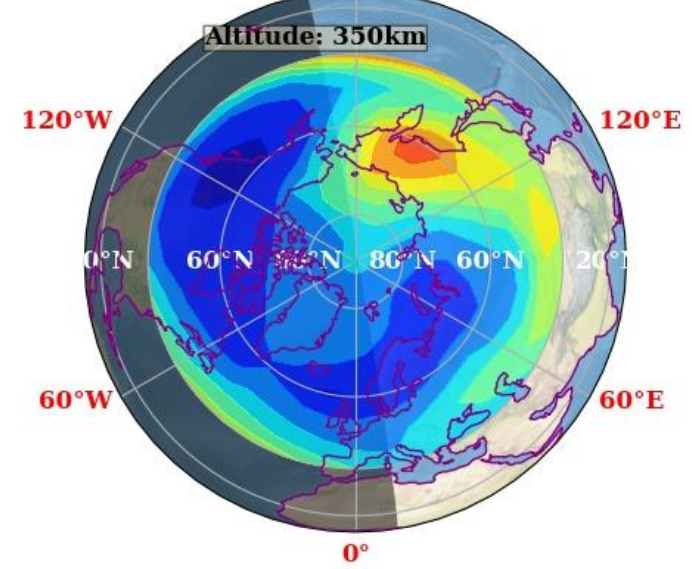
180°

Altitude: 300km



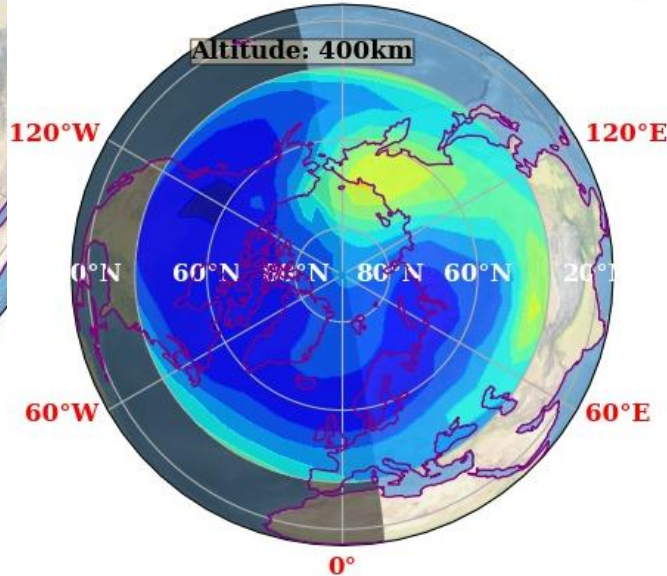
180°

Altitude: 350km



