

Current Status and Future Plans for the TROPOMI/Sentinel-5P L2 Cloud Product

R. Lutz⁽¹⁾, V. Molina García⁽¹⁾, A. del Aguila⁽¹⁾, F. Romahn⁽¹⁾, A. Argyrouli^(1,3), D. Loyola⁽¹⁾, R. Siddans⁽²⁾

(1) German Aerospace Center (DLR)

(2) Rutherford Appleton Laboratory (RAL)

(3) Technical University Munich (TUM)

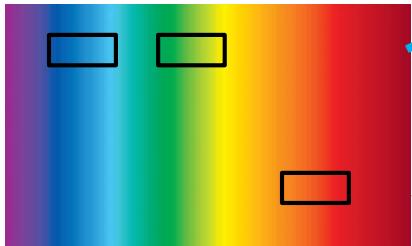
Sentinel-5P: 5 Years Anniversary
Taormina, Italy
13 October 2022



OCRA & ROCINN – Algorithm Overview

OCRA

Optical Cloud
Recognition Algorithm



ROCINN

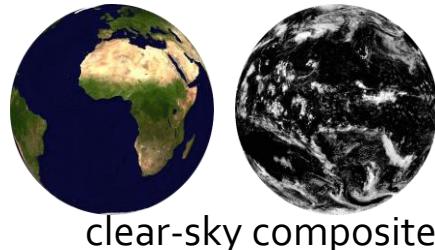
Retrieval of Cloud Information
using Neural Networks



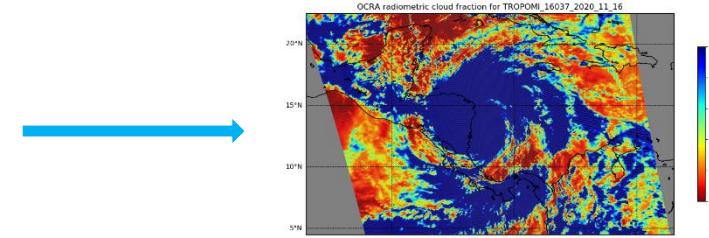
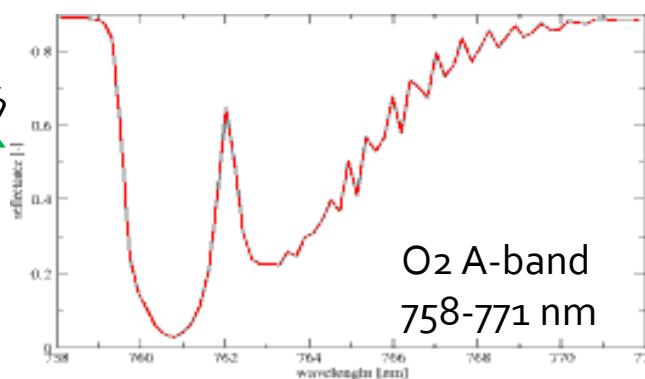
Hurricane Iota
©NASA worldview

color space approach

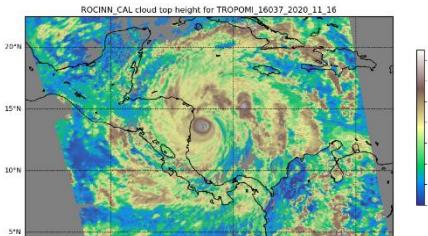
neural network approach



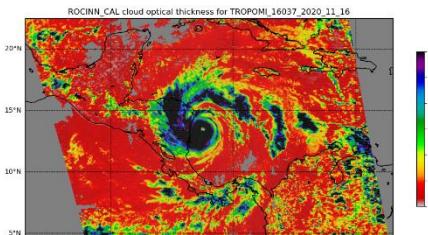
clear-sky composite



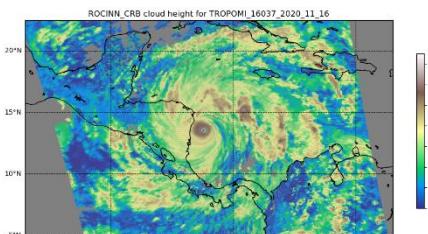
Radiometric
cloud fraction



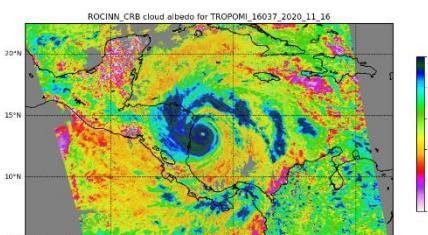
cloud top
height



cloud opt.
thickness



eff. cloud
height



eff. cloud
albedo

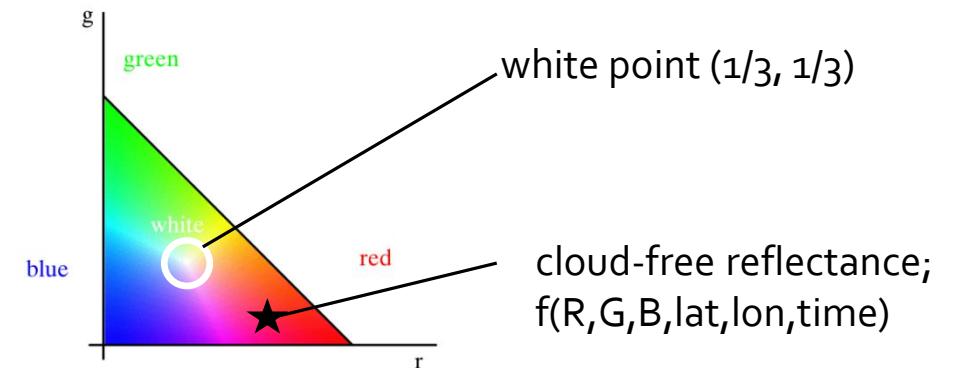
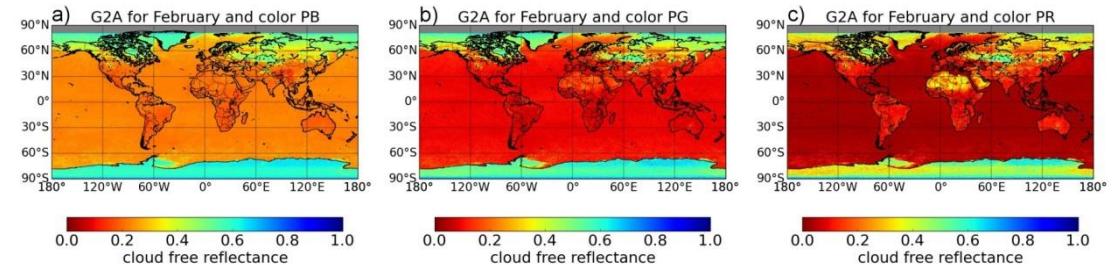
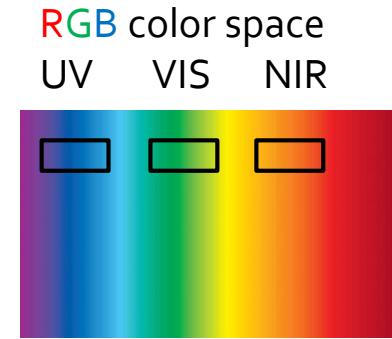


CAL
Clouds as
layers

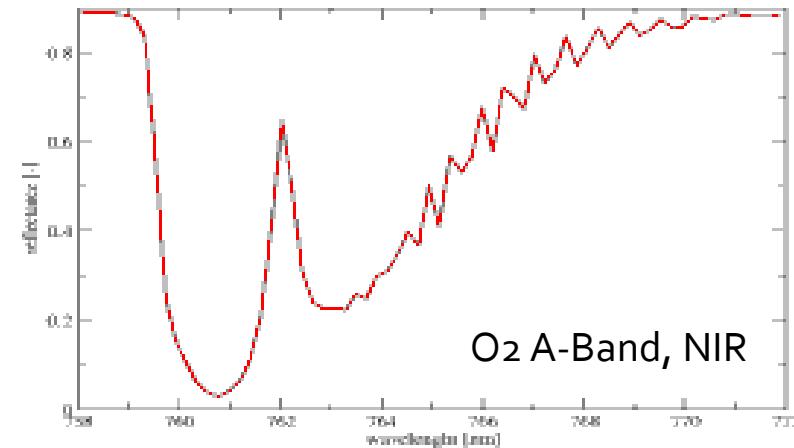
CRB
Clouds as
reflecting boundaries

OCRA Overview

- map measured reflectances to RGB color space
- generate cloud-free reflectance composite maps
 - monthly resolution
 - based on several years of data
- assume a cloud to be „white“ in RGB
 - white point defines fully cloudy condition
- radiometric cloud fraction is scaled between the cloud-free reflectance ($CF=0$) and the „white point“ ($CF=1$)

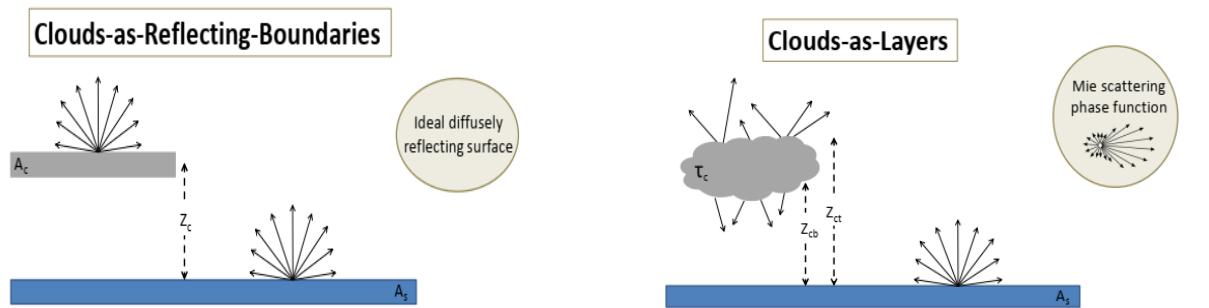


ROCIINN Overview



Fitting window: [758-771] nm

- two cloud models:
CRB: clouds as reflecting boundaries (Lambertian reflector)
CAL: clouds as layers (Mie-scattering liquid water droplets)



