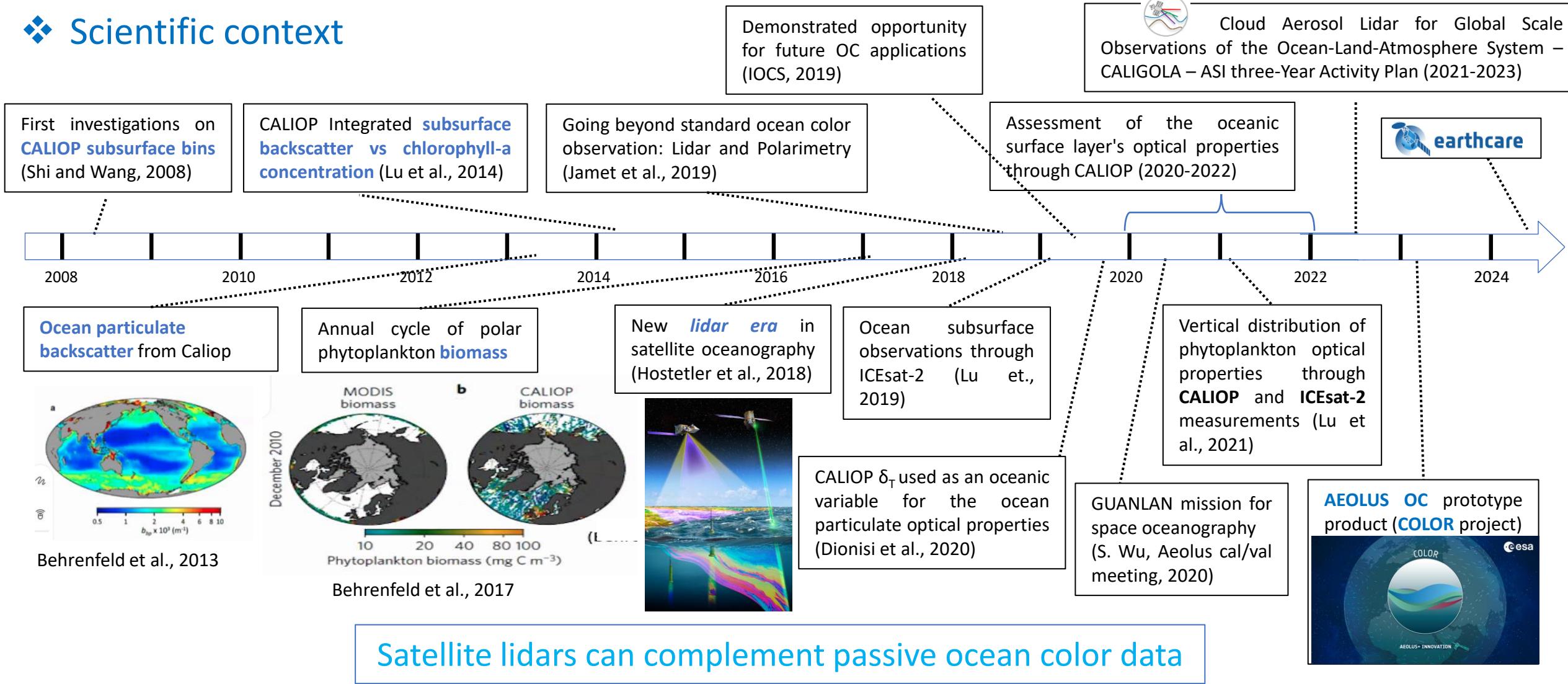


Introduction



❖ Scientific context



Introduction



❖ Scientific context

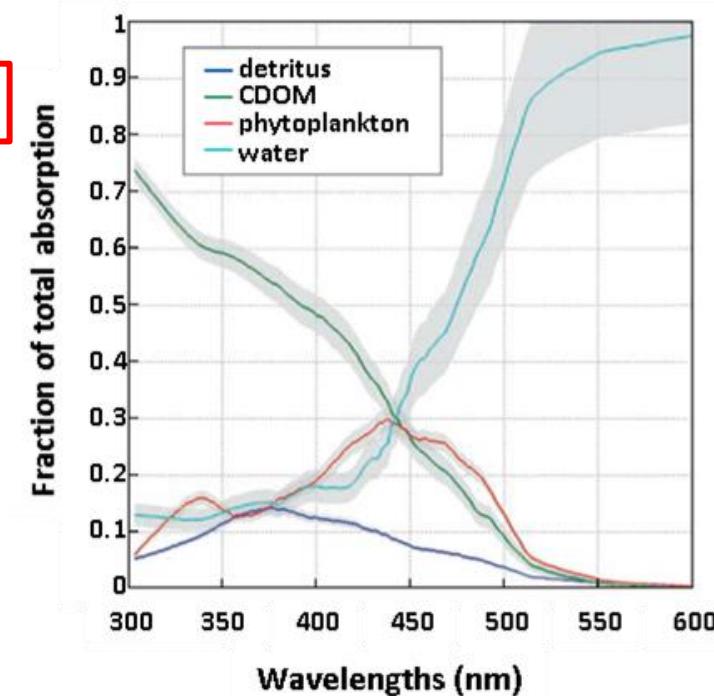
The information content in the water leaving reflectances in the ~350 to 400 nm interval is **crucial** to distinguish *dissolved organic material* from chlorophyll in the upper ocean. The downward transport of organic material is a **key process in Earth's carbon cycle** and both affects, and is affected by, climate change. Chromophoric Dissolved Organic Matter (**CDOM**) is the most relevant contributor to the light absorption at 355 nm.