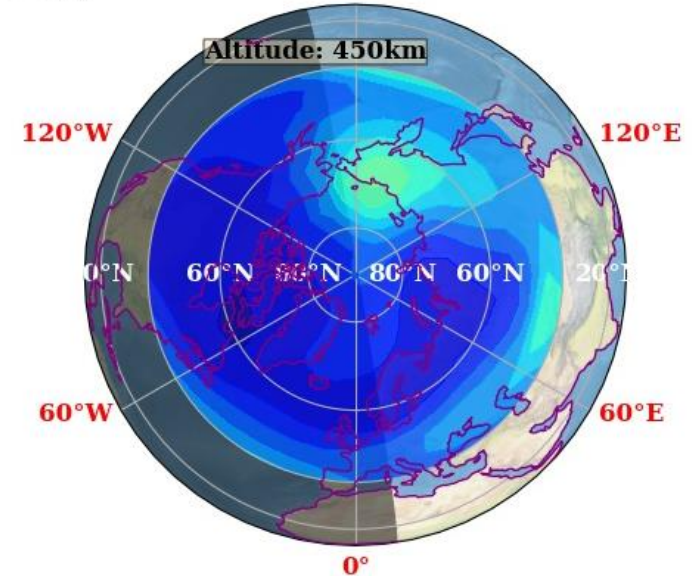
180°

Altitude: 400km

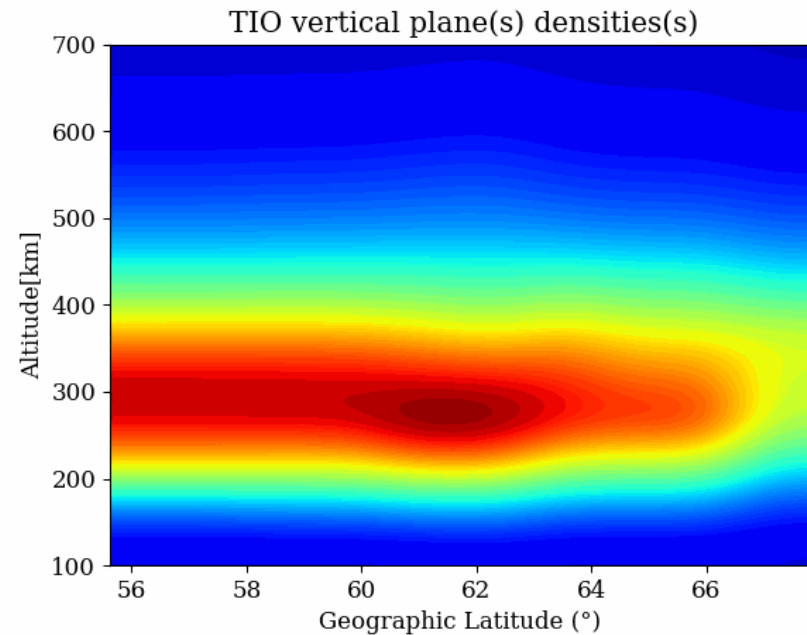
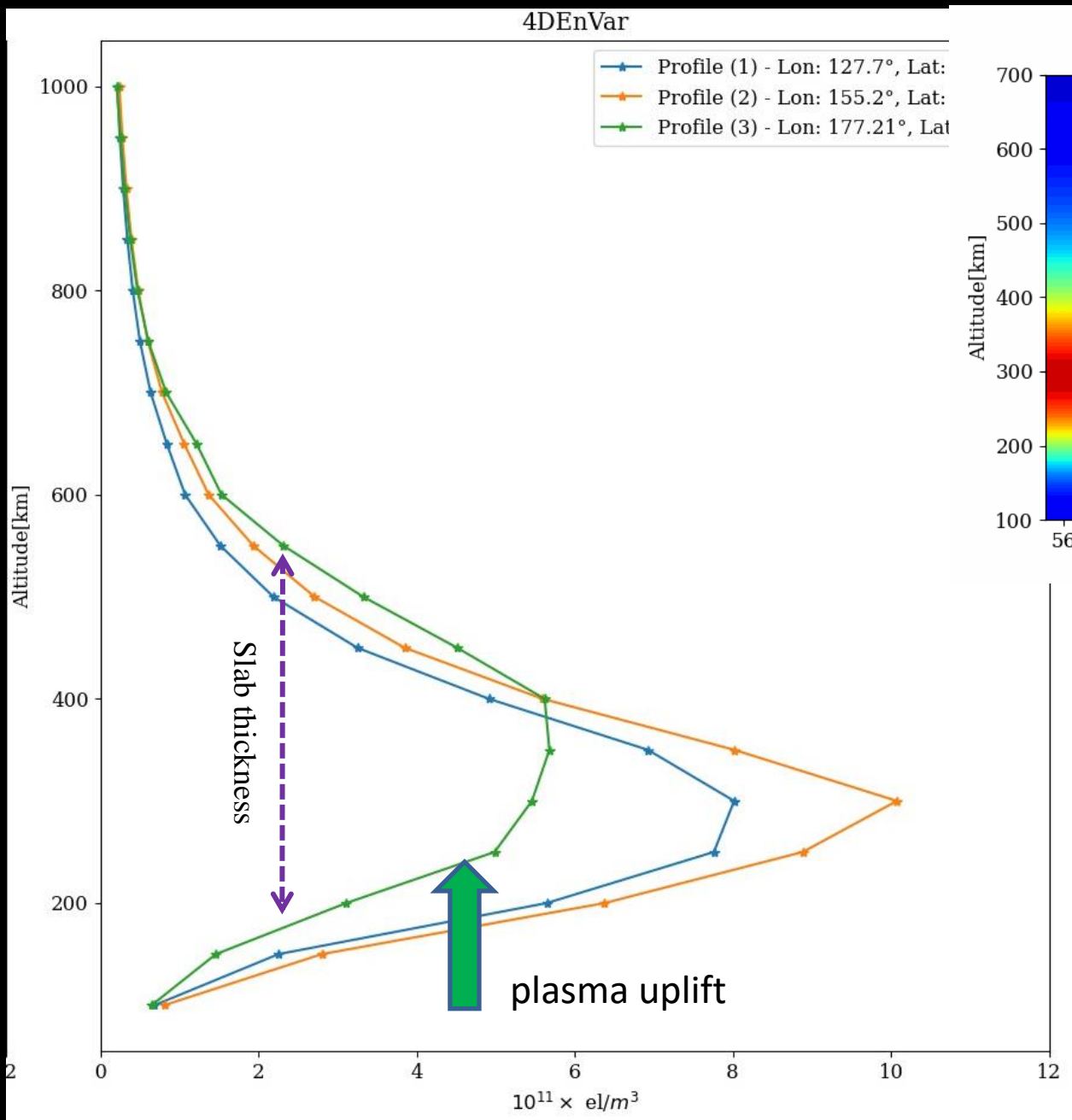