- Usage of neural networks and machine learning techniques

10:00-10:15

Advances in the application of deep neural networks for the retrieval of cloud properties for TROPOMI / Sentinel-5 Precursor (S5P)
 Fabian Romahn (DLR) **See presentation tomorrow!**

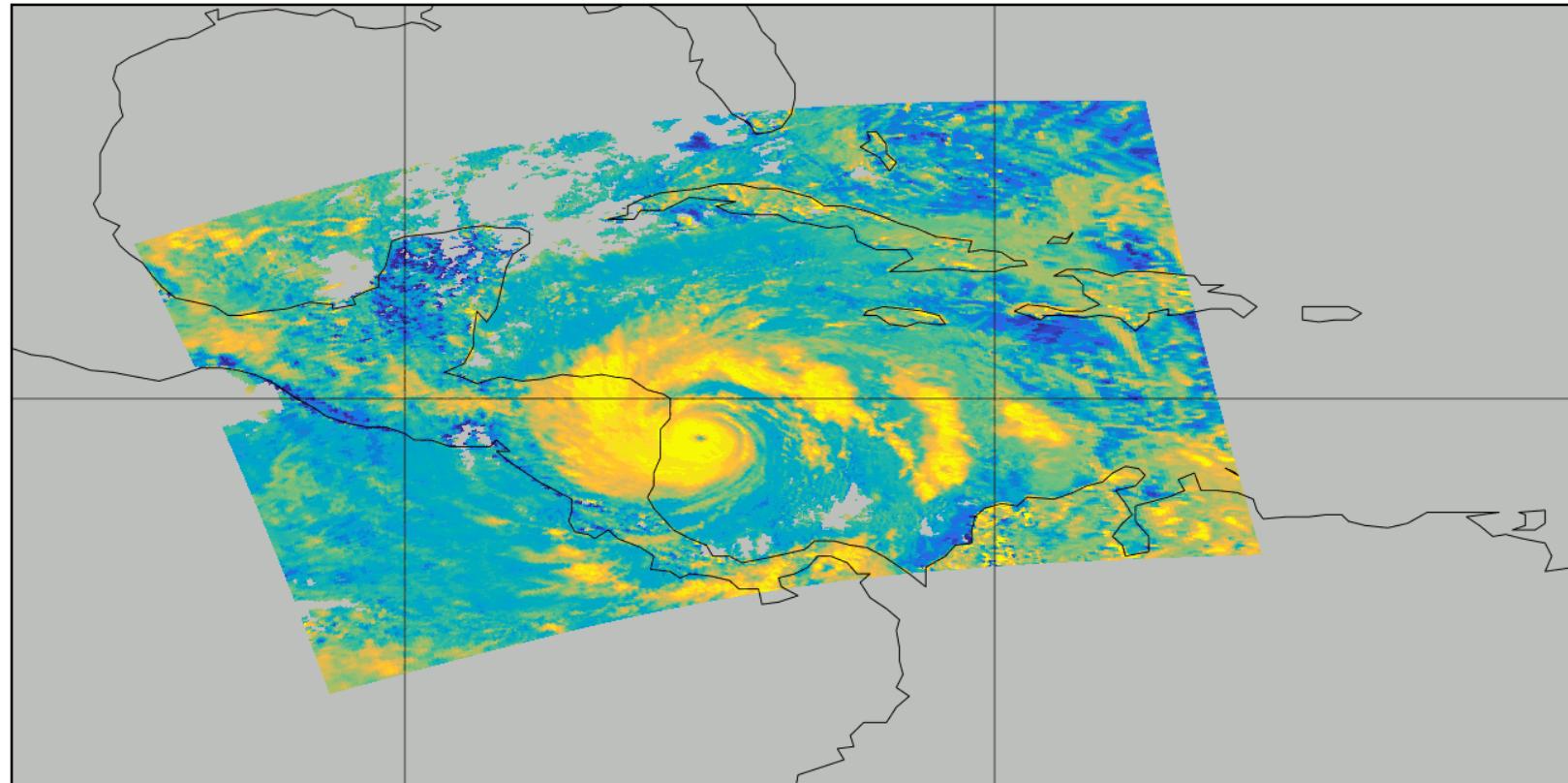
Loyola et al. (2018): The operational cloud retrieval algorithms from TROPOMI on board Sentinel-5 Precursor, *Atmos. Meas. Tech.*, 11, 409-427. <https://doi.org/10.5194/amt-11-409-2018>
 Loyola et al. (2016): Smart sampling and incremental function learning for very large high dimensional data, *Neural Networks*, Vol. 78, 75-87. <https://doi.org/10.1016/j.neunet.2015.09.001>

S5P – operational cloud products

Hurricane Iota, 2020-11-16, orbit 16037

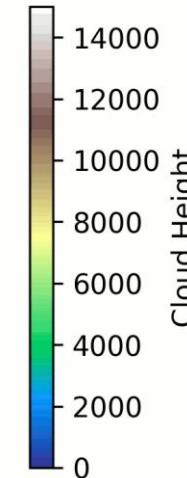
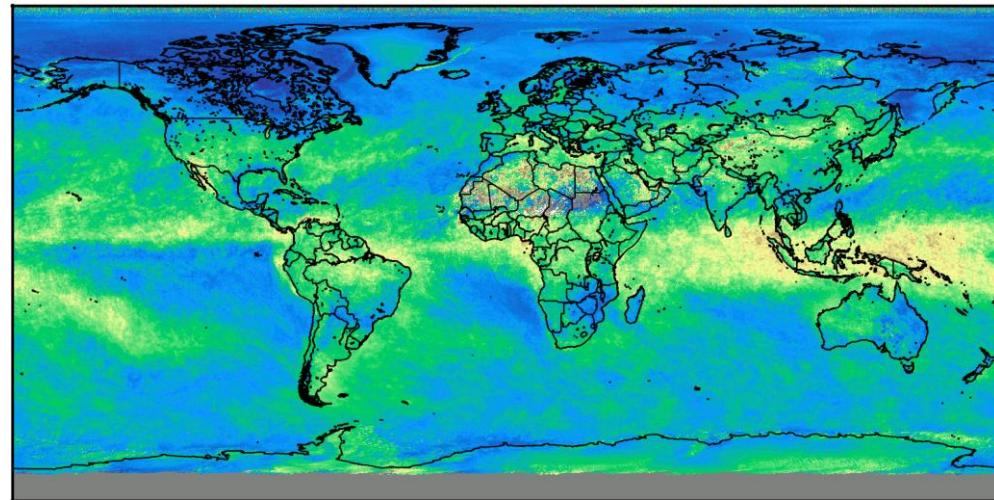


Hurricane Iota
©NASA worldview

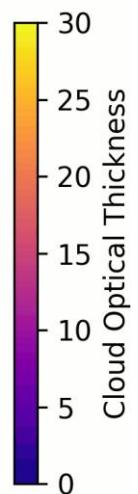
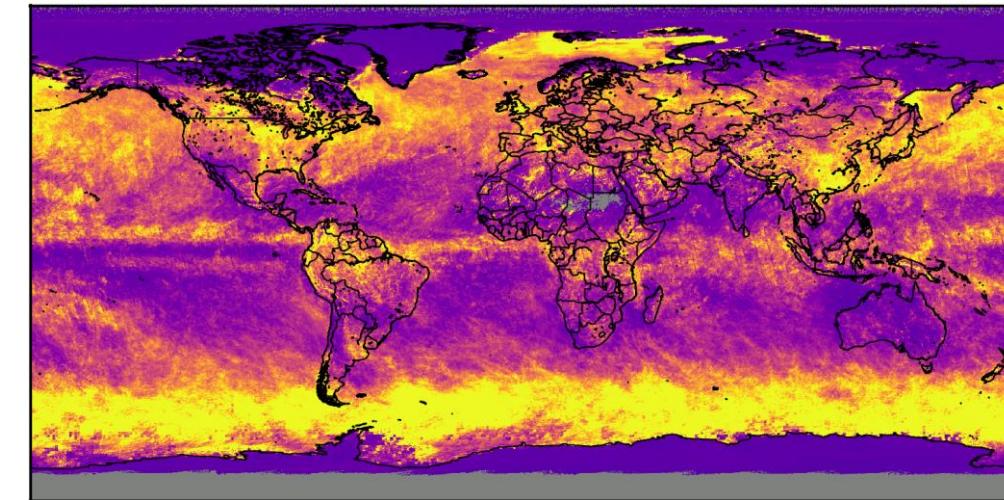


S5P – yearly temporal evolution

TROPOMI_2018_04_res02x02deg_monthly_mean_CTH_CAL.txt



TROPOMI_2018_04_res02x02deg_monthly_mean_COT_CAL.txt



ROCINN CAL cloud top height

ROCINN CAL cloud optical thickness

OCRA & ROCINN – documentation

<https://sentinel.esa.int/web/sentinel/technical-guides/sentinel-5p/products-algorithms>

<https://mpc-vdaf.tropomi.eu/index.php/clouds>

S5P/TROPOMI ATBD Cloud Products

sentinel-sp

document number	: SSP-DLR-L2-ATBD-4001
authors	: Diego Loyola, Ronny Lutz, Athina Argyrouli, Rob Spurr
CI identification	: CI-400-ATBD
issue	: 2.3
date	: 2021-06-25
status	: Released

ATBD

Sentinel-5 precursor/TROPOMI
Level 2 Product User Manual
Cloud Properties

TROPOMI

sentinel-sp

document number	: SSP-L2-DLR-PUM-4001
authors	: Fabian Römann, Matia Pedernana, Diego Loyola, Arneoud Apituley, Maarten Sneep,
CI identification	: CI-400-PUM
issue	: 03.03.00
date	: 2021-06-04
status	: released

