

Towards Adaptive Simulation of Dispersive Tsunami Propagation from an Asteroid Impact

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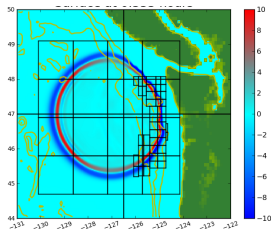
Tsunami Propagation

Overview:

- Impact tsunamis have shorter wavelengths than earthquake tsunamis; shallow water model not appropriate
- For ocean-scale propagation want depth-averaged velocities, reducing simulation from 3 \rightarrow 2 dimensions
- Boussinesq models include dispersion, need elliptic solve each time step. (This work uses Madsen and Shaffer).

Still need AMR:

- In deep ocean only need resolution of kilometers
- For coastal inundation want resolution of meters



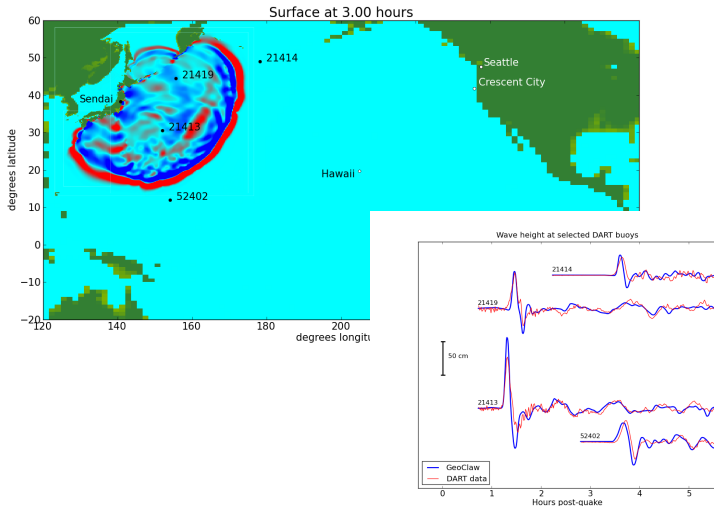
Strategy: Boussinesq in deep ocean, switch to SWE near coast

Based on [Clawpack](http://www.clawpack.org) (www.clawpack.org)

- 2d library for depth-averaged flows over topography.
- Handles dry cells where $\text{depth} = 0$.
- Well-balanced Riemann solvers for small amplitude waves on ocean at rest.
- Well balancing and dry cells in conjunction with adaptive refinement.
- Well validated for earthquake-generated tsunamis.
- **Other applications:**
 - Debris flows (Dave George, USGS — [D-CLAW](#))
 - Storm surge (Kyle Mandli, Columbia)
 - Dam breaks / river floods (DG, M. Turzewski, UW, D. Calhoun, Boise State — [ForestClaw](#))

