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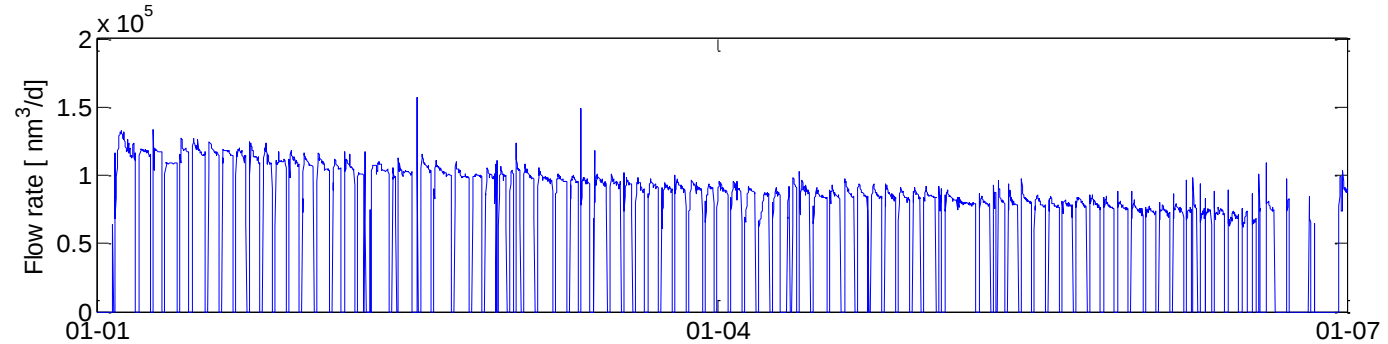
Deep Learning History Matching for Real Time Production Forecasting

K. Loh, P. Shoeibi Omrani, R. van der Linden (TNO, The Netherlands)



› Mature assets production issues

- › e.g. liquid loading, scaling
- › Reliable prediction of production rates



› Availability of more and more data

- › Development of cost effective sensors
- › Mature asset = Lots of historical data in different formats



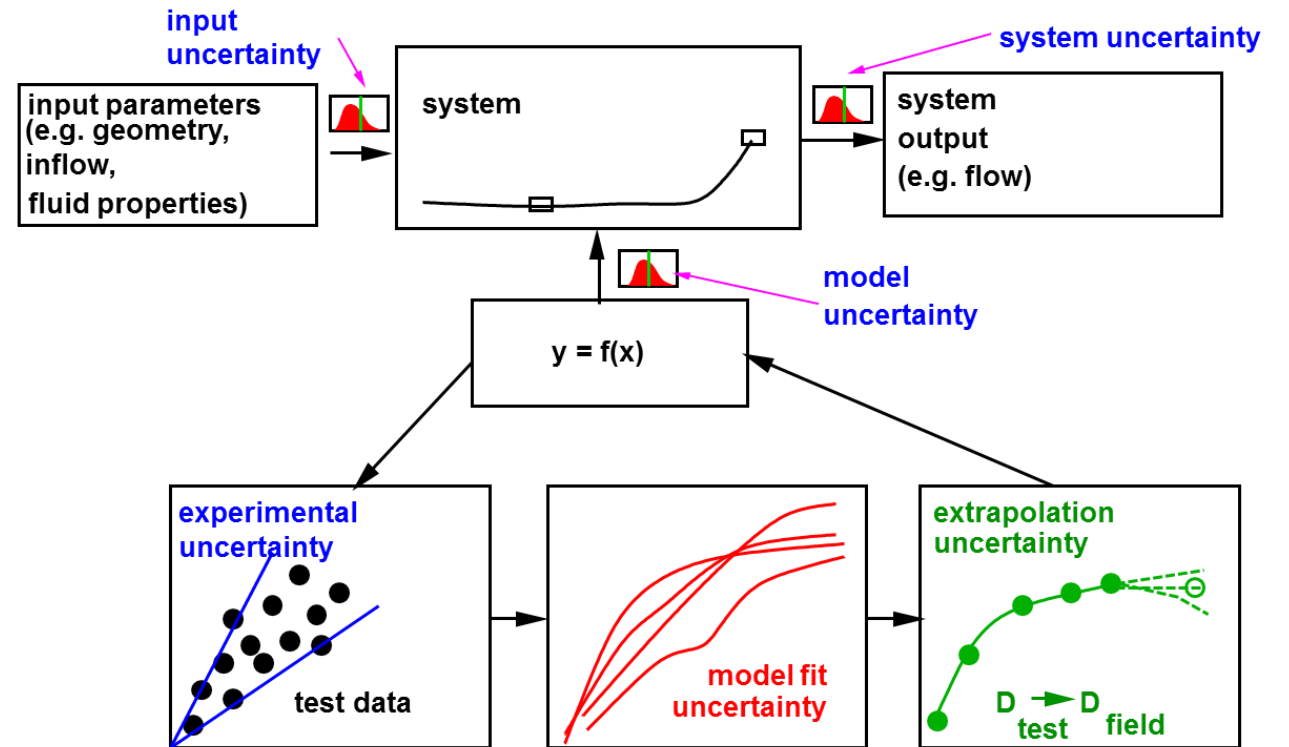
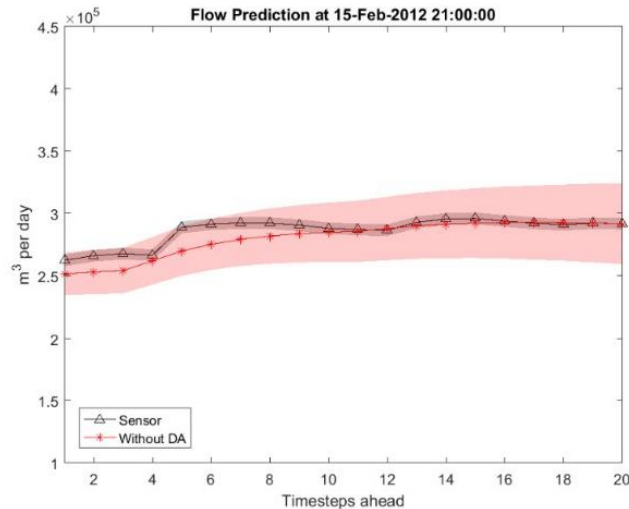
› Clear need for predictive models to improve operation