PUM

TROPOMI

esa

Copernicus

S5P Mission Performance Centre
CLOUD [L2_CLOUD_] Readme

document number	: SSP-MPC-DLR-PRF-CLOUD
issue	: 2.3
date	: 2022-03-09
product version	: V02.03.00
status	: Released
Prepared by	R. Lutz (DLR) F. Römann (DLR) S. Compernolle (BIRA-IASB)
Reviewed by	J. Deutscher (BIRA-IASB) U.-C. Lambert (BIRA-IASB) D. Loyola (DLR) D. P. Veefkind (KNMI)
Approved by	R. Lutz (DLR) F. Römann (DLR) C. Zehner (ESA)
MPC ESL-L2 Product Lead	MPC ESL-L2 Processor Lead
MPC Validation Coordinator	MPC Validation Lead
MPC ESL-VAL Lead	MPC ESL-L2 Lead
MPC Technical Manager	MPC Mission Manager
ESL Manager	ESL Mission Manager

PRF

TROPOMI

esa

Copernicus

Sentinel-5 Precursor
Mission Performance Centre

Quarterly Validation Report of the
Copernicus Sentinel-5 Precursor
Operational Data Products #14:
April 2018 – March 2022

Prepared by	Sentinel-5 Precursor Mission Performance Centre
Reference	SSP-MPC-4008-ROCVR-14.01.01-20220408
CI identification	DLR-MPC-ROCVR
Document update	#14
Issue	14.01.01
Date of issue	2022-04-08
Status	Final
Distribution	Public

AERONET
SRON
KNMI
NILU
S&T
beispo

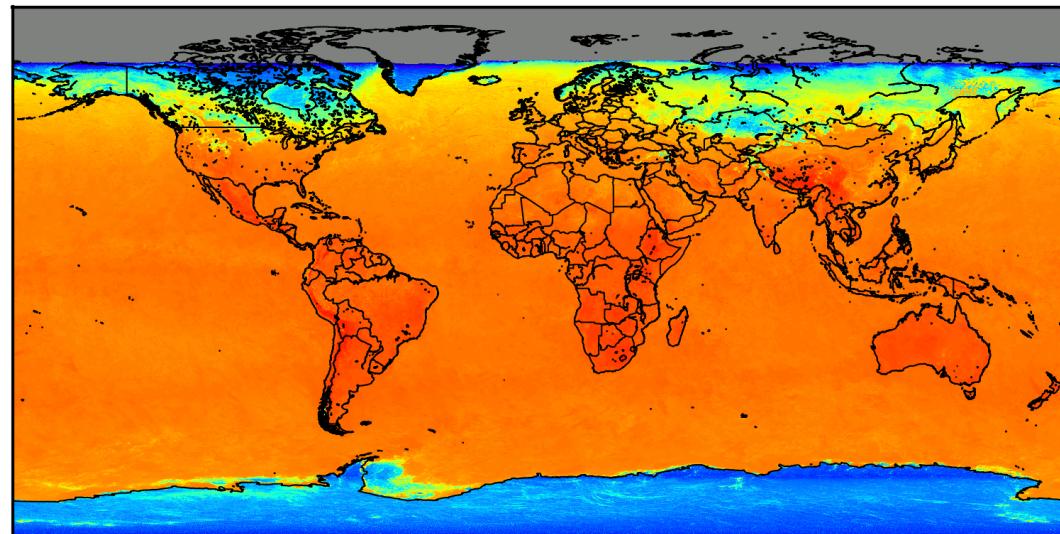
ROCVR



OCRA & ROCINN – recent improvements and upcoming developments (I)

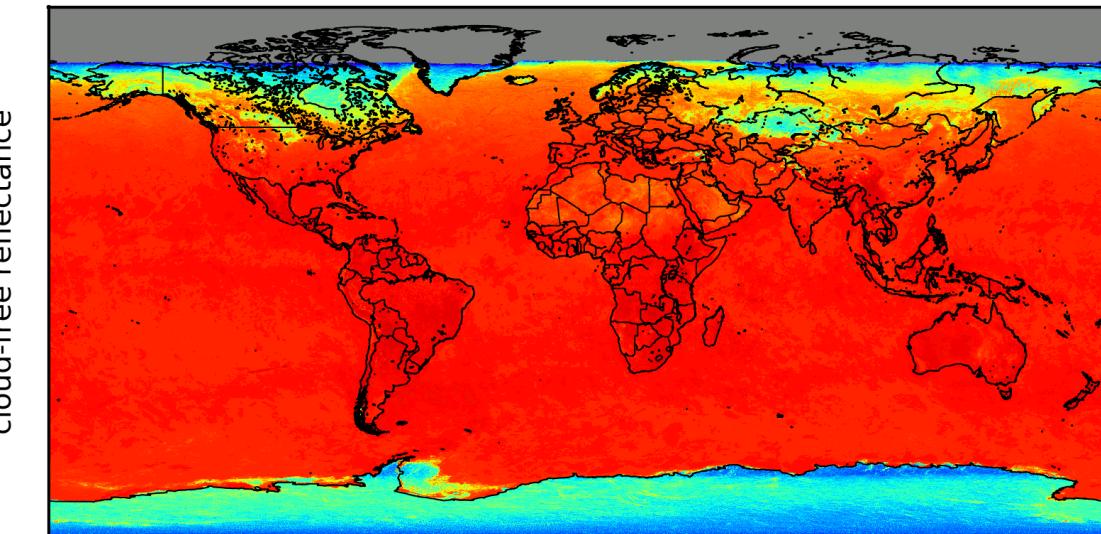
- OCRA clear-sky maps have been updated based on 3 years of TROPOMI data and to include L1 degradation
 - this improved the cloud fraction retrieval, particularly at low cloud coverages

TROPOMI_01_monthly_cloudfree_res02x02deg_3years_mincol_B.txt

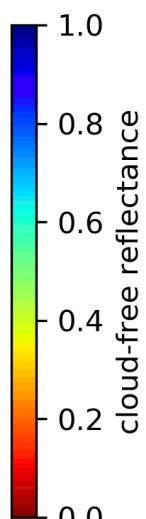


OCRA blue channel

TROPOMI_01_monthly_cloudfree_res02x02deg_3years_mincol_G.txt



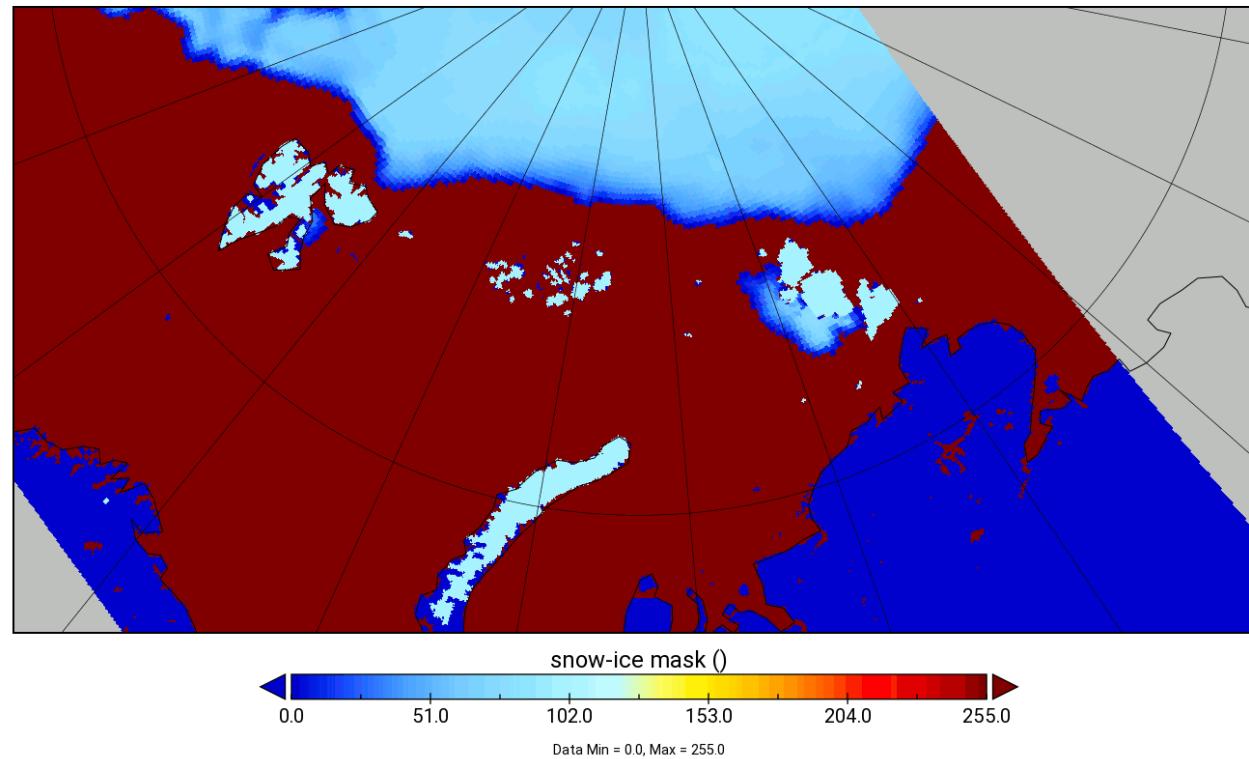
OCRA green channel



OCRA & ROCINN – recent improvements and upcoming developments (II)

- ROCINN surface albedo climatology is replaced by daily surface albedo retrieval (GE_LER) using TROPOMI measurements and the surface albedo map is updated on a daily basis (G₃_LER)
 - this improved the cloud retrieval particularly over snow/ice surfaces

ECMWF snow-ice mask with NISE definitions, 2020-08-09, orbit 14625



OCRA & ROCINN – recent improvements and upcoming developments (III)

- ROCINN neural networks have been updated
→ this improved ROCINN in general

10:00-10:15

Advances in the application of deep neural networks for the retrieval of cloud properties for TROPOMI / Sentinel-5 Precursor (S5P)
Fabian Romahn (DLR) **See presentation tomorrow!**

Upcoming developments:

- Extension of the clear-sky composite maps from 3 years to 5 years
- ROCINN ice cloud parameterisation
 - this will improve both the cloud top height and optical thickness retrievals when ice clouds are present
 - the following slides will show why this is necessary



Routine validation with ground based data

- Routine validation of the TROPOMI L2_CLOUD product is performed with ground based CLOUDNET data in the framework of the ATM MPC: VDAF validation facility: <https://mpc-vdaf.tropomi.eu/index.php/clouds>