Lack of the UV information of past and current Ocean Color sensors



AEOLUS gives the opportunity to investigate the signal backscattered by the ocean sub-surface:

- ❑ First orbiting HSRL lidar
- ❑ Ocean subsurface information content in the UV
- ❑ The line-of-sight (LOS) points 35° from nadir



Outline



COLOR (CDOM-proxy retrieval from aeOLus ObseRvations) was a feasibility study approved by **ESA** within the **Aeolus+ Innovation program** (ESA AO/1-9544/20/I/NS). **March 2021 - April 2023.** (ESA project responsible M.H.Rio)

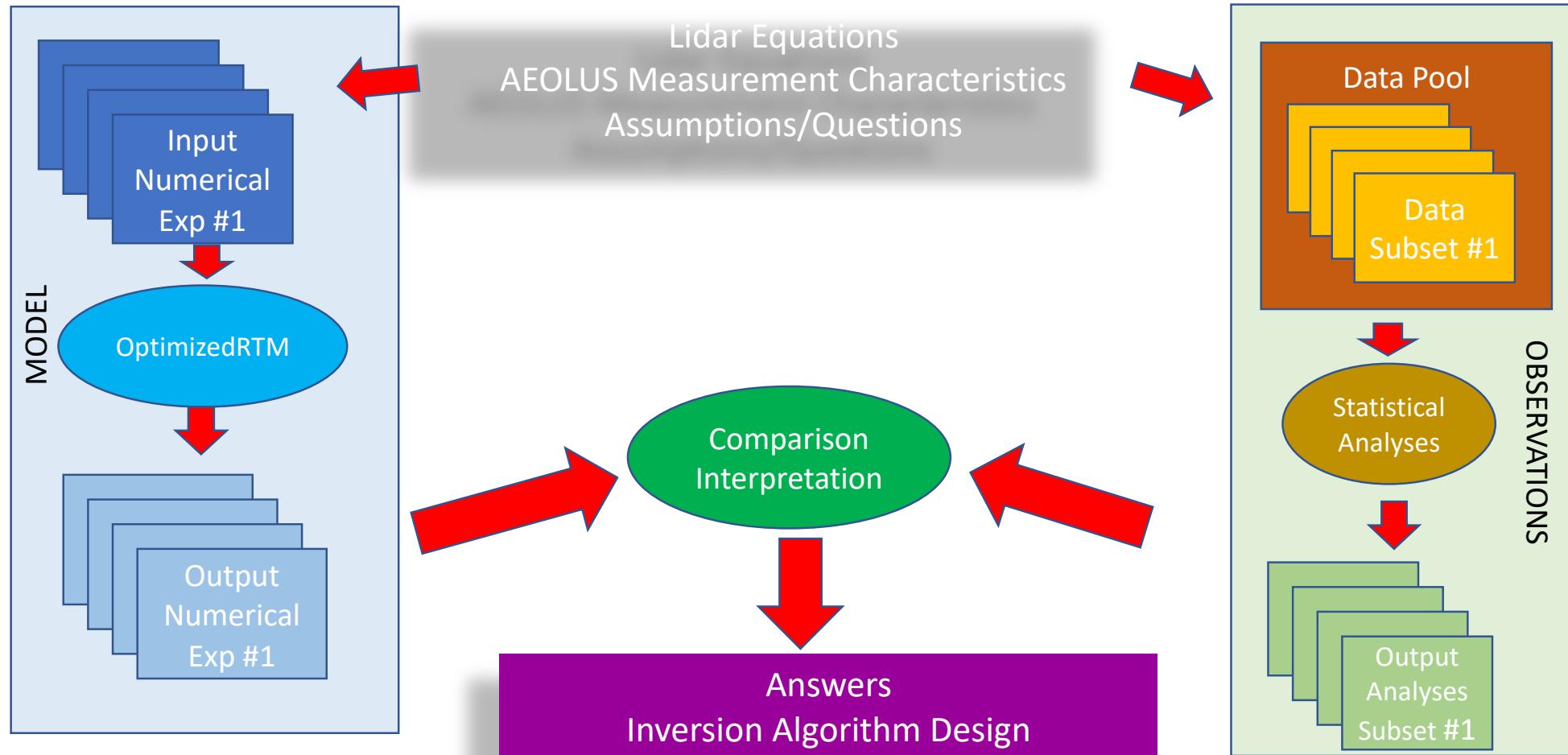
Objective: COLOR proposes to evaluate and document the **feasibility** of deriving an **in-water AEOLUS product at 355 nm**