- › Accurate and robust
- › Computationally efficient
- › Requires less manual calibration and tuning



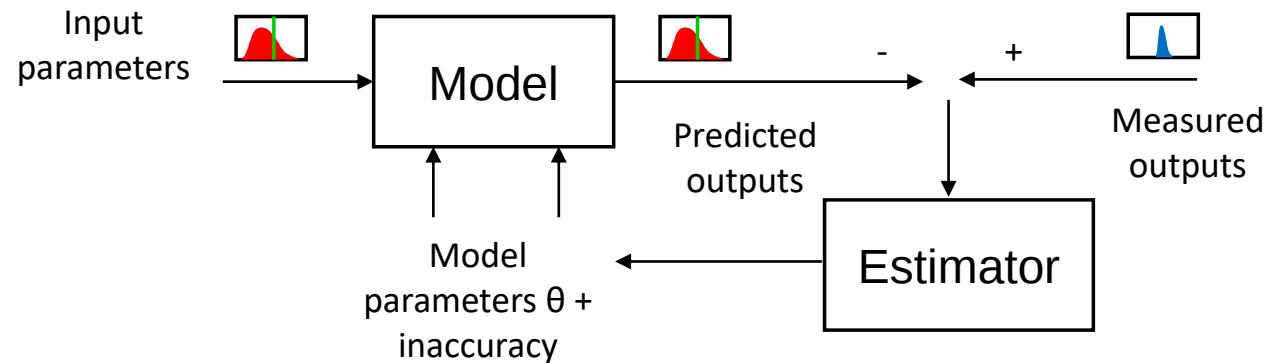
Uncertainties and Forecasts

- › Employing forward model for forecast
 - › Physics-based model
 - › Data-driven
- › Uncertainties and errors inherent in
 - › Measurements; irreducible
 - › Models (parameters); reducible