Compernolle et al.: Validation of the Sentinel-5 Precursor TROPOMI cloud data with Cloudnet, Aura OMI O₂–O₂, MODIS, and Suomi-NPP VIIRS, *Atmos. Meas. Tech.*, 14, 2451–2476, <https://doi.org/10.5194/amt-14-2451-2021>, 2021

Validation with satellite data

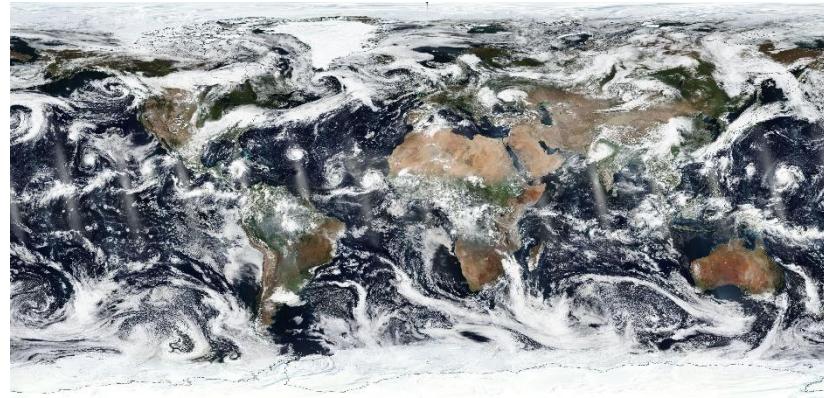
- VIIRS/S-NPP allows for reasonable spatio-temporal comparability due to close formation with S5P
- Re-gridded VIIRS cloud test products have been generated by RAL in the framework of the S5P MPC
- Comparisons for ROCINN_CAL CTH and COT
- data subsets:
 - surface condition: land (🌳) and water (🌊)
 - cloud phase: liquid phase (💧) and ice phase (❄️), based on VIIRS cloud phase probability (>90 %)



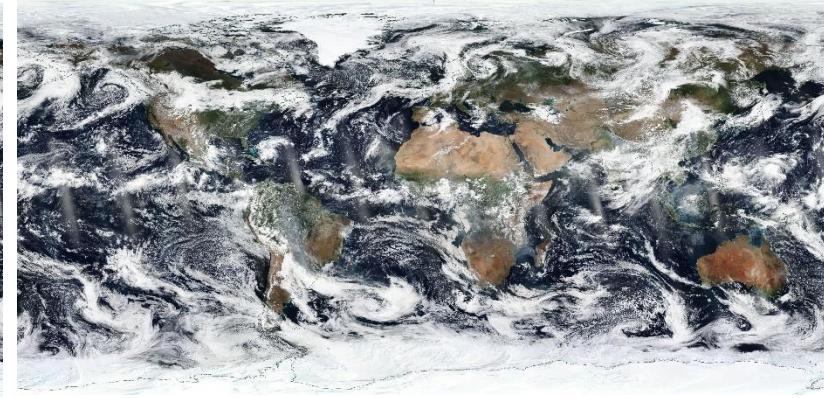
Comparison with satellite data from VIIRS/S-NPP – Global

SZA < 70°, qa > 0.5, most recent UPAS version 2.4

2018-09-09



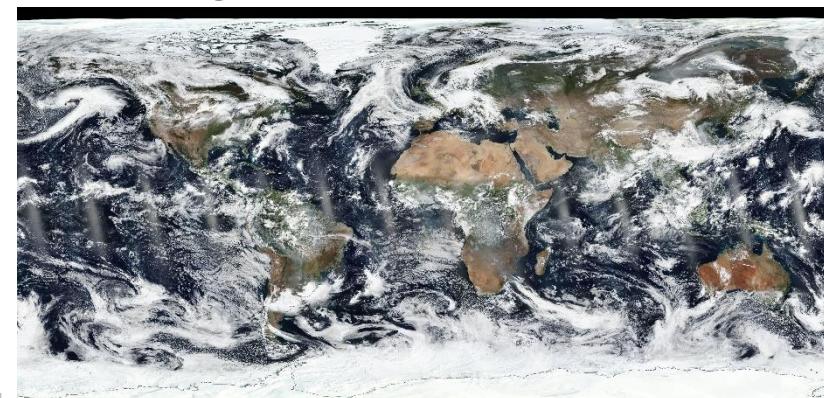
2019-09-11



2020-09-11



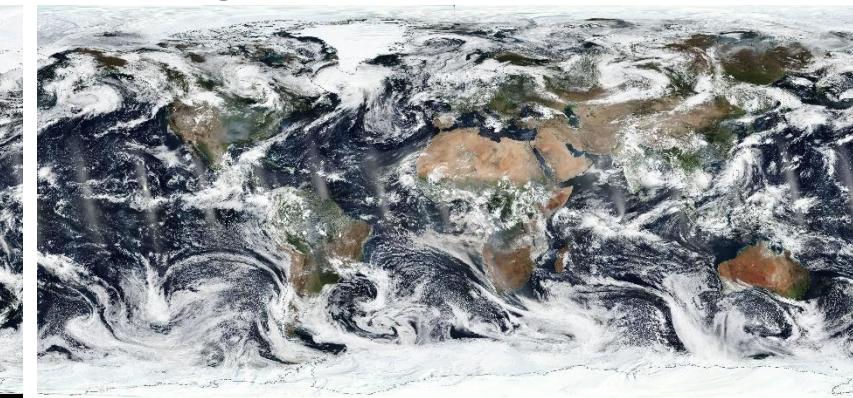
2020-09-26



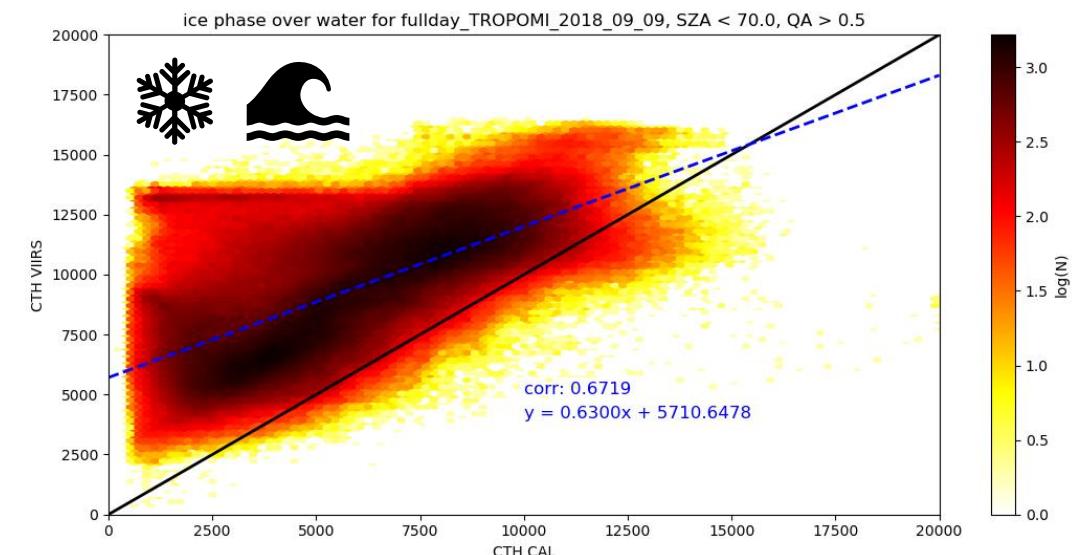
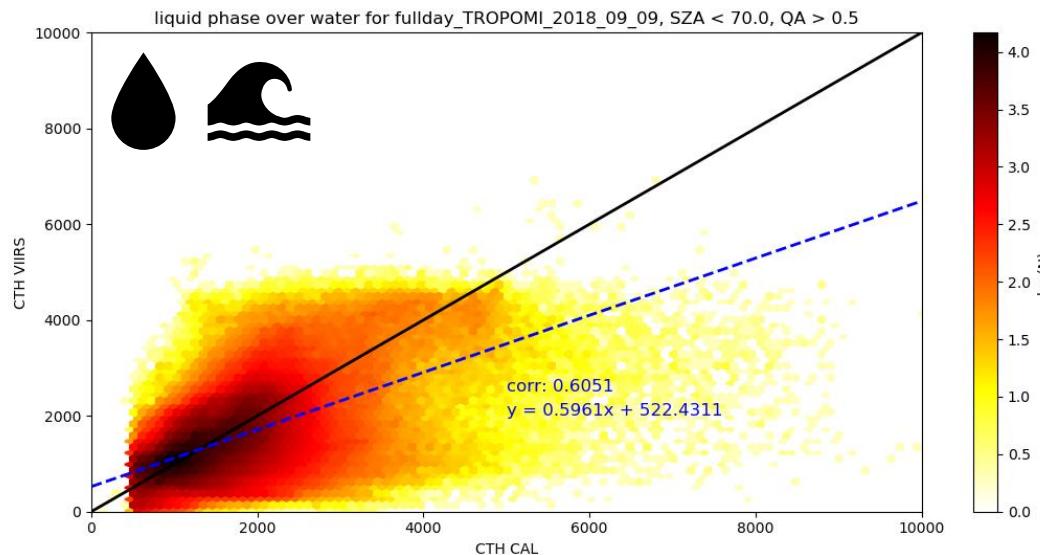
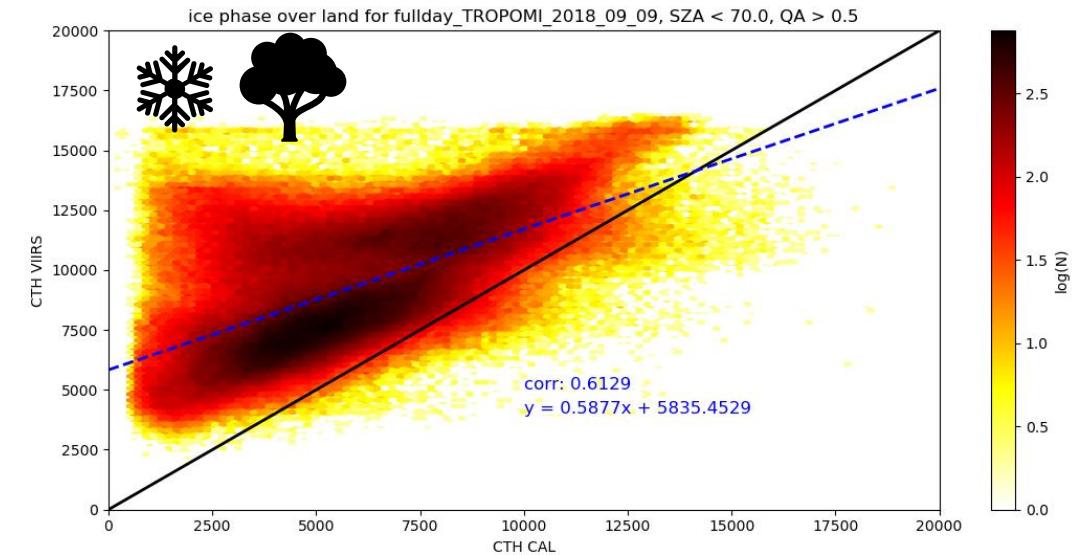
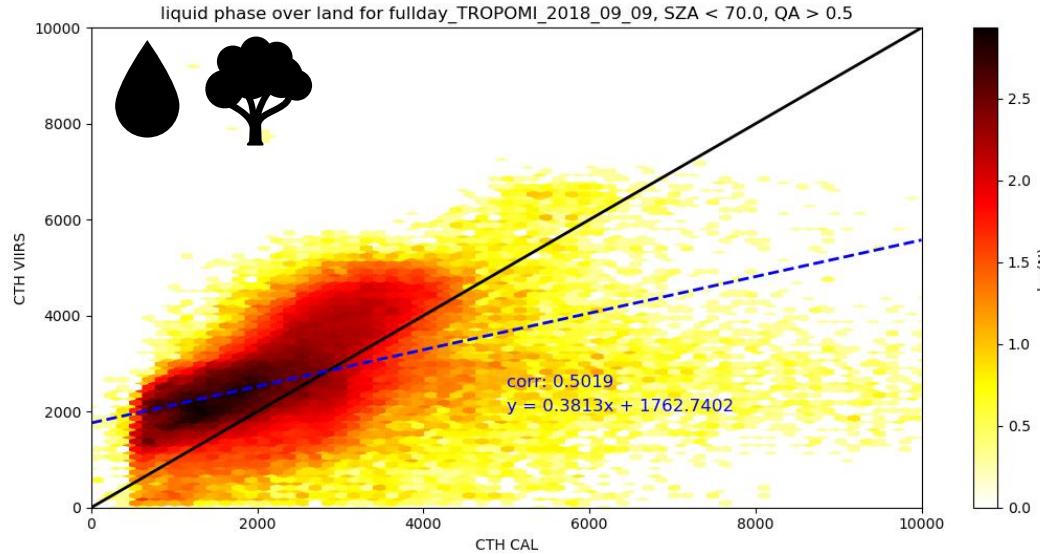
2021-04-11