Methods



❖ COLOR general approach



Methods

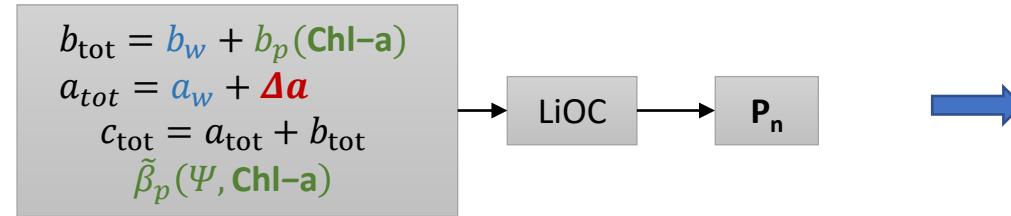


❖ LiOC in-water forward model

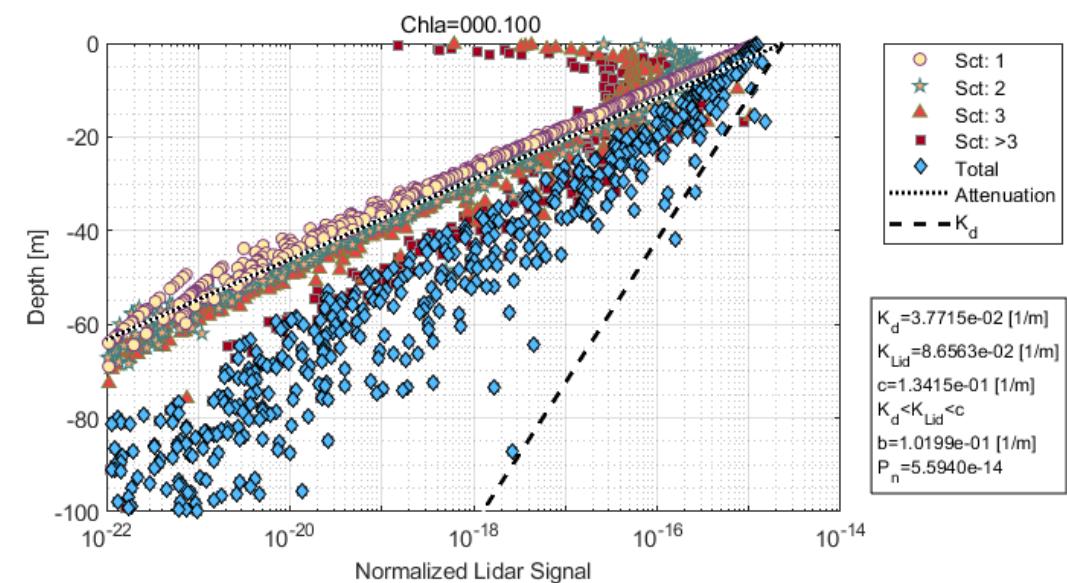
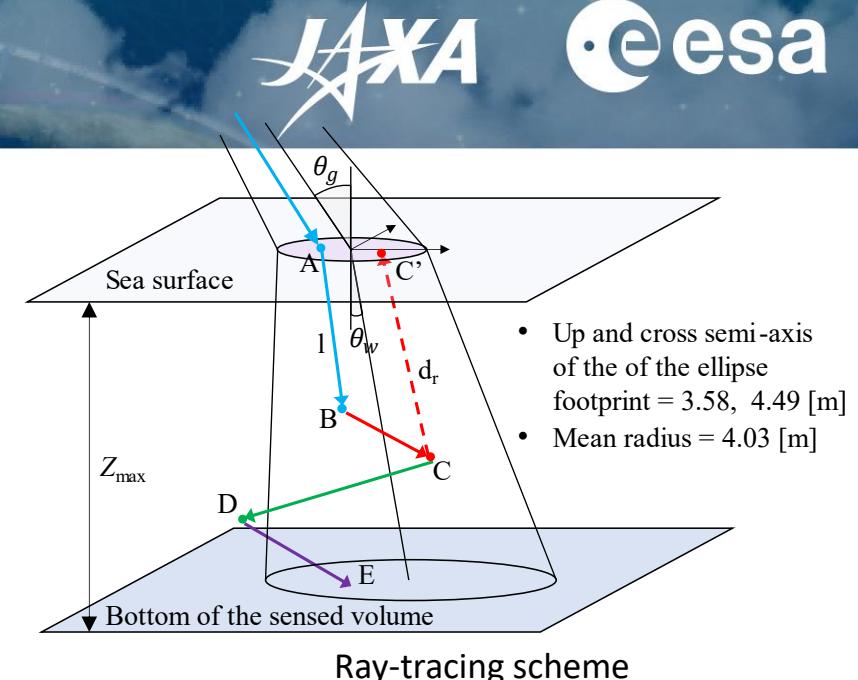
Lidar simulation code for Ocean Color applications (**LiOC**) developed fully accounting for ALADIN characteristics

$$\text{LiOC components: } P_n = P_n^s + P_n^b + P_n^w$$

- At the surface: negligible contribution of the reflected signal for wind speed up to the formation of white caps ($\sim 8 \text{ ms}^{-1}$)
- At the bottom: negligible contribution of bottom effects in oligotrophic conditions for depth $\leq 80 \text{ m}$.
- In the water columns: MC ray tracing is driven by seawater Inherent Optical Properties.



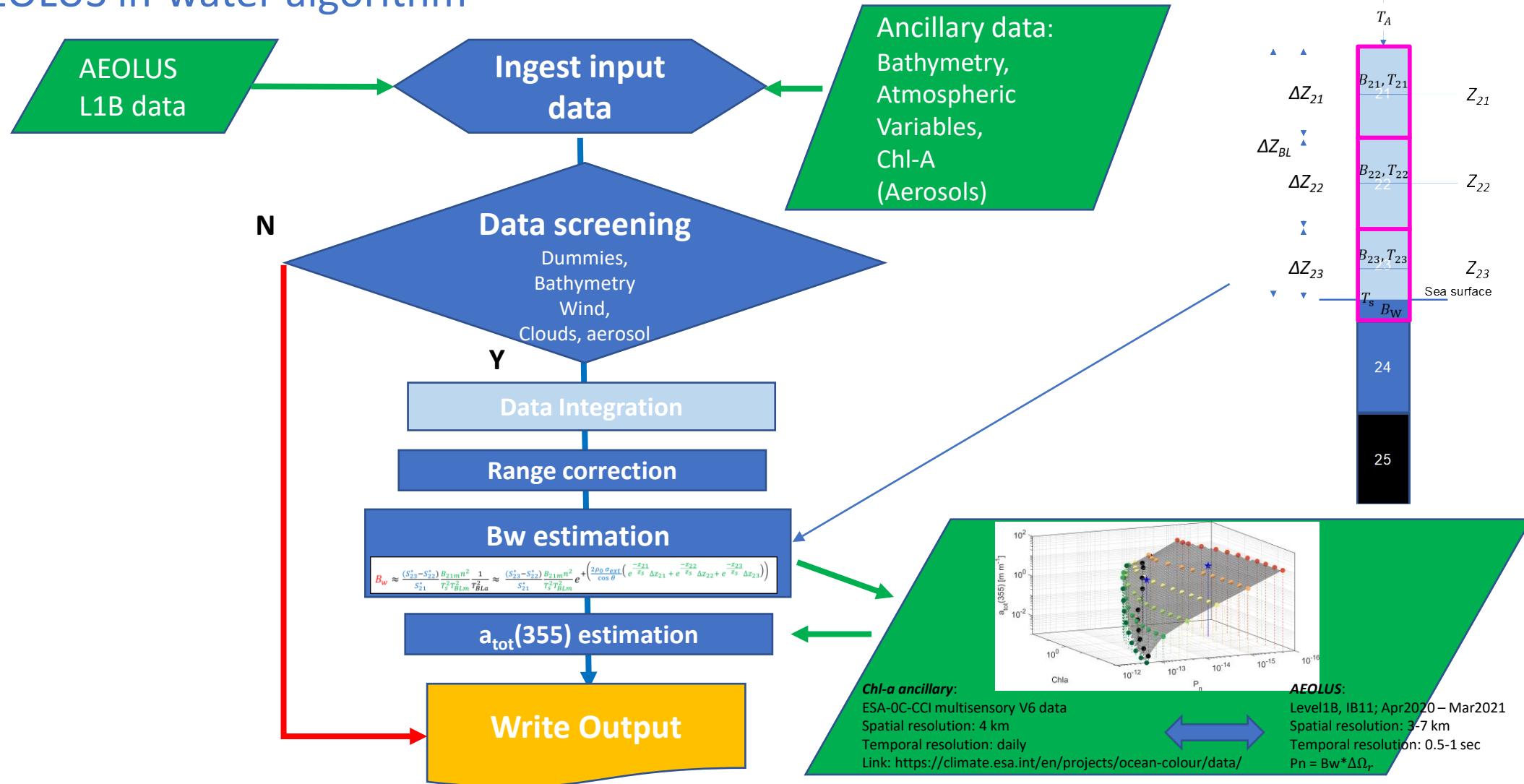
D'Alimonte et al., 2023 (submitted to Optic Express)