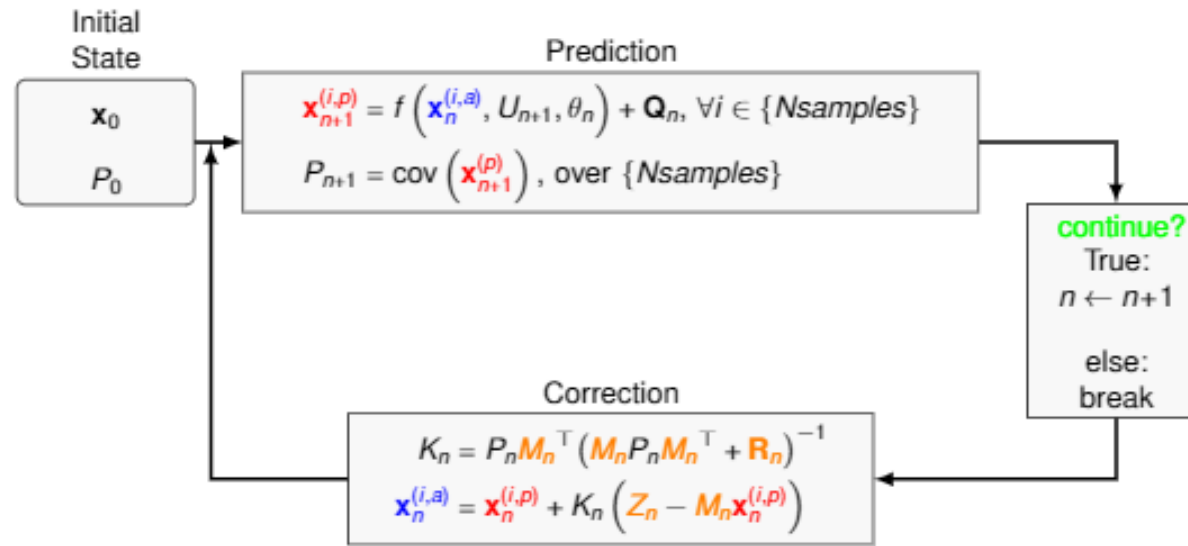


Objective

- › Goal: Workflow development for production forecast updated with measurements
 - › Cheap, robust and reliable production forecast model
 - › Requires less manual calibration
- › Most importantly to answer the question: Can this method help in improving forecasts from the forward models?
- › KPI for workflow effectiveness



Methodology – Ensemble Kalman Filter



- › The EnKF algorithm is essentially a predictor-corrector method. The prediction model in the figure is f .
- › The algorithm first starts to predict the state of the system, given assumed values of the model parameters (i.e. the **prior** state).
- › When **data** at the same timestep of the prediction are available, a correction is made (weighted least squares). We then have the **posterior** state, which we use for the predictions in the next timestep.

Forward model – Stacked LSTMs

- › Stacked LSTM as the forward model, with the following parameters
 - › Production rate; Q
 - › Tubing head pressure, Well head temperature; θ ,
 - › Choke opening; U
 - › Model weight and bias parameter, W ,

$$Q_{n+1} = f_{D-LSTM} \begin{pmatrix} Q_{n,n-1,...,n-35} \\ \theta_{n,n-1,...,n-35} \\ U_{n+1,n,...,n-34} \\ W \end{pmatrix}$$

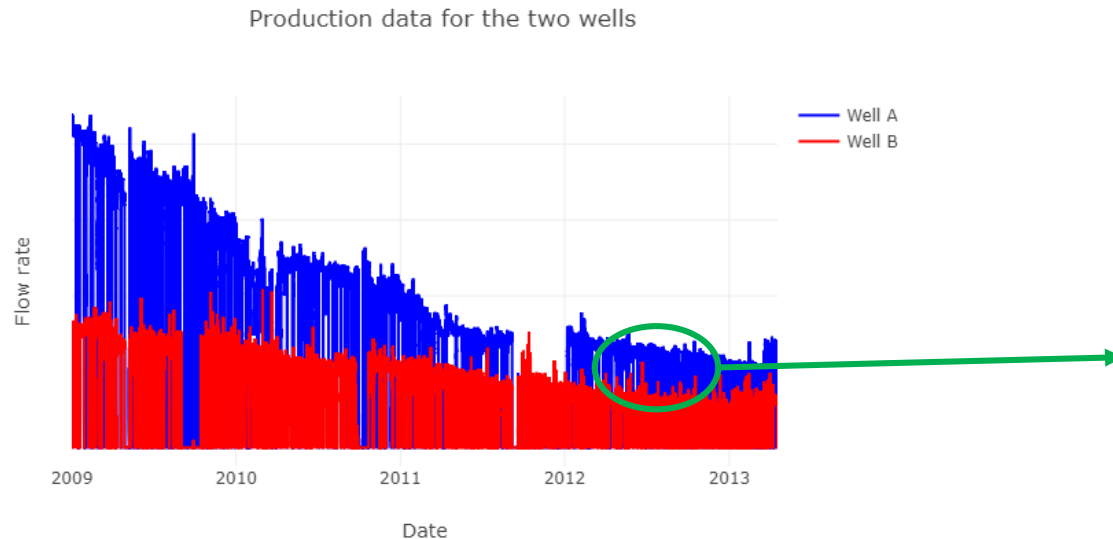
- › The state space representation of the system is then given by

$$x_{n+1} = \begin{pmatrix} Q_{n+1} \\ W_{n+1} \end{pmatrix} = f(x_n, U_{n+1}) = \left(f_{D-LSTM}(Q_n, \theta_n, U_{n+1}) + W_n \right)$$

Layer (type)	Output Shape	Param #
gaussian_noise_1 (GaussianNoise)	(None, 36, 6)	0
lstm_1 (LSTM)	(None, 36, 5)	240
lstm_2 (LSTM)	(None, 36, 5)	220
lstm_3 (LSTM)	(None, 36, 5)	220
lstm_4 (LSTM)	(None, 36, 5)	220
lstm_5 (LSTM)	(None, 36, 5)	220
lstm_6 (LSTM)	(None, 5)	220
p_re_lu_1 (PReLU)	(None, 5)	5
dense_1 (Dense)	(None, 5)	30
dense_2 (Dense)	(None, 1)	6
Total params: 1,381		
Trainable params: 1,381		
Non-trainable params: 0		

Dataset

- › Figure shows the entire production dataset for two mature wells in the North Sea from 2009 to mid 2013.
- › Dataset contains the Production rate, Tubing head pressures, Well head temperatures, and Choke settings for the period.
- › Can clearly see a decline in production rates due to salt formation for smaller time scales.