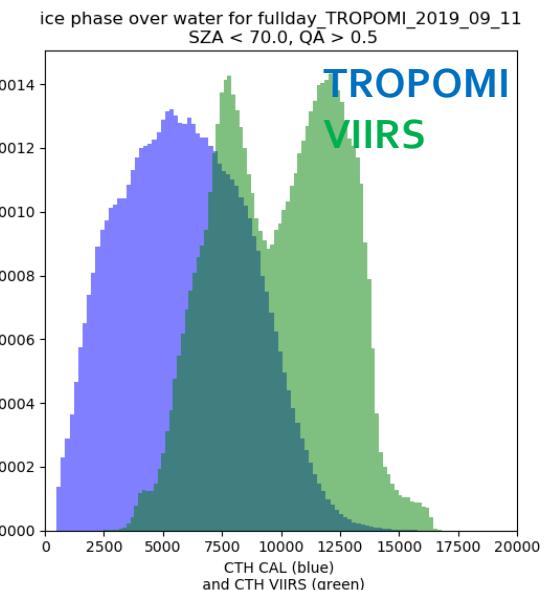
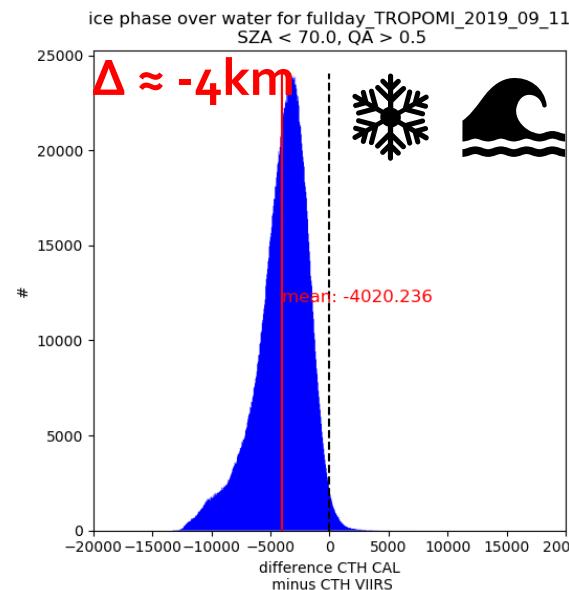
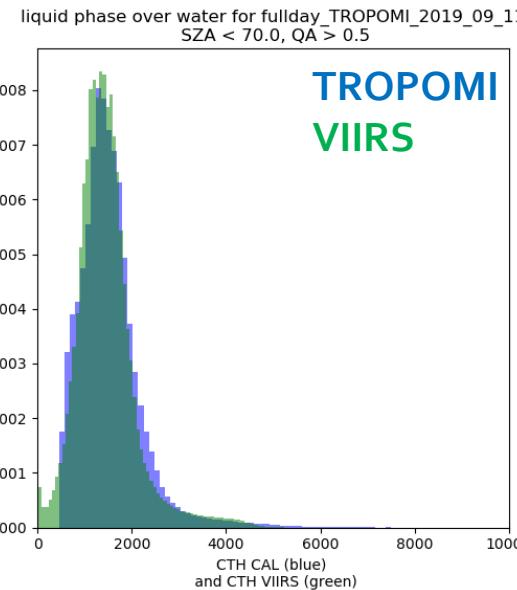
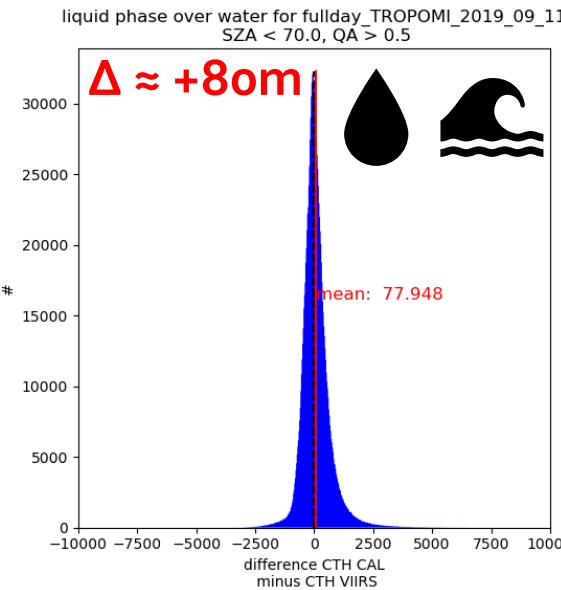
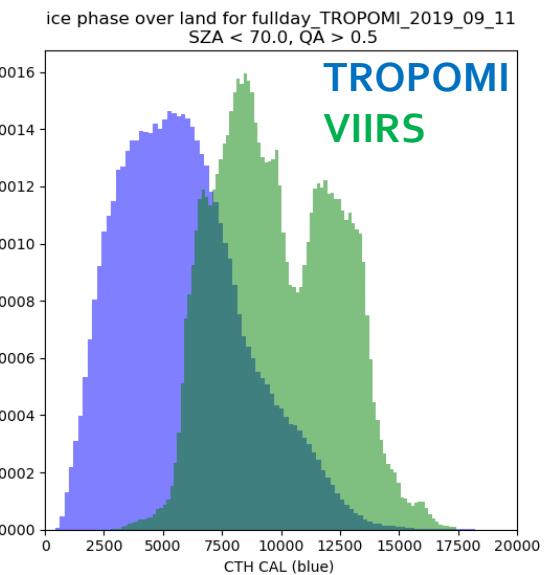
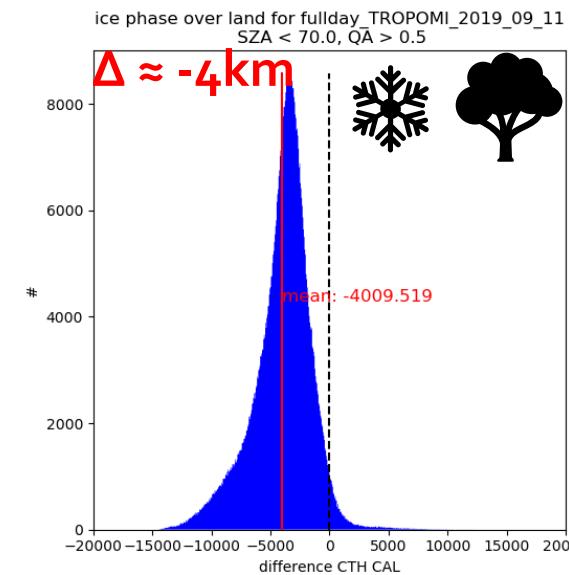
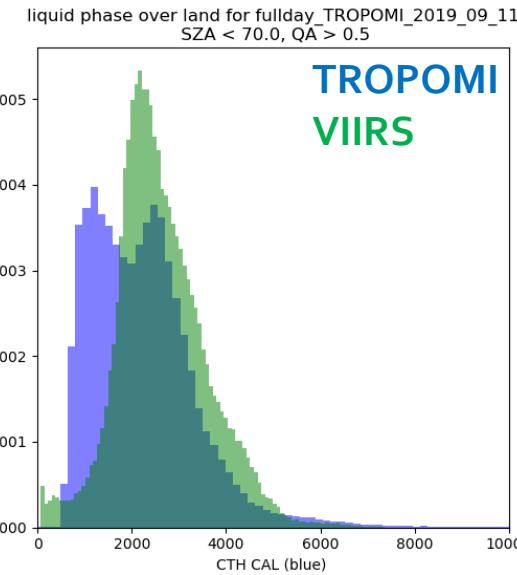
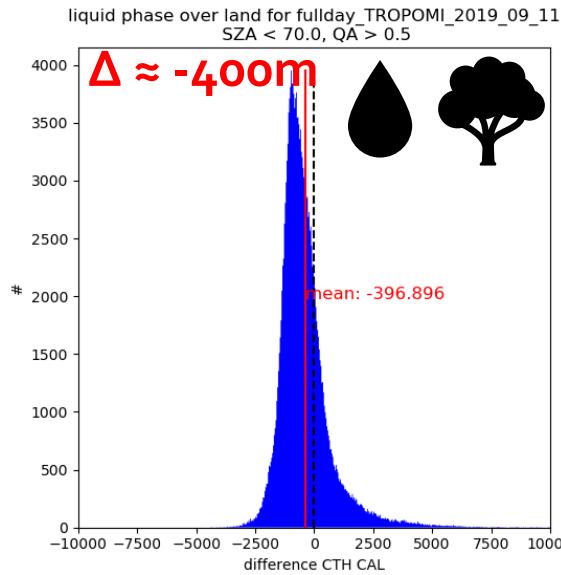
2021-09-11