Methods



❖ AEOLUS in-water algorithm



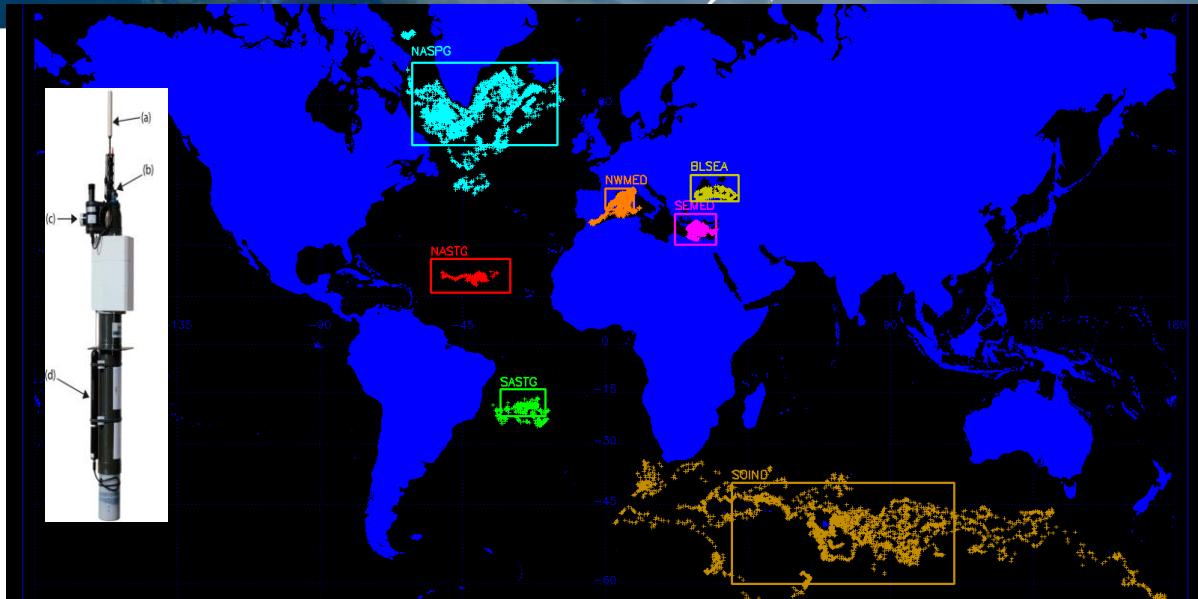
Results



❖ Algorithm Assessment

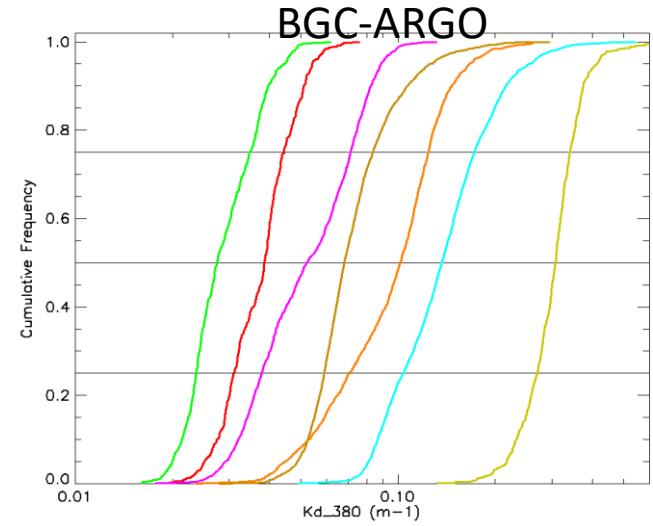
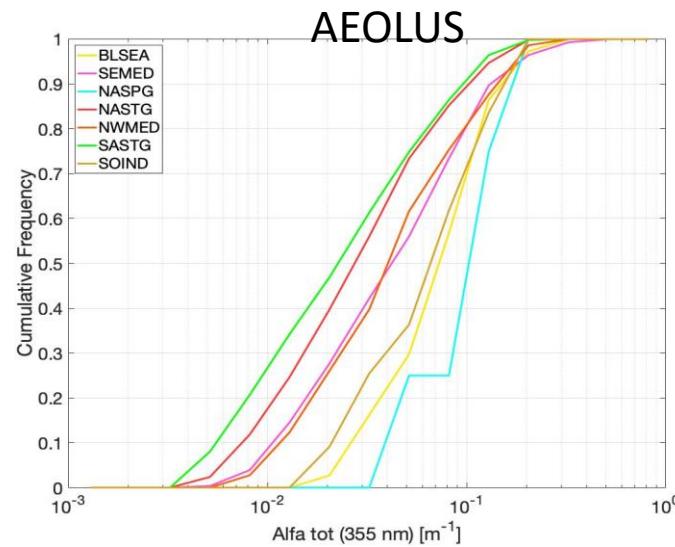
Reference datasets

- a) BGC-Argo (global scale; >40000 radiometric profiles at 4 bands available since 2012, <https://maps.biogeochemical-argo.com/bgcargo/>)
- b) ESA Ocean Colour Climate Change Initiative (ESA-OC-CCI; esa-oceancolour-cci.org)



AEOLUS L1B Dataset, Baseline 11: April 2020 - March 2021.