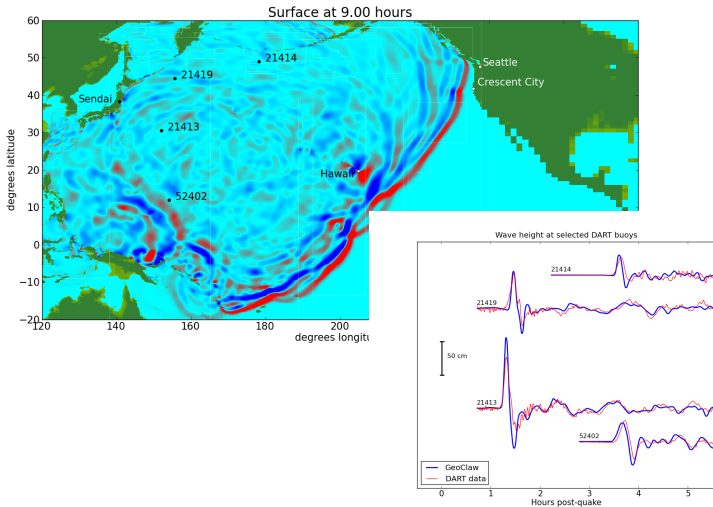
DART Buoys — Tohoku 2011

Deep Ocean Assessment and Reporting of Tsunamis

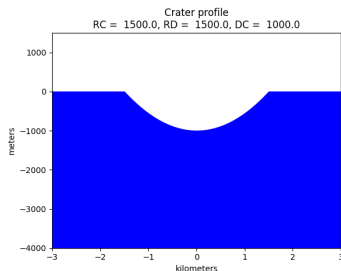


DART Buoys — Tohoku 2011

Deep Ocean Assessment and Reporting of Tsunamis



Asteroid Impact Tsunami – Static crater test case



Our tests used the crater with no lip as initial data.

Depth of crater: 1000 m, Depth of ocean: 4000 m.

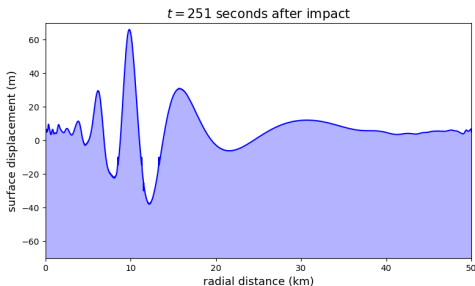
Initial conditions for 2D Boussinesq:

Full 3D multi-physics hydrocode (ALE3D) was run in 2D axisymmetric mode for this simplified initial condition.

(Darrel Robertson, NASA Ames Research Center).

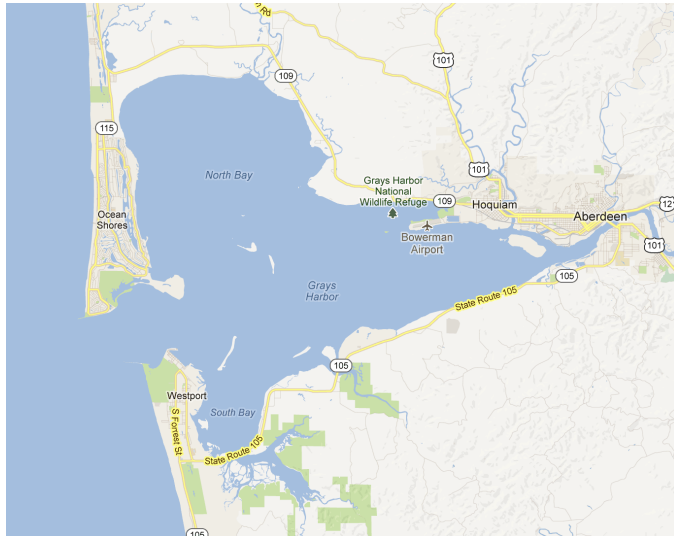
Asteroid Impact Tsunami – Static crater test case

Surface at $t = 251$ seconds transferred as radially-symmetric initial data for depth-averaged Boussinesq.

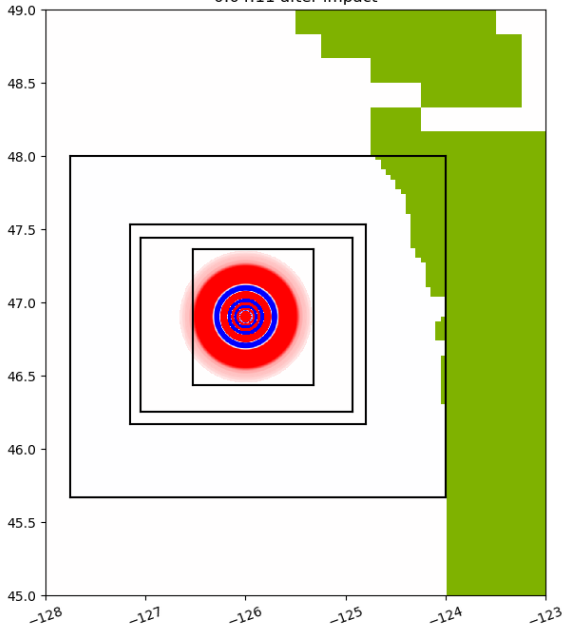


Impact placed ≈ 150 km off Washington coast.