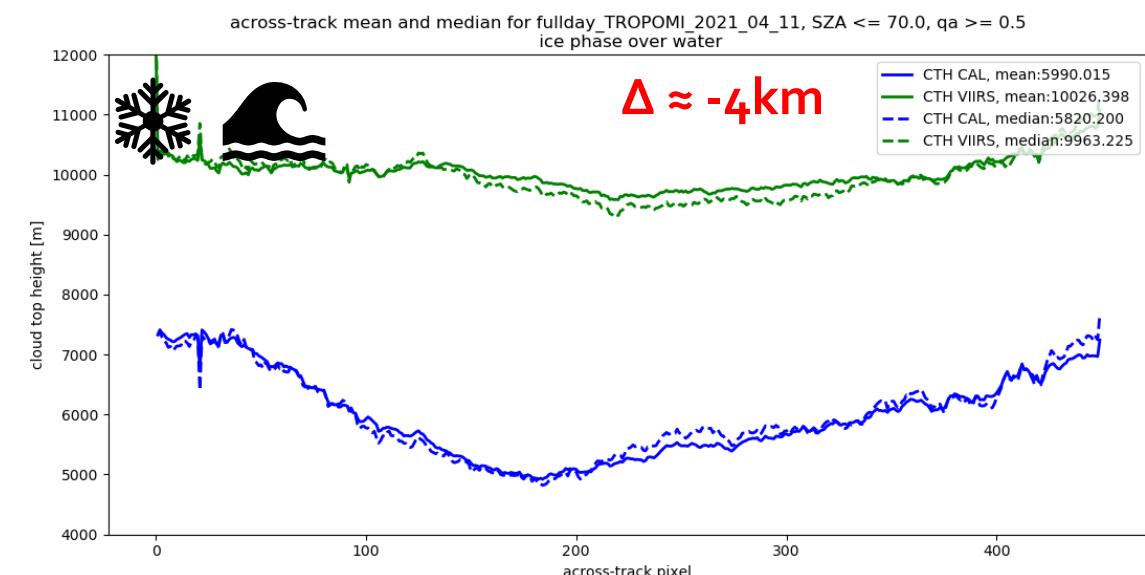
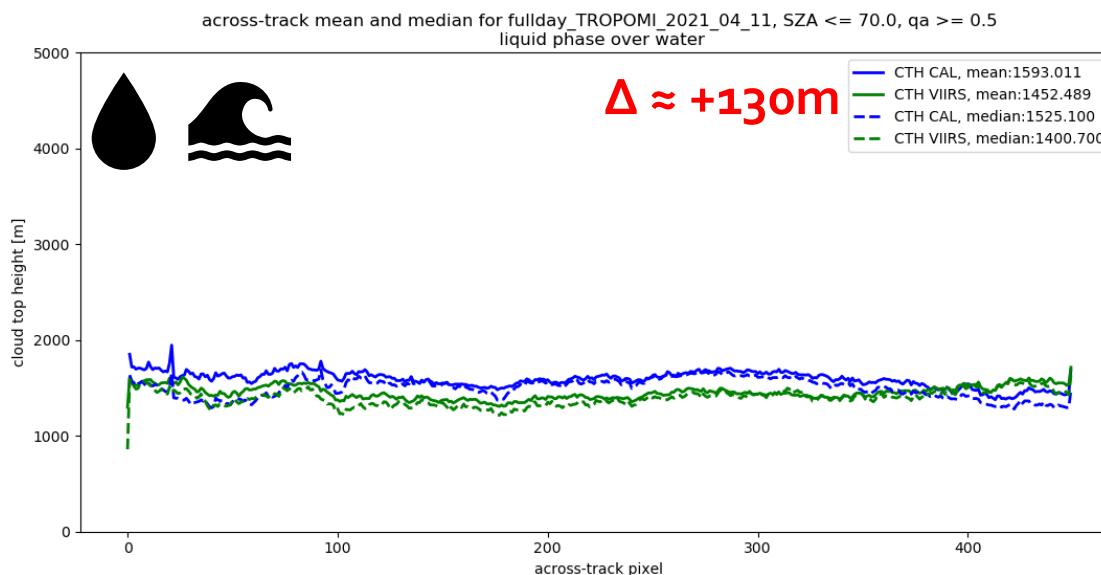
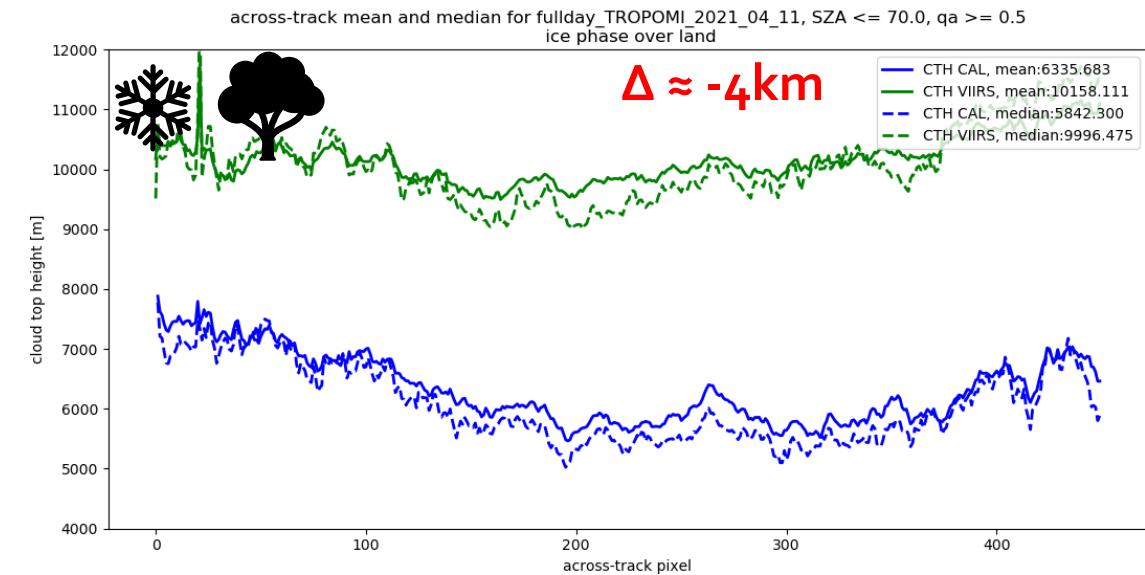
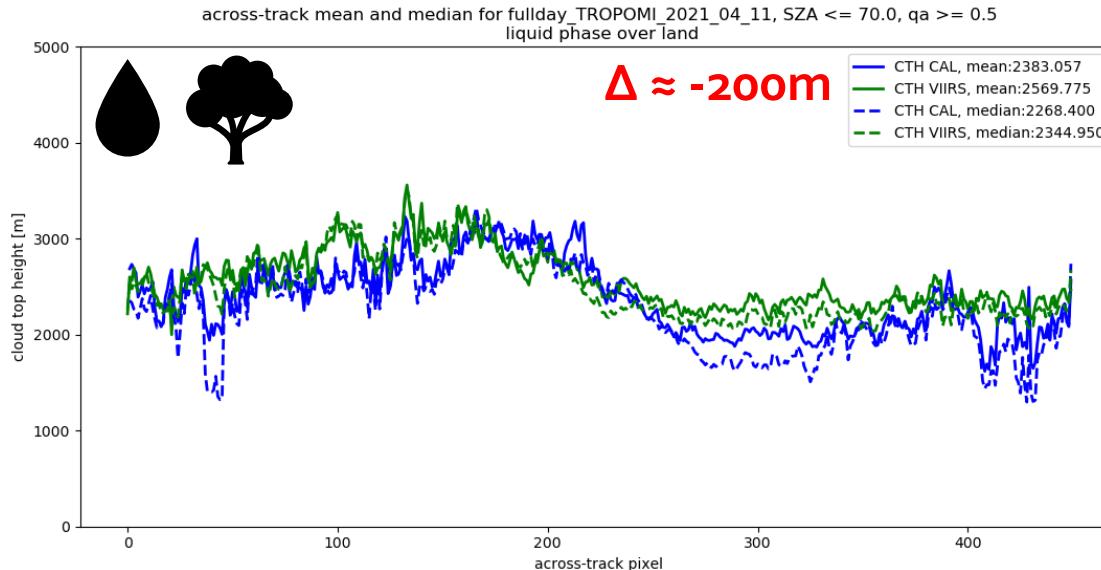
Comparison with satellite data from VIIRS/S-NPP – Global – Cloud Top Height