Region\Season	DJF	MAM	JJA	SON	ALL
NASTG	193	146	127	252	718
SASTG	212	130	140	79	561
NWMED	8	4	44	17	73
SEMED	34	40	144	64	282
NASPG	0	0	3	1	4
BLSEA	1	4	22	10	37
SOIND	24	9	3	19	55



Results



Match-up Assessment

- ESA-OC-CCI @ 412 nm scaled @ 355 nm
- Dataset: April 2020 - March 2021
- only AEOLUS data with $\Delta Bw/Bw \leq 1$

Match-up criteria

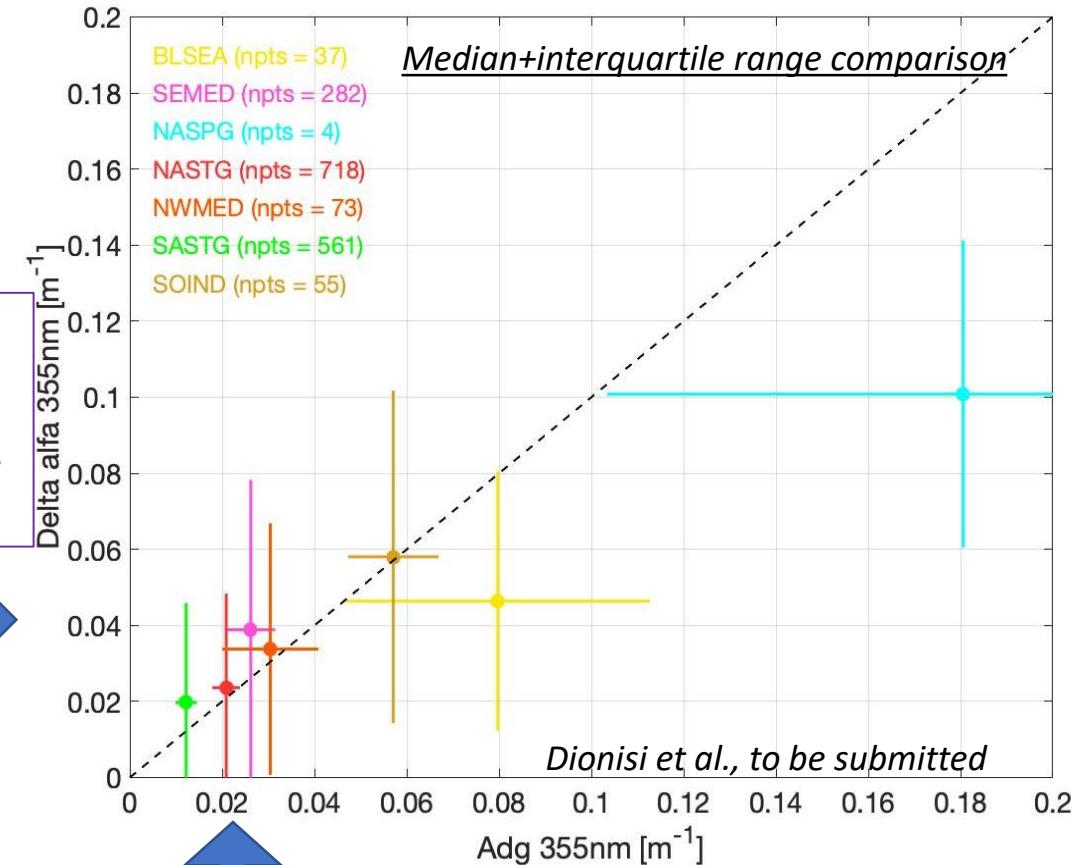
- 1) Temporal matching: ± 24 hrs
- 2) Spatial matching: 5x5 pixels (20x20 km) around the AEOLUS measurement.
- 3) Number of valid pixels: ≥ 4 out of 25

$$\Delta a(355) = a_{\text{tot}}(355) - a_w(355) - (0.052 \cdot Chl-a^{0.635})$$

$$\Delta a(355) = a_{CDOM}(355) + a_{NAP}(355)$$

$$a_{CDOM}(355) \gg a_{NAP}(355)$$

$$a_{CDOM}(355) \approx \Delta a(355)$$



AEOLUS

ESA-OC-CCI

Conclusions



- ✓ Development of a status of the art modeling tool (LIOC)
- ✓ Demonstrated sensitivity of the AEOLUS measurements to marine optical properties
- ✓ AEOLUS OC prototype product in a spectral region (355 nm) not covered by operational OC products
- ✓ Overall demonstrated agreement between reference measurements and the proposed OC product

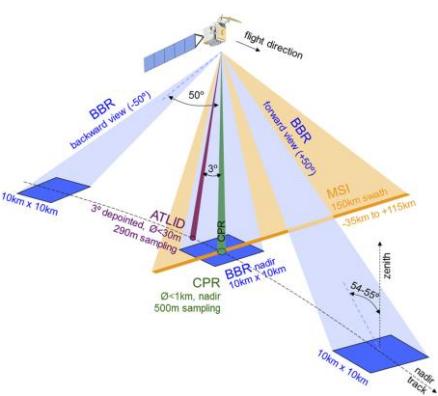
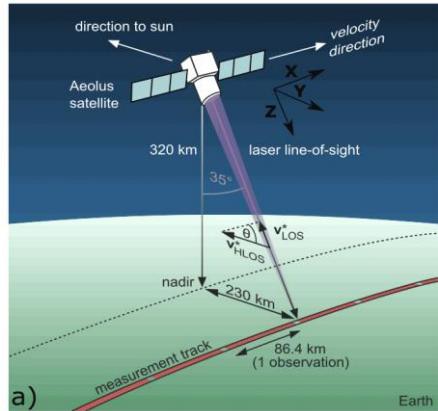
- ✗ Atmospheric disturbances (cloud and aerosol contamination) not properly accounted for
- ✗ Low SNR in the cloud free ground bin signal
- ✗ Limited spatial and temporal coverage
- ✗ HSRL not exploited (single channel (Mie) retrieval)
- ✗ In-water profiling capability not available

Roadmap



Applicability of the COLOR results to EarthCARE mission

Main differences between AEOLUS and ATLID for OC application:



	ALADIN	ATLID	
<input type="checkbox"/> Vertical resolution:	500 m	100 m	Better separation of the atmospheric signal in the ground bin return (e.g. optimization of cloud and aerosols identification)
<input type="checkbox"/> Laser emitting angle:	35°	3°	Stronger surface return and signal propagation
<input type="checkbox"/> Acquisition channels:	-Co-polar Rayleigh A -Co-polar Rayleigh B -Co-polar Mie	-Co-polar Rayleigh -Co-polar Mie -Total cross polar	Optical characterization of the ocean particles through polarization capability
<input type="checkbox"/> Instruments on platform:	-	-Cloud Profiling Radar -Multi-Spectral Imager -Broad-Band Radiometer	Improvement of scene characterization (e.g. cloud detection)
<input type="checkbox"/> Local solar time (LST) sampling:	dawn/dusk	day/night	Large variability of the background signal. Marine diurnal cycle. OC information during nighttime. LST passage closer to OC satellite missions