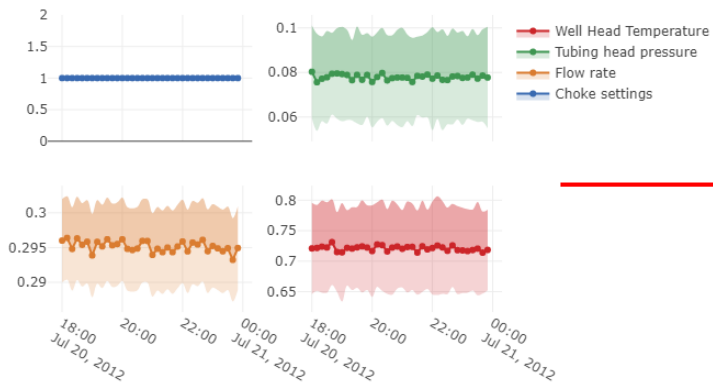


Uncertainties in dataset

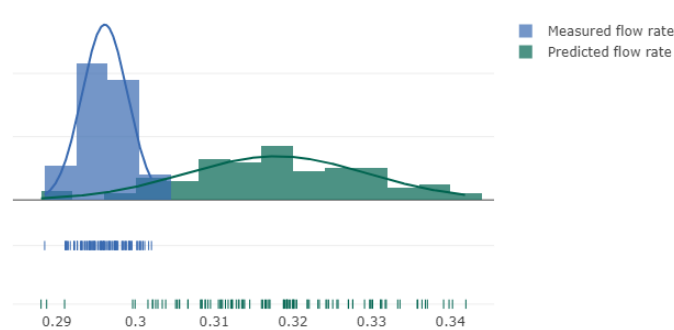
- › Add noise to the inputs scaled using the typical sensor sensitivities for each input variables.
- › Determine the distribution of the forecasts using Monte Carlo. This provides the baseline case.

Normalized Variable	Scaled Standard deviation
Flow rate	0.003
Tubing Head Pressure Sensor 1	0.01
Tubing Head Pressure Sensor 2	0.01
Tubing Head Pressure Sensor 3	0.01
Temperature	0.04
Choke settings (valve opening)	0 (Assumed perfect)

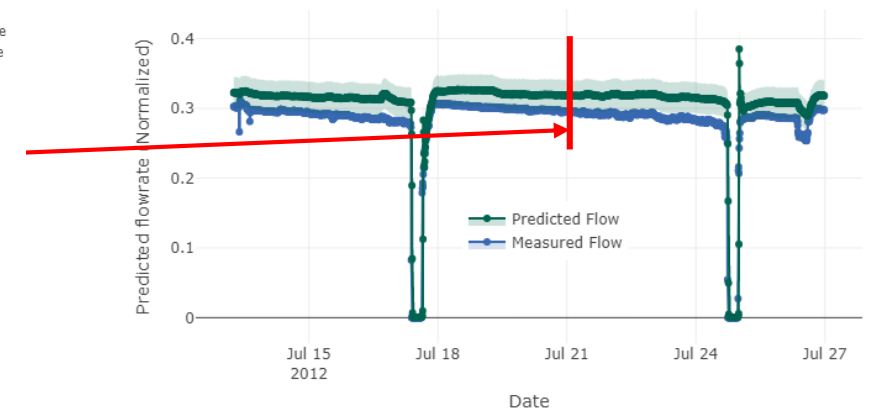
Inputs for predicting the flow rate on 2012-07-21 00:00:00



Distributions for the predicted and measured flowrates on 2012-07-21 00:00:00



Baseline model predictions, KL-div=36.22



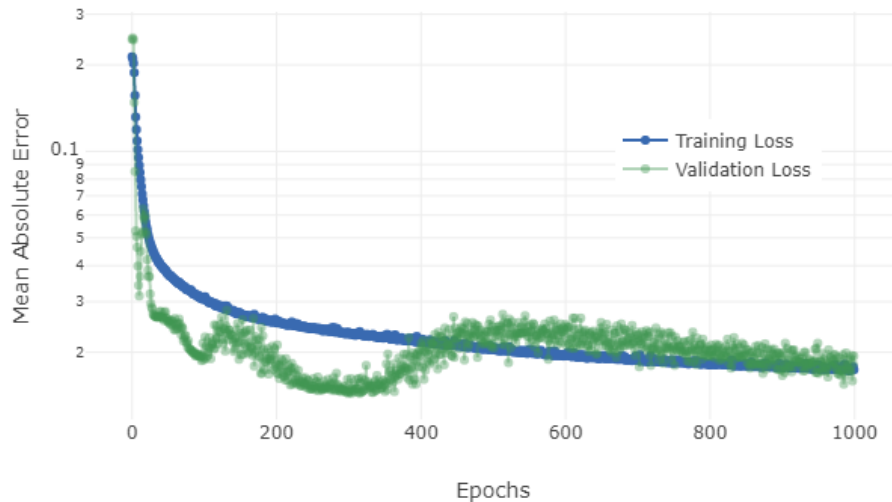
Overview of cases

- › Workflow was tested on two cases
 - › Mature gas asset in North Sea, suffering from salt precipitation
- › Case I.
 - › Training the forward model on Well A
 - › Forecasting the production of Well A
- › Case II.
 - › Training the forward model on Well A
 - › Forecasting the production of Well B