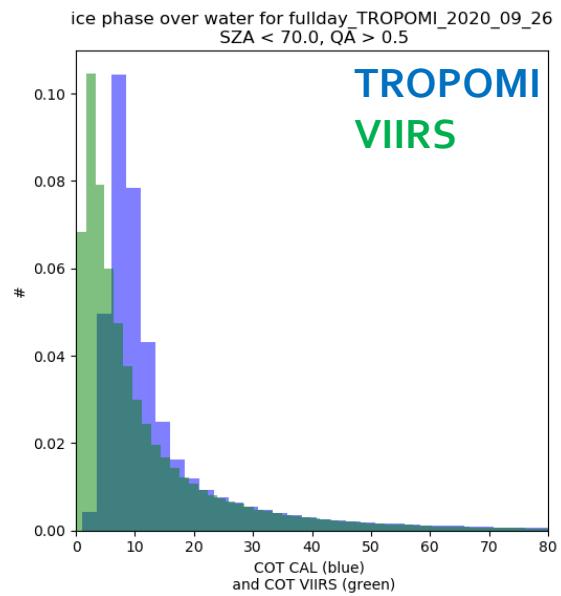
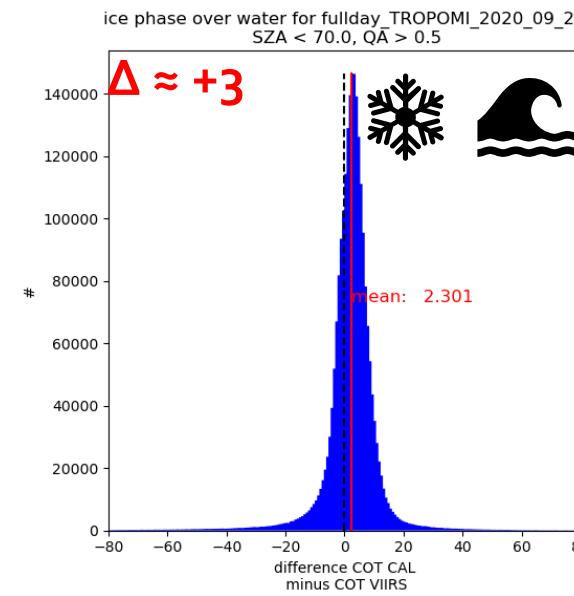
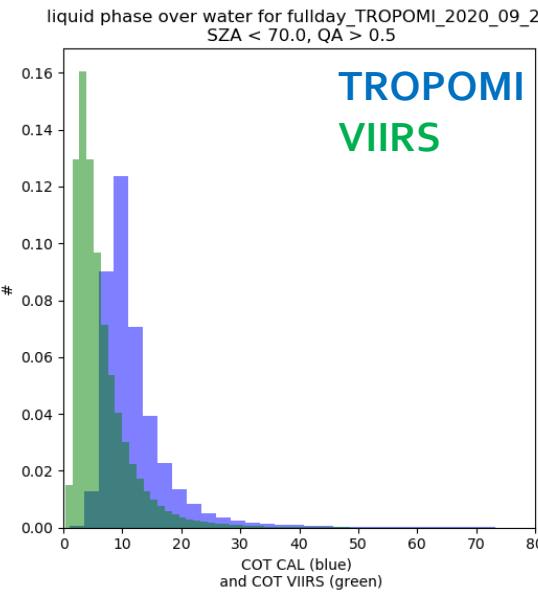
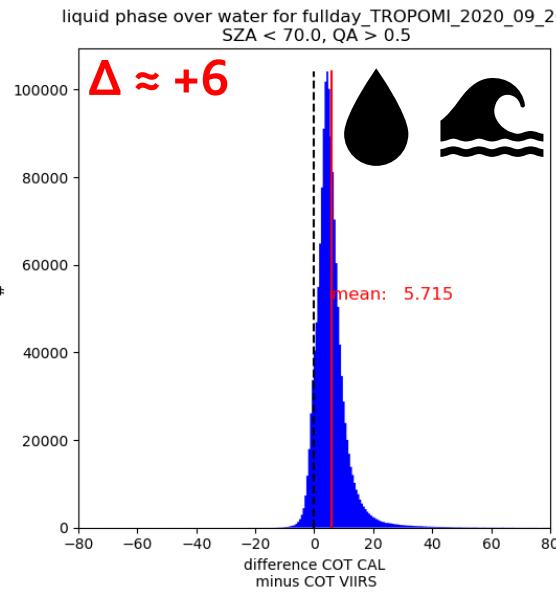
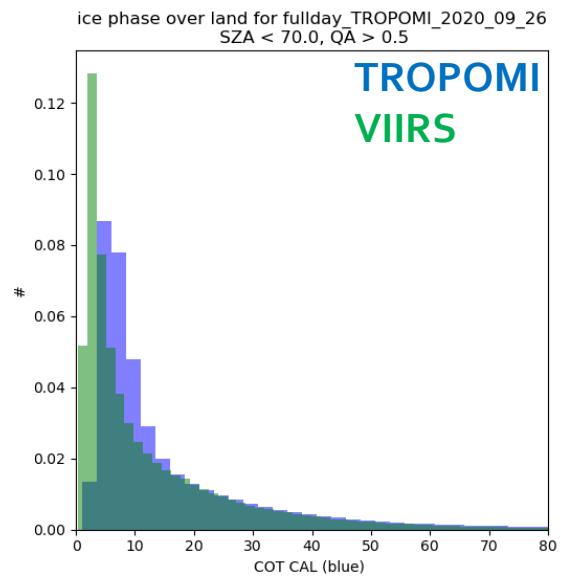
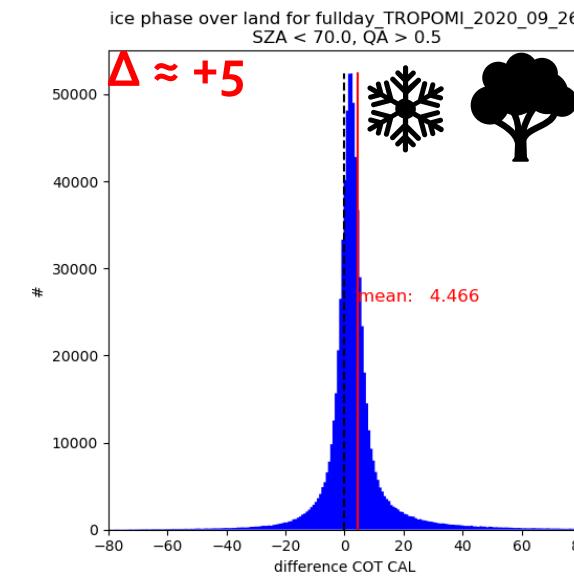
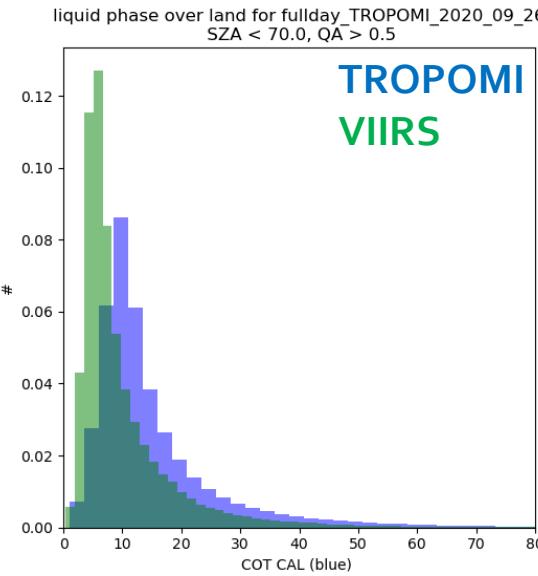
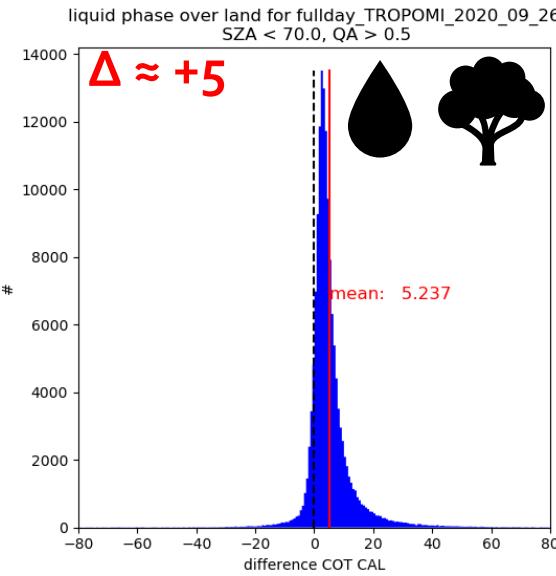
Comparison with satellite data from VIIRS/S-NPP – Global – Cloud Top Height