Applicability of the COLOR results to EarthCARE mission

Actions to exploit COLOR's heritage for OC studies using EarthCARE

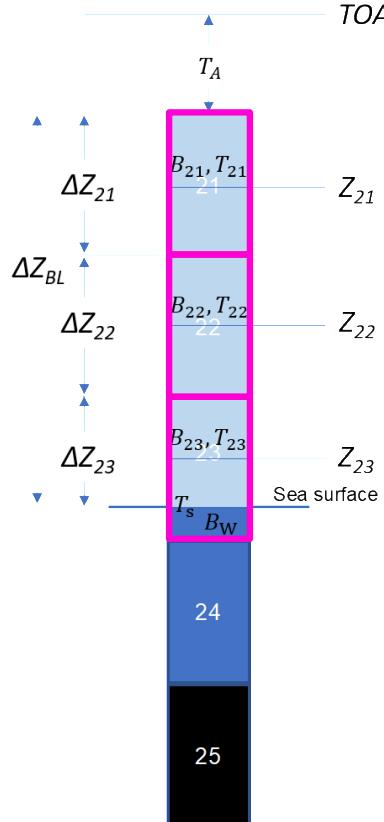
- Data analysis procedure
- LiOC radiative transfer tool
- Improved characterization of atmospheric (aerosols and clouds) disturbances
- Exploitation of High Spectral Resolution Lidar (HSRL) capabilities
- Exploitation of Polarization capabilities
- Possibility to implement Synergetic Inversion algorithm including, as input, active and passive measurements (OC missions).



Methods

❖ AEOLUS in-water algorithm

Elastic Backscatter Lidar AEOLUS-adapted inversion algorithm



Rationale: use the information in bins 21 and 22 to account for the instrumental and atmospheric contribution in the bin 23 signal

INPUTS: (Mie channel) Range Corrected Signals (S_{xx}^*) and geometry of bins 21, 22, 23 ($z_{xx}, \Delta z_{xx}$)

ANCILLARY: Atmospheric density profile, surface wind (T_s^2), sea temperature and salinity, aerosols scale height (z_s) .

OUTPUT: sea water contribution (backscattering+extinction) to ground bin signal (B_w)

$$B_{wat} \approx \frac{(S_{23}^* - S_{22}^*)}{S_{21}^*} \frac{B_{21m} n^2}{T_s^2 T_{BLm}^2 T_{BLa}^2} \frac{1}{e^{(\frac{2\rho_0 \sigma_{ext}}{\cos \theta}) (\frac{-z_{21}}{z_s} \Delta z_{21} + \frac{-z_{22}}{z_s} \Delta z_{22} + \frac{-z_{23}}{z_s} \Delta z_{23})}}$$

ASSUMPTIONS:

- Contributions of **sea surface backscattering** and of **sea bottom reflection** are **negligible**
- Sea surface transmittance $T_s = 0.97$, independent from the direction of propagation
- Refractive index of sea water $n=1.356$ independent from salinity and temperature
- **Difference between atmospheric backscattering contribution of bin 22 and 23 is negligible** compared to the contribution of **sea water in bin 23**
- Atmospheric backscattering dominated by molecular contribution both for the optical thickness and for the shape of the phase function
- **Homogeneity of the aerosol type** in the Marine Atmospheric Boundary Layer (MABL) and **known vertical distribution**

Results



Aequira
serco



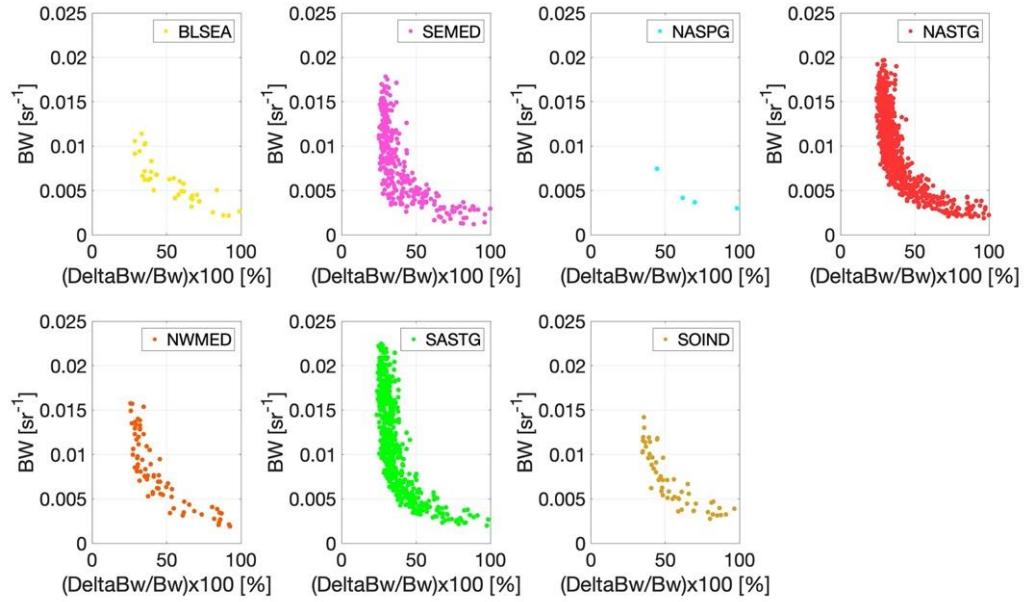
COLOR
CDOM-proxy retrieval from aeOLus ObseRvations

Estimation of associated uncertainty

Identified sources of uncertainties:

- *Data homogeneity*
- *Radiometric noise*
- *Cloud contamination*
- *Assumptions in the analytical model*
- *Aerosols*
- $B_w \rightarrow \alpha$ conversion

$$\Delta B_{wat}(355) = \sqrt{\left(\frac{\partial B_w}{dS_{21}^*}\right)^2 \cdot (\Delta S_{21}^*)^2 + \left(\frac{\partial B_w}{dS_{22}^*}\right)^2 \cdot (\Delta S_{22}^*)^2 + \left(\frac{\partial B_w}{dS_{23}^*}\right)^2 \cdot (\Delta S_{23}^*)^2}$$