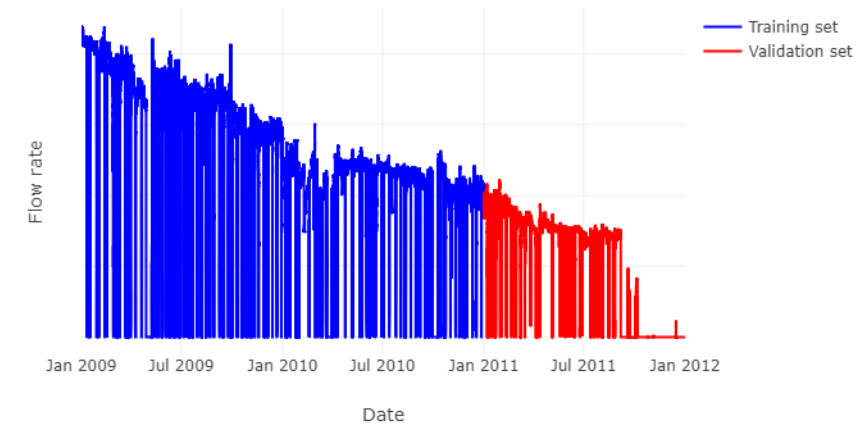
Case I: Train Well A, Test Well A

- › The training is performed on Well A dataset from 2009 to 2011
- › Testing is performed on Well A in the period of Jul 13 - 27, 2012
- › Initial model parameters (bias) uncertainties estimated in the training phase

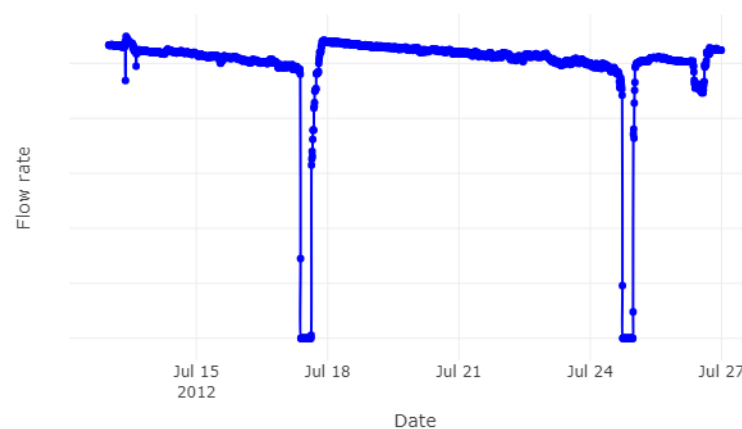
Model losses (on Well A, 2009 to 2011)



Flow rate for Well A

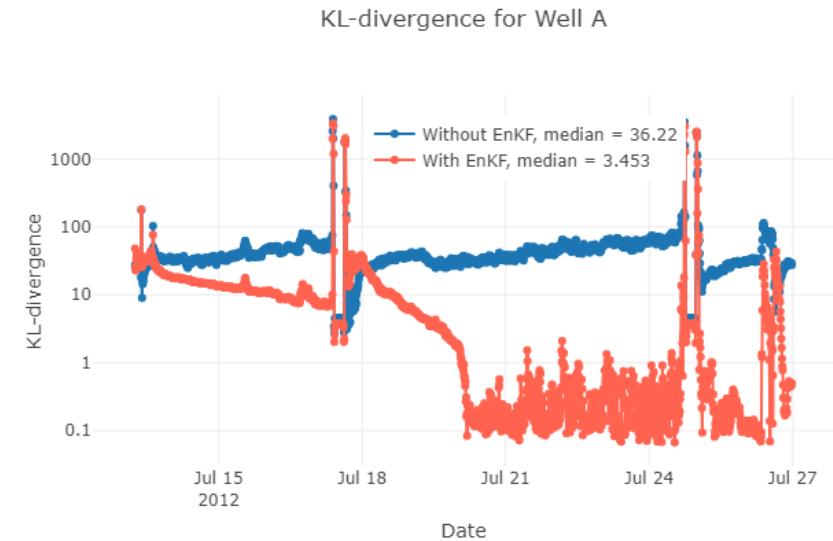
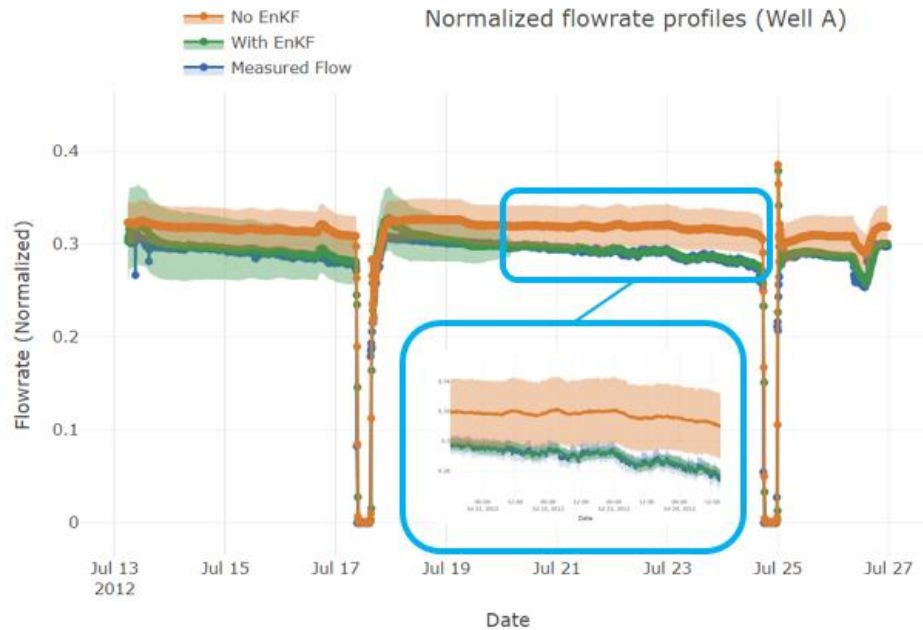