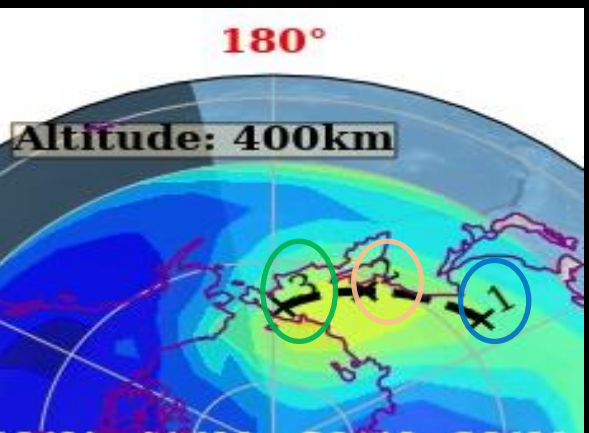
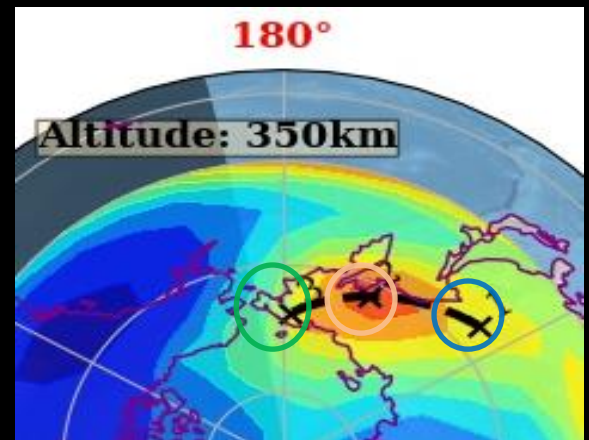
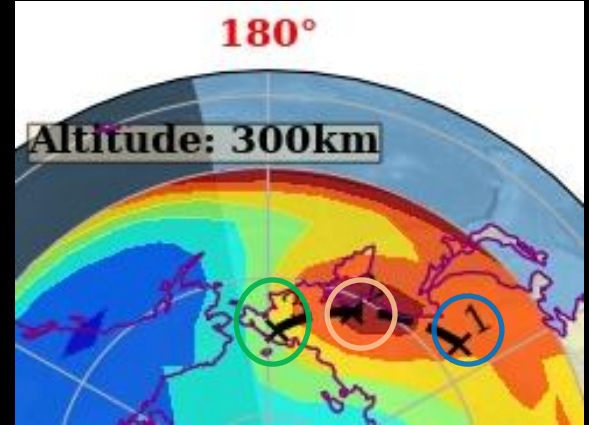