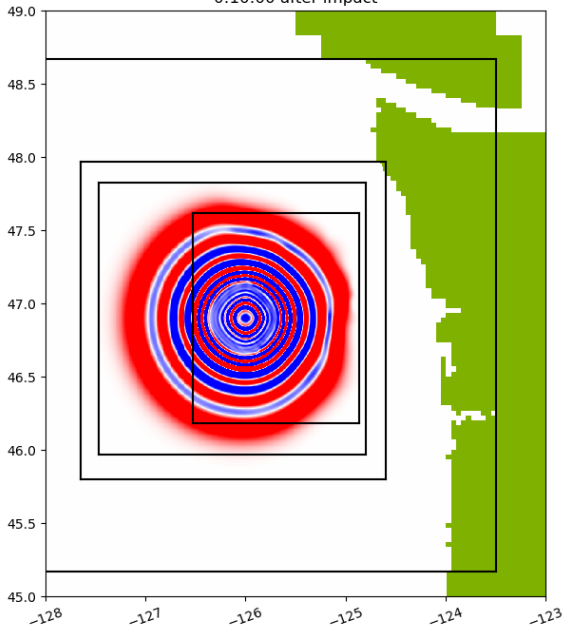
Grays Harbor



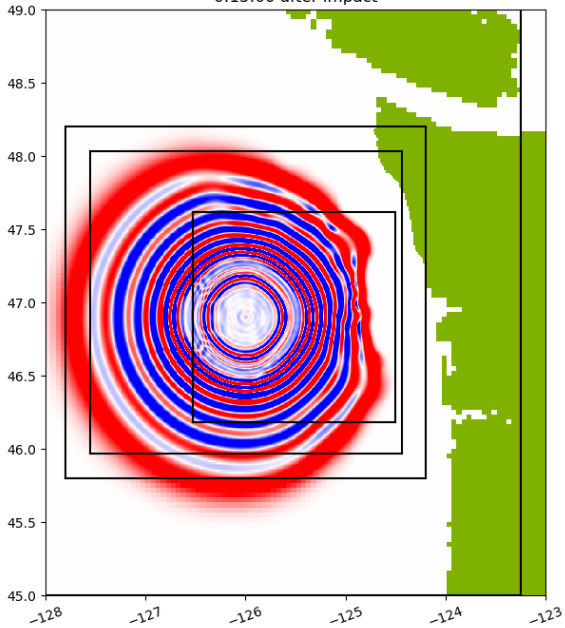
0:04:11 after impact



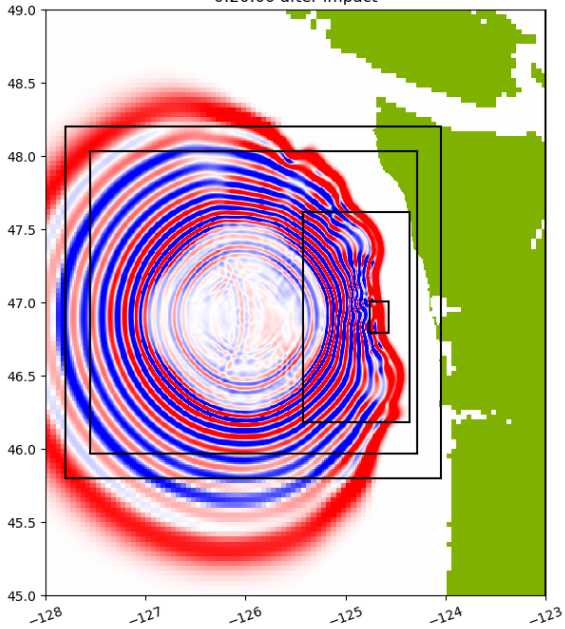
0:10:00 after impact



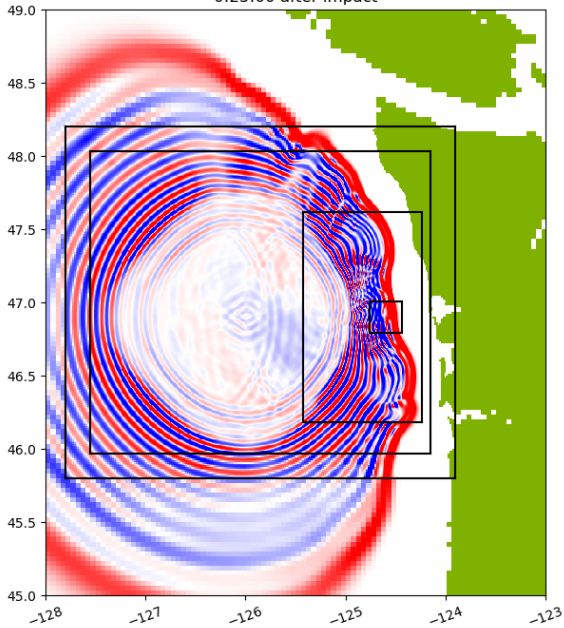