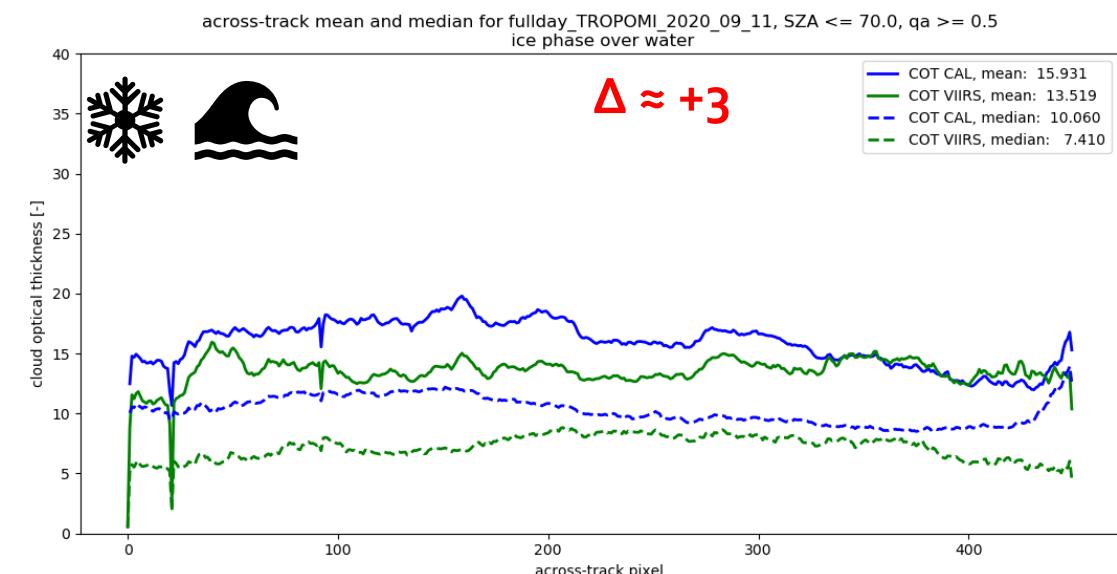
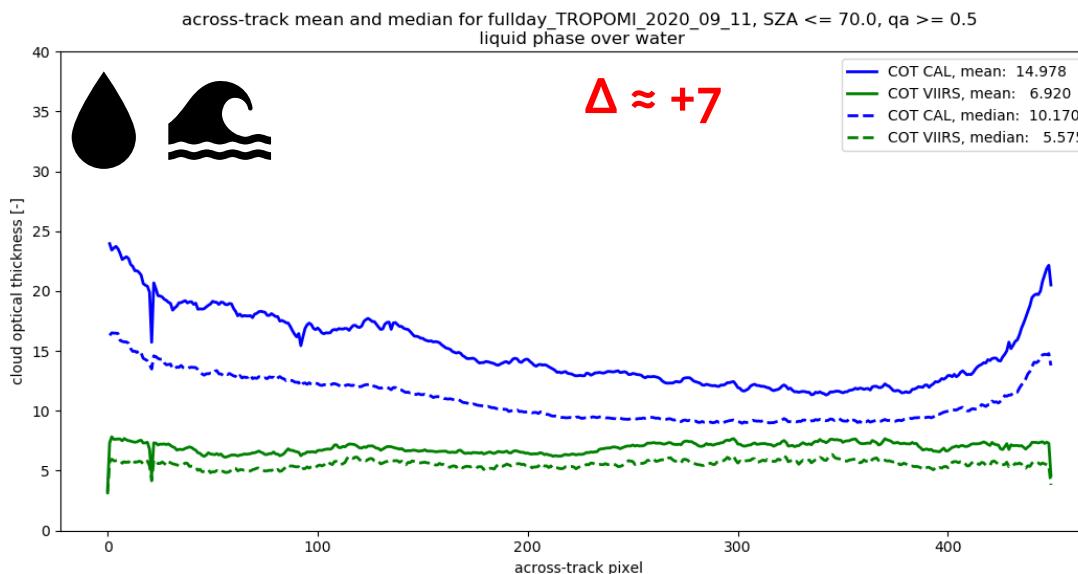
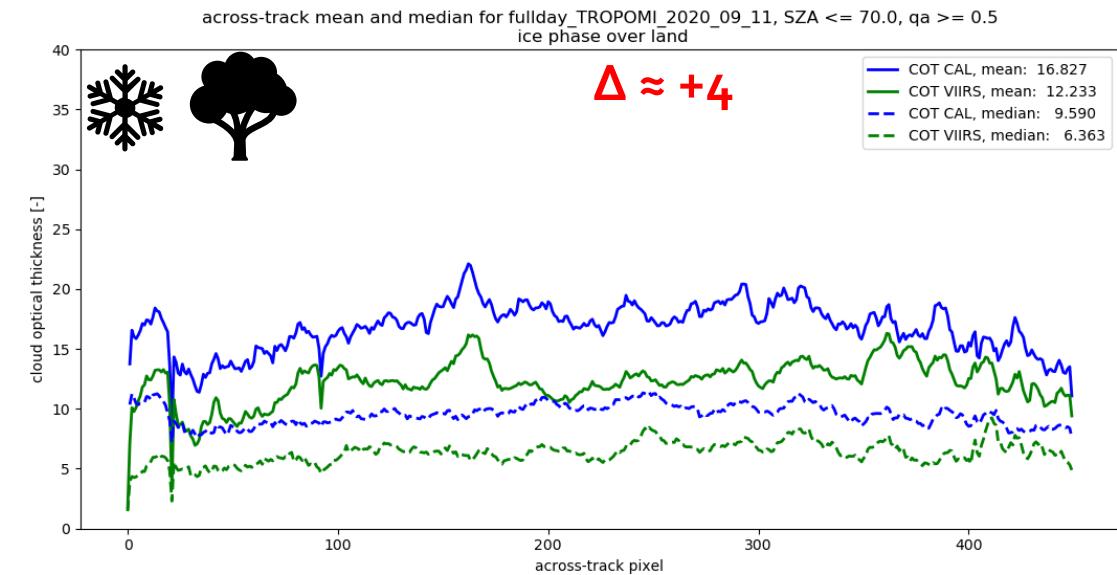
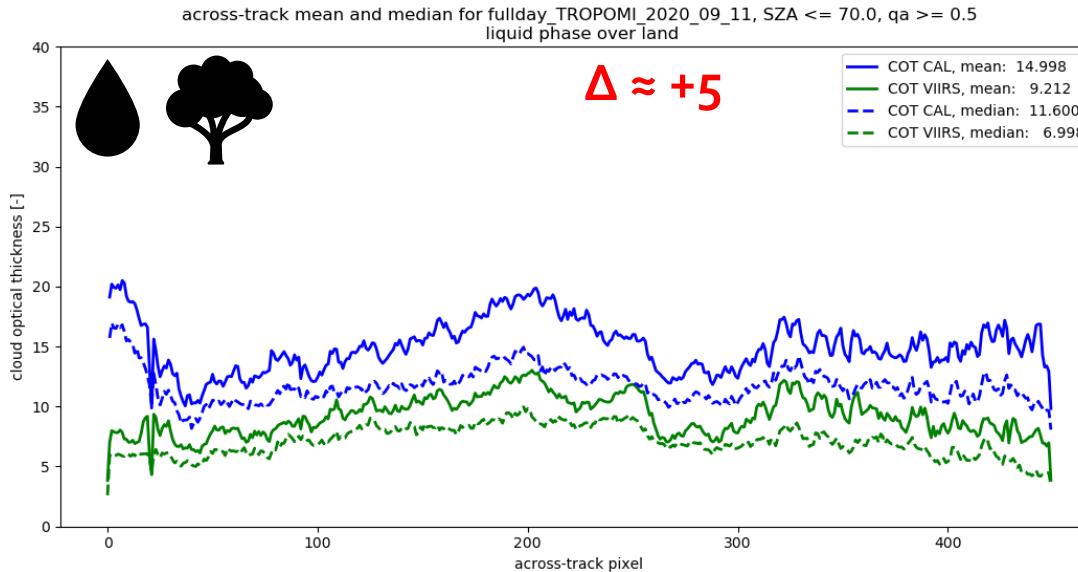
Comparison with satellite data from VIIRS/S-NPP – Global – Cloud Top Height



Comparison with satellite data from VIIRS/S-NPP – Global – Cloud Optical Thickness



Comparison with satellite data from VIIRS/S-NPP – Global – Cloud Optical Thickness



Comparison with satellite data from VIIRS/S-NPP – Cloud masking

Compare OCRA/ROCINN and VIIRS cloud fractions as tool for cloud masking:

Assumption "clear": $CF < 0.05$

Assumption "cloudy": $CF \geq 0.05$

For the global data, we find an agreement in **88%** of the cases assuming the threshold 0.05

Cloud fraction threshold 0.05	TROPOMI clear	TROPOMI cloudy
VIIRS clear	24% True Positives	5% False Negatives
VIIRS cloudy	7% False Positives	64% True Negatives

→ Cloud fractions agree well when used for cloud masking



Summary

- **Cloud top heights** agree better over water than over land for liquid clouds and in general much better for liquid phase clouds than for ice phase clouds. Mean differences TROPOMI minus VIIRS are:

	liquid ph. over land	liquid ph. over water	ice phase over land	ice phase over water
2018-09-09	-373 m	+88 m	-3420 m	-3546 m
2019-09-11	-397 m	+78 m	-4010 m	-4020 m
2020-09-11	-311 m	+92 m	-3954 m	-3874 m
2020-09-26	-1044 m	-46 m	-3755 m	-3523 m
2021-04-11	-239 m	+123 m	-3856 m	-3967 m
2021-09-11	-542 m	+45 m	-3784 m	-4048 m
Mean difference	-400 m	+80 m	-3800 m	-3830 m



Summary

- Cloud optical thickness of TROPOMI is in general larger as for VIIRS, irrespective of surface type and cloud phase.
Mean differences TROPOMI minus VIIRS are:

	liquid ph. over land	liquid ph. over water	ice phase over land	ice phase over water
2018-09-09	+5.9	+5.5	+3.7	+1.9
2019-09-11	+7.9	+5.7	+3.7	+2.3
2020-09-11	+5.3	+7.7	+4.5	+2.1
2020-09-26	+5.2	+5.7	+4.5	+2.3
2021-04-11	+4.8	+5.4	+2.3	+2.7
2021-09-11	+6.4	+5.7	+4.6	+1.9
Mean difference	+5.9	+6.0	+3.9	+2.2



Conclusion and Outlook

Conclusion

- OCRA/ROCINN is running successfully for several LEO missions in an **operational environment**
- several **features** have been **added** and evolved during the last 5 years of the S5P operational phase
- comparisons with the **VIIRS** cloud product look very **good for liquid phase** clouds
- larger **differences** appear **for ice phase** clouds due to lack of an ice cloud parameterisation in ROCINN_CAL
- usage for **cloud masking** is very consistent (88% agreement)

Outlook

- work on **ice cloud parameterisation** for ROCINN_CAL



Thank you for your attention!

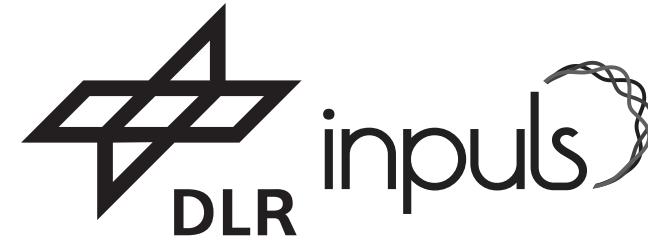
DLR-Atmos:

<https://atmos.eoc.dlr.de/calendar>

Interested in quicklooks and L3 data?

Check the INPULS project:

<https://atmos.eoc.dlr.de/inpuls/>



This work was performed with national funding