180°

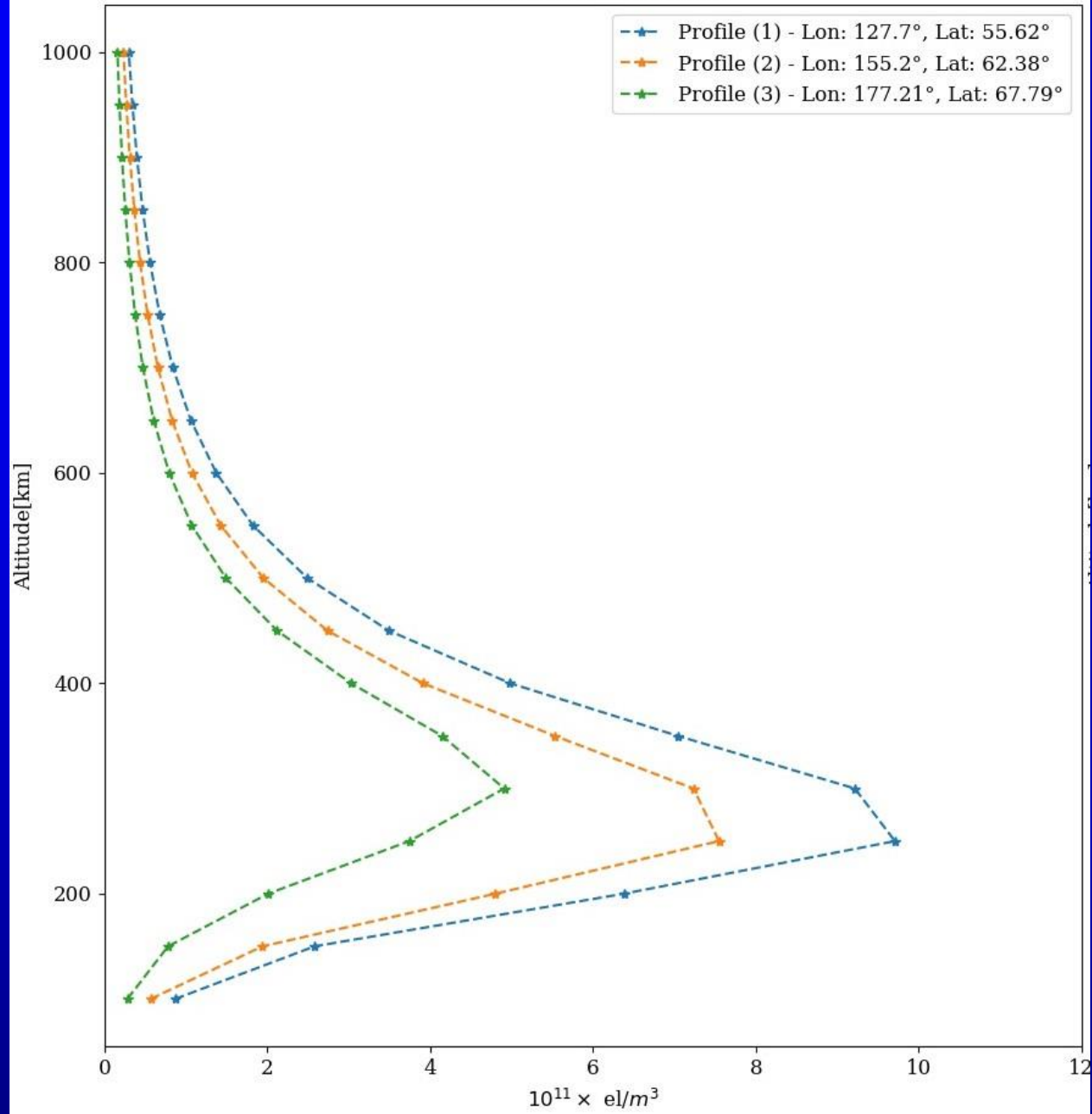
Altitude: 450km



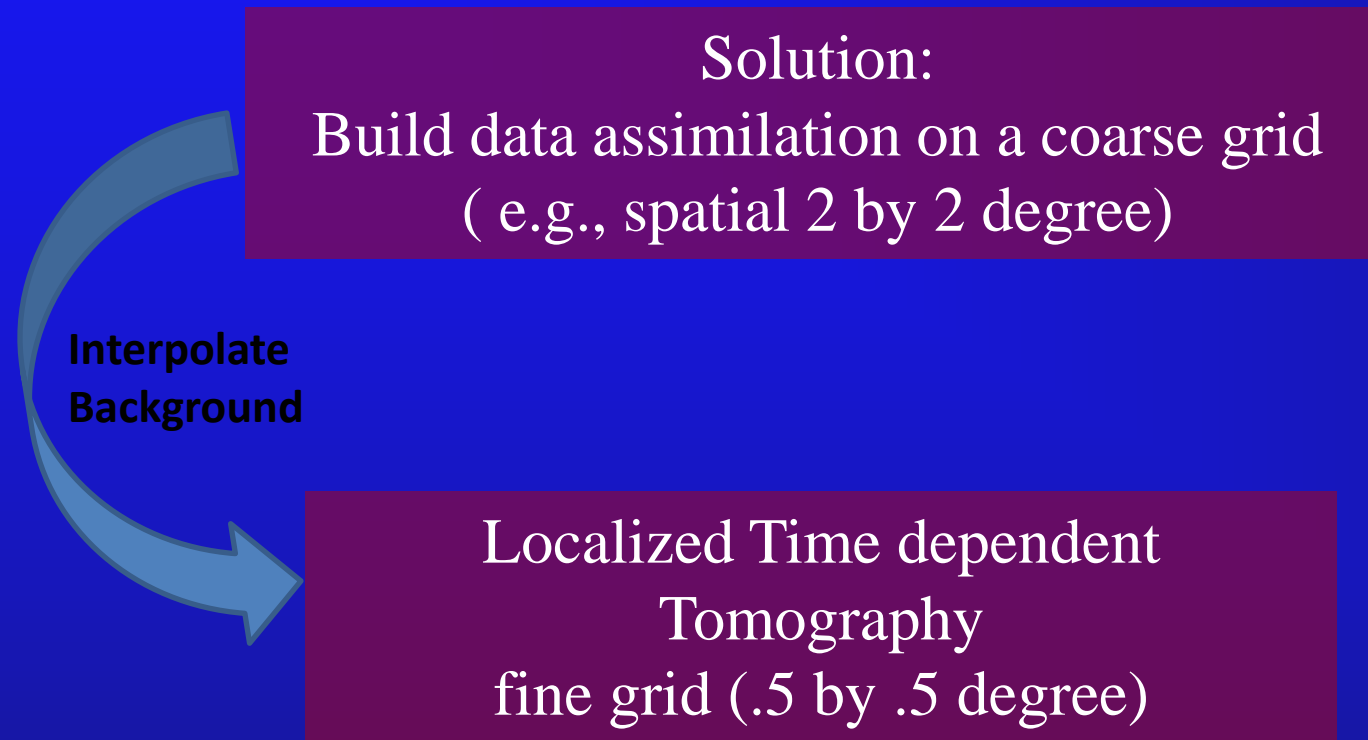
Slice at different altitudes: 300km, 350km, 400km and 450km