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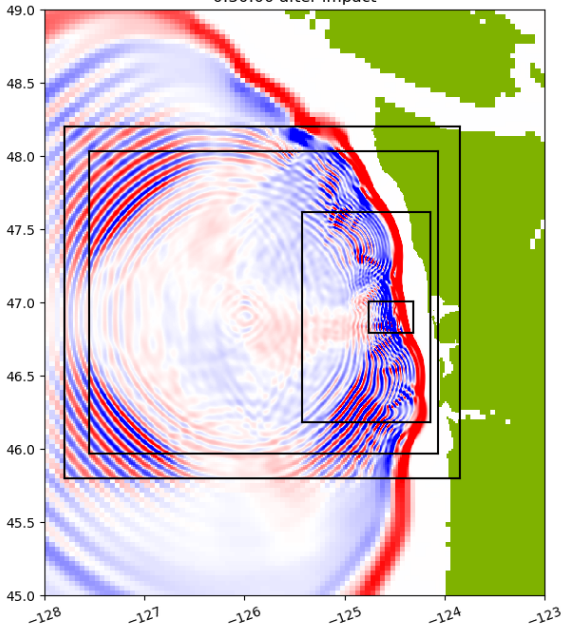
0:20:00 after impact



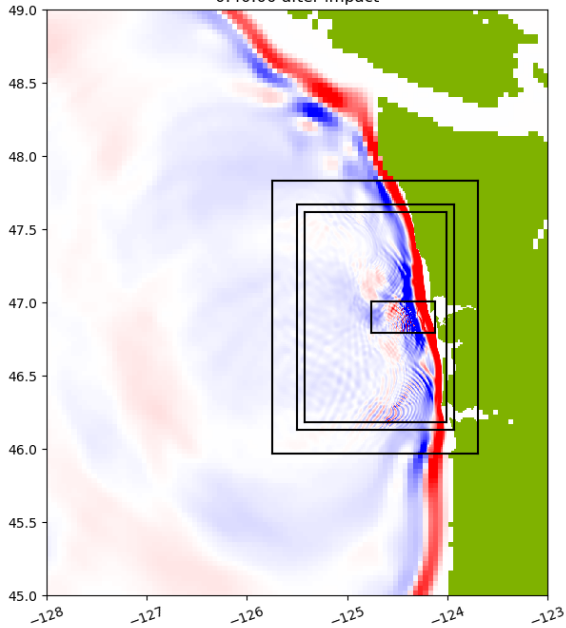
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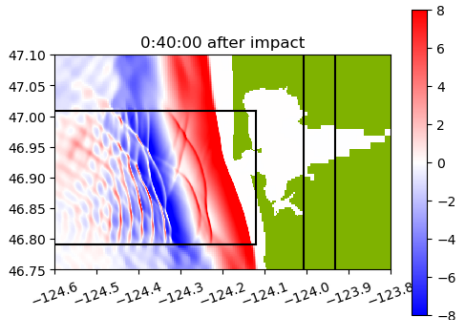
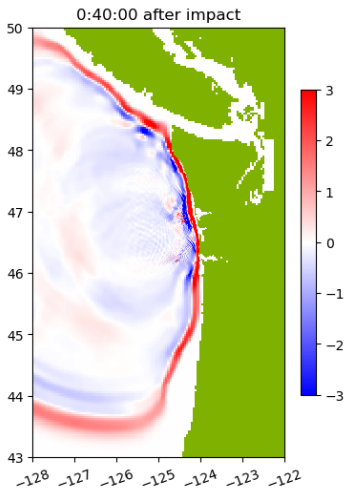