Flow rate for Well A



Results: Case I

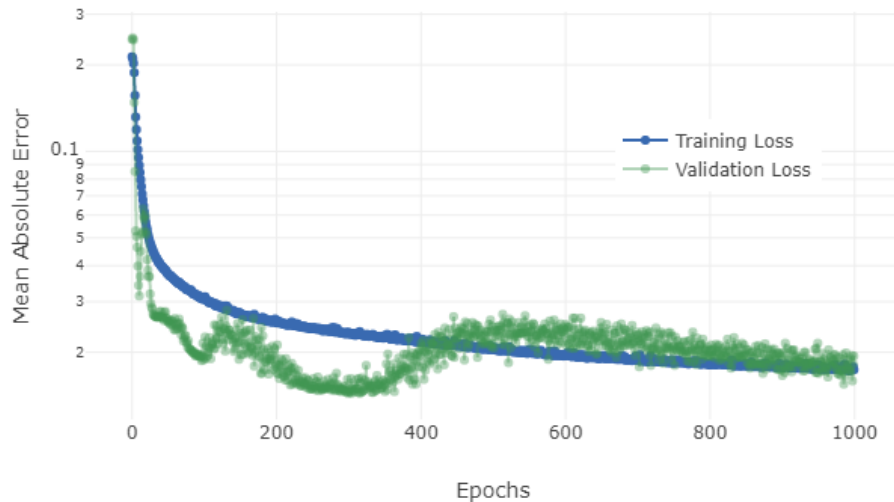
- › Prediction results show that local bias errors are corrected.
- › Better Kullback-Liebler divergence compared with baseline model.



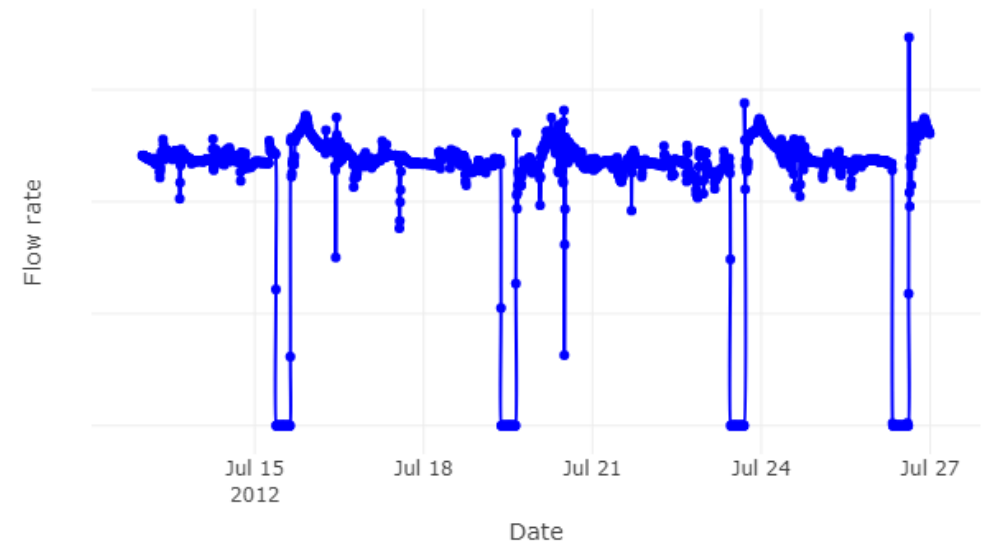
Case II: Train Well A, Test Well B

- › Reuse the model trained from dataset of Well A
 - › Avoid (sometimes computationally expensive) retraining of forward model
- › Test dataset (same period) on Well B data