Background: IRI-2016



- In most cases the imaged structures requires a high spatial and temporal resolution. Particularly at the the edge of a patch or TOI, where we could have horizontal gradients.



DATA ASSIMILATION TECHNIQUE

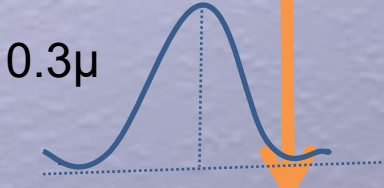
Initialize from IRI-2016

Strong constraint 4D-Ensemble Var approach (SC4DEnVar)

1. Sensitivities

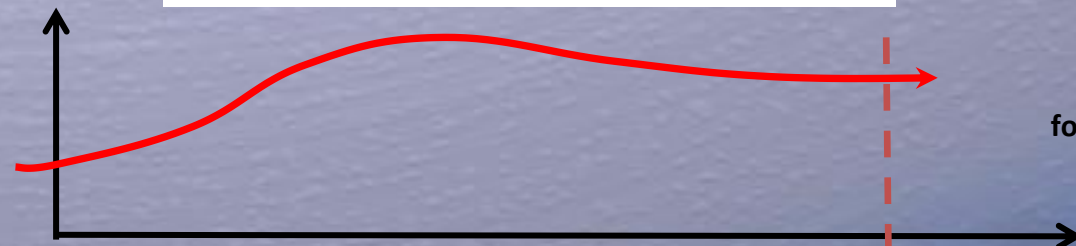
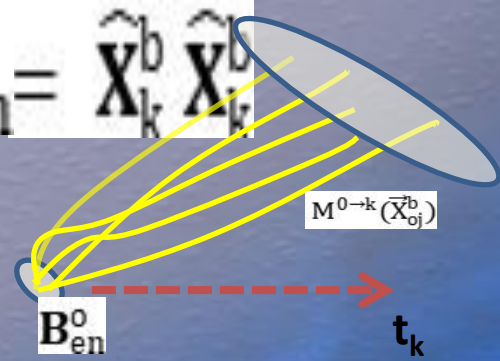
$$\tilde{\mathbf{M}}_k \times \frac{\partial \mathbf{h}_k}{\partial \bar{\mathbf{X}}_k}, \quad \tilde{\mathbf{H}}_k = \frac{\partial \mathbf{h}_k}{\partial \bar{\mathbf{X}}_k}$$

Use Ensembles: Perturb IRI inputs
 e.g: Rz12, IG12, F10.7 daily, hmF2, Kp :- 30 Members

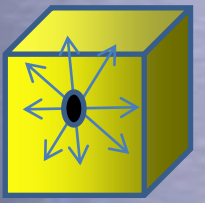


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$$\vec{\mathbf{X}}_{k+1} = \vec{\mathbf{X}}_b^{k+1} + (\vec{\mathbf{X}}_k - \vec{\mathbf{X}}_b^k) * \exp(-dT/\tau)$$



2. Spread of new information Error Covariances (B)



B

3D