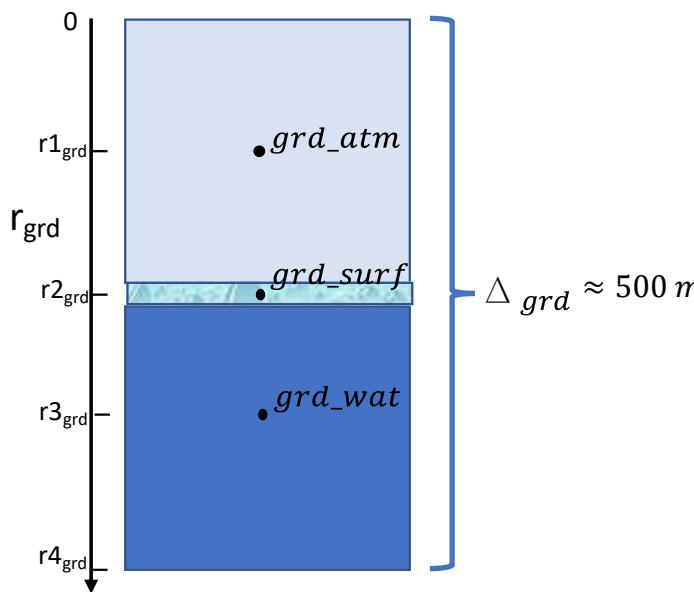


Associated uncertainty to the prototype product is based on the effect of radiometric noise recognized as major (and quantitatively documented) source of uncertainty.

A robust quantitative and detailed validation-based estimation of uncertainties of the AEOLUS OC product is not possible due to the small dimension of the comparison dataset.

❖ General approach: ground bin characterization

The potential information on ocean subsurface optical properties is contained in the AEOLUS ground bin volume (Δr_{grd})



$$S_X(\text{grd}) = M_X \left[\frac{A}{\left(r_{\text{atm}} + \frac{\Delta r_{\text{atm}}}{n} \right)^2} \right] B_{\text{grd}} T_A^2(r_{\text{atm}}) + S_{\text{bkd}} \quad (1)$$

$X = \text{Ray}_{\text{A,B}}$
 $X = \text{Mie}$

$$B_{\text{grd}} = B_{\text{atm}} + B_{\text{srf}} + B_{\text{wat}}(K_L, \beta_{\text{wat}}^{\text{par}}, \beta_{\text{wat}}^{\text{mol}}) \quad (2)$$

$$B_{\text{wat}} = \int_0^{r_{\text{wat}}} \beta_{\text{wat}}(\pi, r'_{\text{wat}}) \exp \left[-2 \int_0^{r''_{\text{wat}}} K_{\text{LID}}(r'''_{\text{wat}}) dr'''_{\text{wat}} \right] dr'_{\text{wat}} \quad (3)$$

This characterization is based on:

- a) Radiative transfer numerical modelling
- b) AEOLUS data analysis

Methods

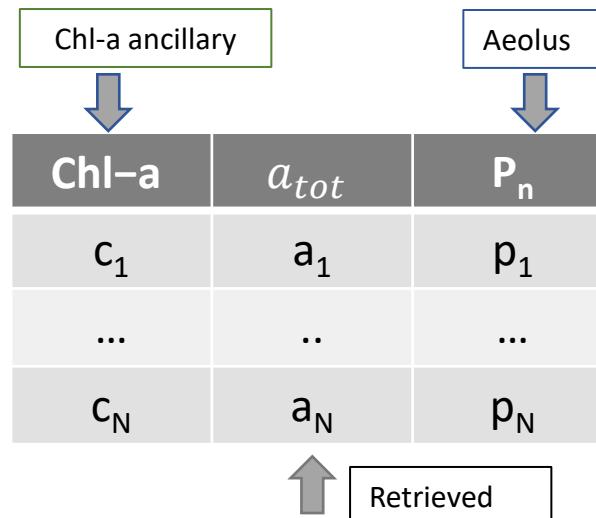
❖ LiOC in-water forward model

Overview of the backward scheme for a_{tot} retrieval

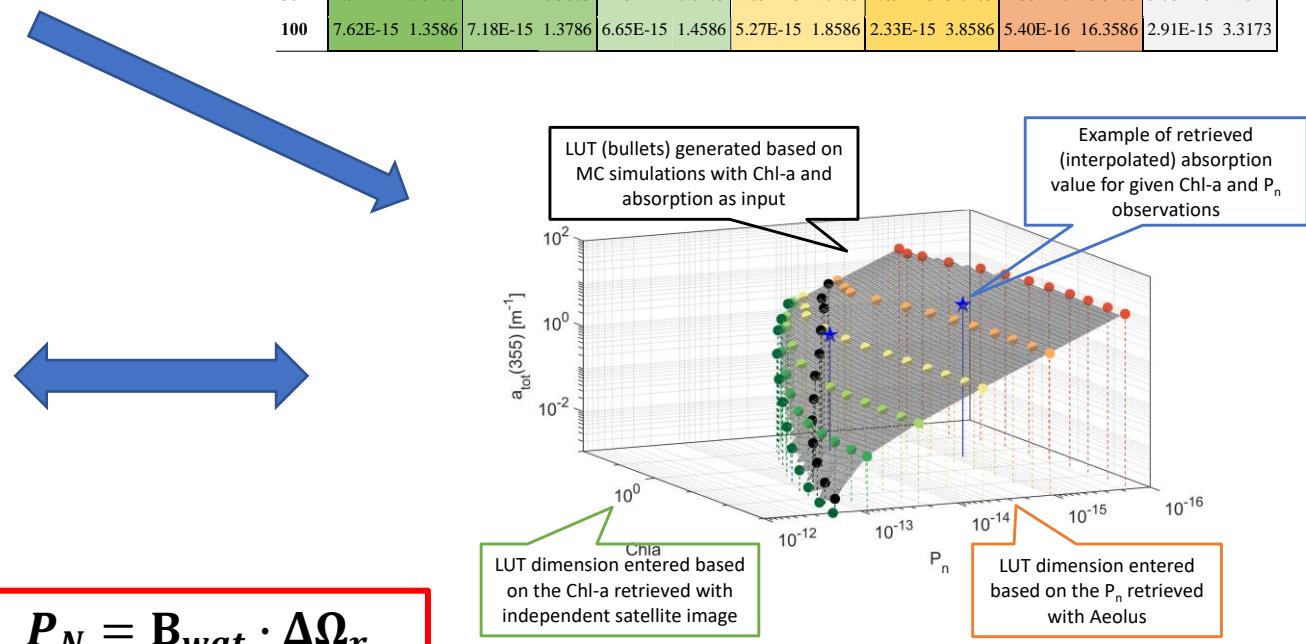
1. LUT computed through forward MC simulations to determine P_n as a function of IOPs.