Model losses (on Well A, 2009 to 2011)

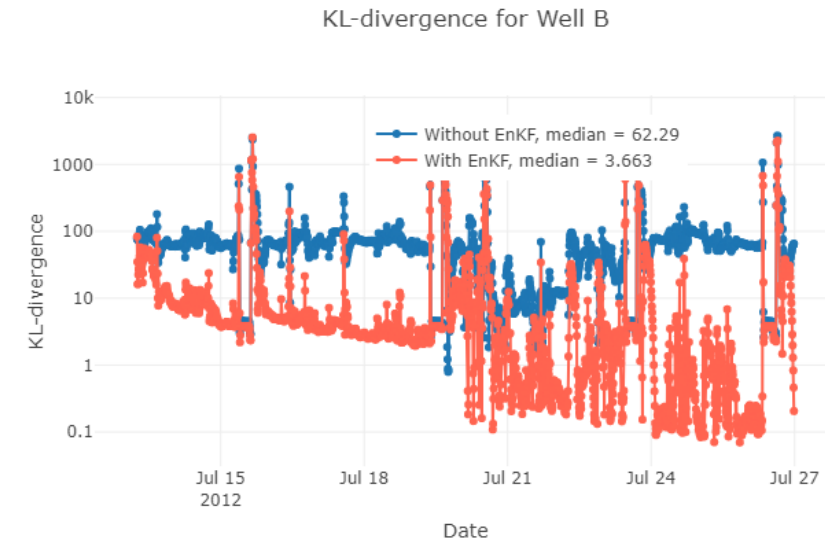
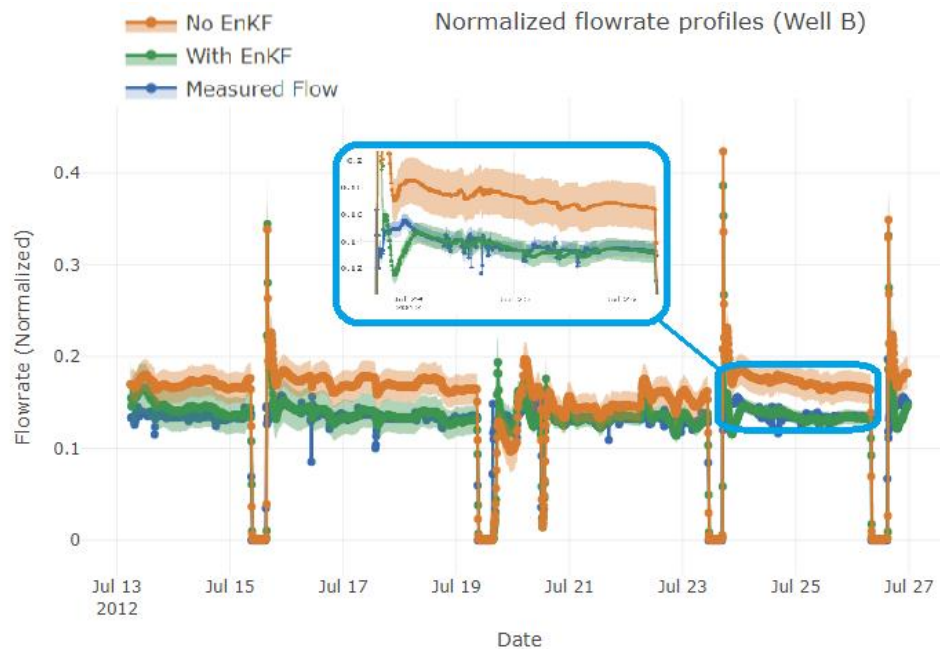


Flow rate for Well B



Results: Case II (1/2)

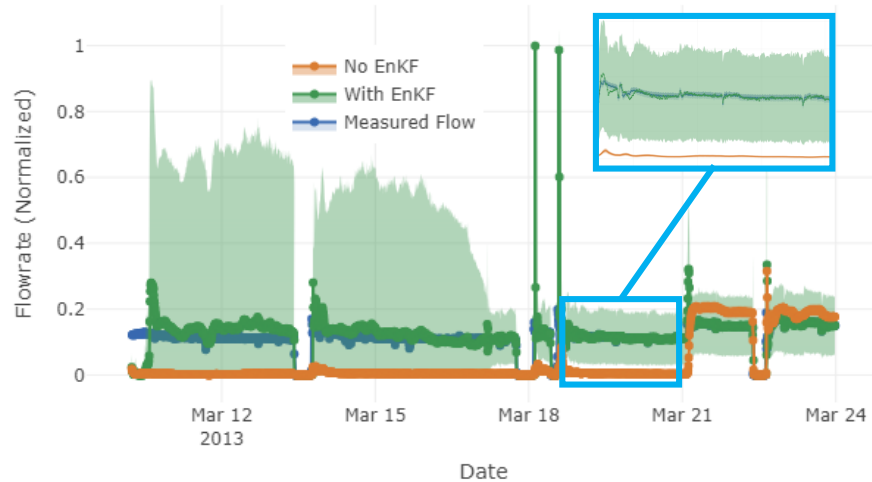
- Figure shows localized bias errors have been corrected. Moreover, uncertainties with the forecasts are also reduced.



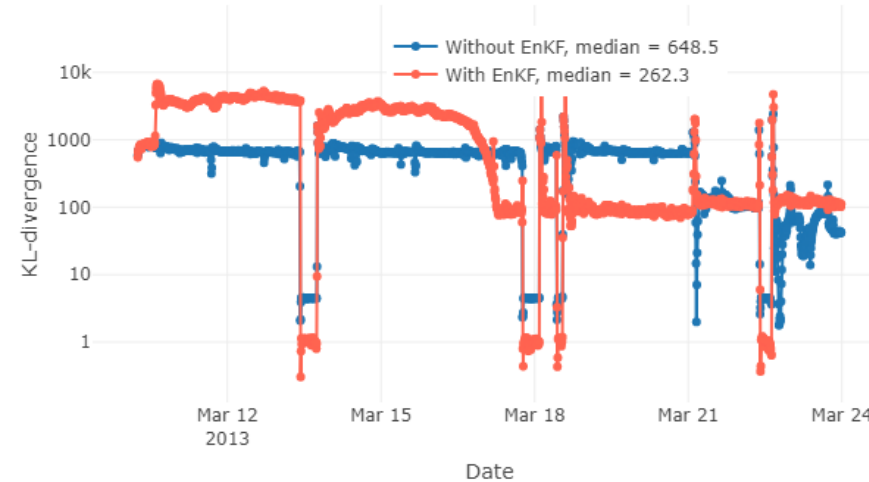
Results: Case II (2/2)

- › Test also on a separate test period (March 10-24 2012) for Well B dataset.
- › In the mean sense, the forecasts have been improved. Shows clearly that once the filter has settled, uncertainties are still relatively high. KL-divergence potentially can indicate need for retraining.

Normalized flowrate profiles (Well B)



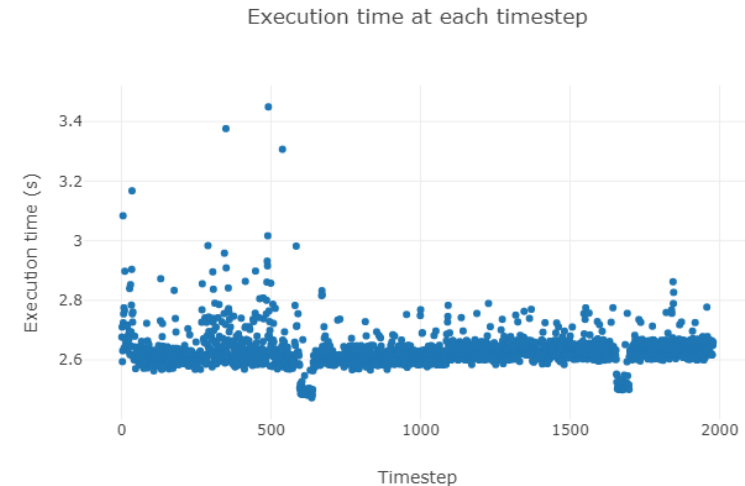
KL-divergence for Well B



Results: Case I-II (Timings)

- › Training performed on GTX1080 gpu, approximately ~ **5 hr**
- › For performance testing, the model was deployed in a laptop with core i7-4810MQ with 16 GB ram.
- › Each timestep takes about **3 seconds** (including data assimilation). Which means that the algorithm can be deployed in a real-time production optimization framework.

Processor: Intel(R) Core(TM) i7-4810MQ CPU @ 2.80GHz 2.80 GHz
Installed memory (RAM): 16.0 GB
System type: 64-bit Operating System, x64-based processor



Conclusions

- › Cheap and accurate models for production predictions, including the uncertainties in data
- › Reduce the prediction uncertainties by incorporating new measurements/observations
- › No retraining required, as long as the production trends are similar
- › Generic workflow which could also be used as an operation support system (KPI, alarms,...)

Way forward

- › Implementing the workflow in real-time (robust auto-tuned live forecast)
- › Apply methodology to predict performance of other components in the production
 - › Compressor, turbine performance degradation prediction

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Pejman.shoeibiomrani@tno.nl

Kelvin.loh@tno.nl

[arXiv:1802.05141](https://arxiv.org/abs/1802.05141)