2. The LUT entered through the observed Chl-a and P_n values

3. The a_{tot} value retrieved by interpolation



Chl-a	Δa log-uniformly varied between 0 and 15 m^{-1}						Ref. case							
	P_n	a1	P_n	a2	P_n	a3	P_n	a4	P_n	a5	P_n	a6	P_n	atot
0.001	1.92E-13	0.0012	8.48E-14	0.0212	2.49E-14	0.1012	5.39E-15	0.5012	1.09E-15	2.5012	1.82E-16	15.0012	1.83E-13	0.0025
0.003	1.75E-13	0.0014	8.19E-14	0.0214	2.49E-14	0.1014	5.43E-15	0.5014	1.10E-15	2.5014	1.83E-16	15.0014	1.54E-13	0.0041
0.01	1.46E-13	0.0021	7.73E-14	0.0221	2.49E-14	0.1021	5.49E-15	0.5021	1.11E-15	2.5021	1.86E-16	15.0021	1.18E-13	0.0078
0.03	1.20E-13	0.0037	6.98E-14	0.0237	2.48E-14	0.1037	5.62E-15	0.5037	1.14E-15	2.5037	1.91E-16	15.0037	8.62E-14	0.015
0.1	9.10E-14	0.0078	6.17E-14	0.0278	2.47E-14	0.1078	5.87E-15	0.5078	1.19E-15	2.5078	2.00E-16	15.0078	5.61E-14	0.0322
0.3	6.84E-14	0.0168	5.16E-14	0.0368	2.40E-14	0.1168	6.10E-15	0.5168	1.27E-15	2.5168	2.14E-16	15.0168	3.60E-14	0.0658
1	4.82E-14	0.0408	3.98E-14	0.0608	2.21E-14	0.1408	6.71E-15	0.5408	1.42E-15	2.5408	2.41E-16	15.0408	2.23E-14	0.146
3	3.49E-14	0.0934	2.96E-14	0.1134	2.04E-14	0.1934	7.11E-15	0.5934	1.68E-15	2.5934	2.87E-16	15.0934	1.33E-14	0.3047
10	2.33E-14	0.2334	2.12E-14	0.2534	1.61E-14	0.3334	7.70E-15	0.7334	2.19E-15	2.7334	3.90E-16	15.2334	8.19E-15	0.6873
30	1.51E-14	0.5405	1.42E-14	0.5605	1.23E-14	0.6405	7.65E-15	1.0405	2.69E-15	3.0405	4.88E-16	15.5405	5.08E-15	1.4524
100	7.62E-15	1.3586	7.18E-15	1.3786	6.65E-15	1.4586	5.27E-15	1.8586	2.33E-15	3.8586	5.40E-16	16.3586	2.91E-15	3.3173



Methods



❖ AEOLUS in-water algorithm

High Spectral Resolution Lidar approach

Objective: coupling the signals coming from Brillouin and Mie spectra (Rayleigh+Mie channels)

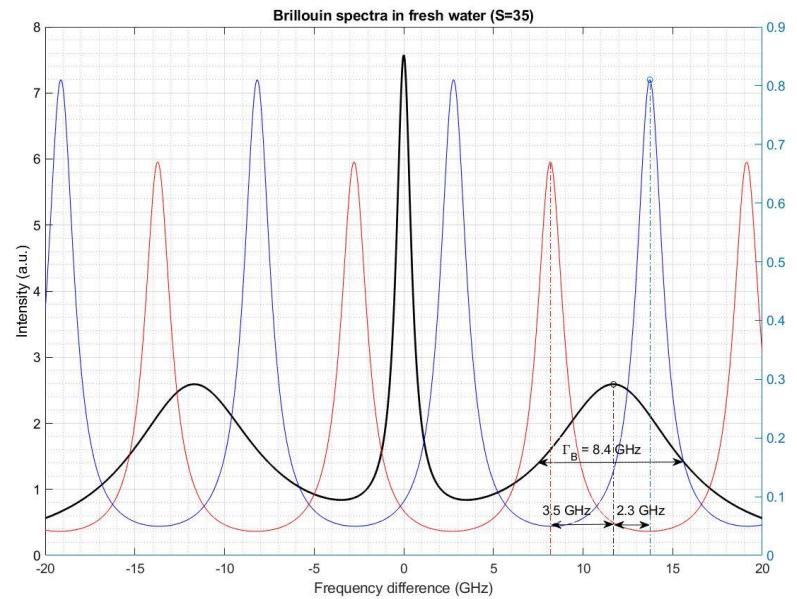
HSRL in water

$$S_{Mie} = M_{Mie}^w \left[\frac{A}{\left(r_{atm} + \frac{\Delta r_{atm}}{n} \right)^2} \right] (C_4^w \beta_{wat}^m + C_3^w \beta_{wat}^p) \exp \left[-2 \int_0^{r_{wat}} K_{LID}(r'_{wat}) dr'_{wat} \right] T_A^2(r_{atm})$$

$$S_{Ray} = M_{Ray}^w \left[\frac{A}{\left(r_{atm} + \frac{\Delta r_{atm}}{n} \right)^2} \right] (C_1^w \beta_{wat}^m + C_2^w \beta_{wat}^p) \exp \left[-2 \int_0^{r_{wat}} K_{LID}(r'_{wat}) dr'_{wat} \right] T_A^2(r_{atm})$$

$$\beta_{wat}^p = \beta_{wat}^m \left[\frac{S_R M_{Mie}^w C_4^w - M_{Ray}^w C_1^w}{M_{Ray}^w C_2^w - S_R M_{Mie}^w C_3^w} \right]$$

- Calibration and cross talk coefficients estimated for atmospheric application **cannot be used for the Brillouin scattering in water**
- **High variability** of the Rayleigh ground bin signal



FWHM	1,78 GHz
FSR	10,95 GHz
Spacing between A and B	5,5 GHz
Filter A Peak Transmission	81 %
Filter B Peak Transmission	67 %