0:30:00 after impact

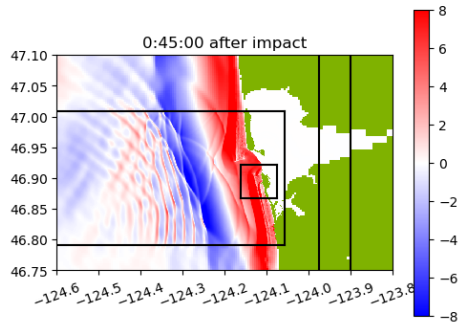
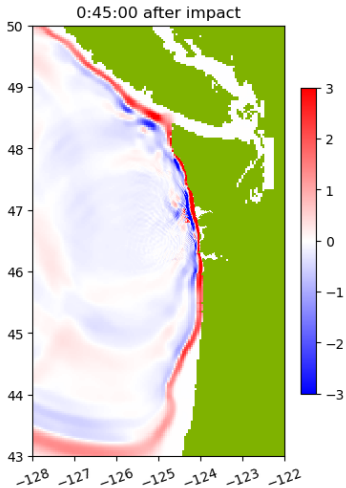


0:40:00 after impact

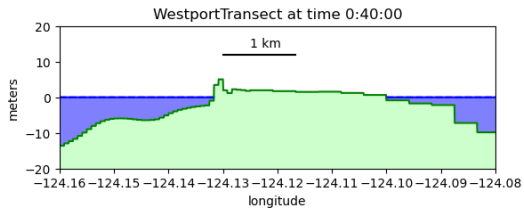
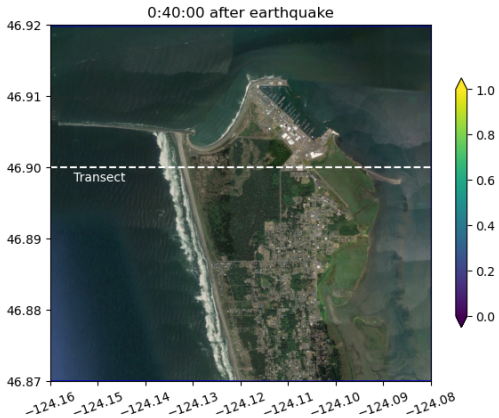


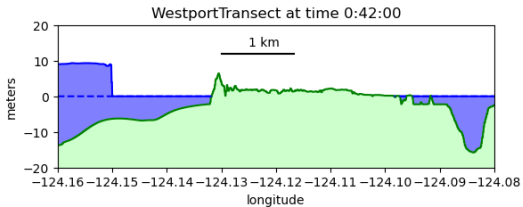
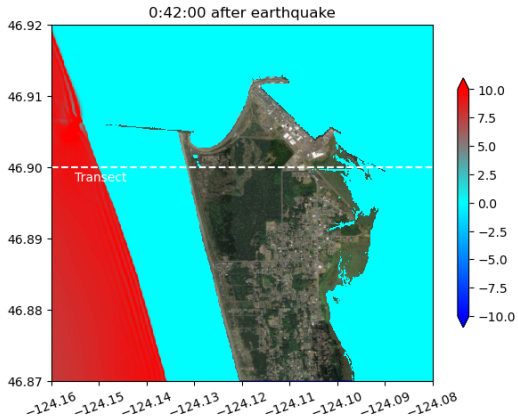


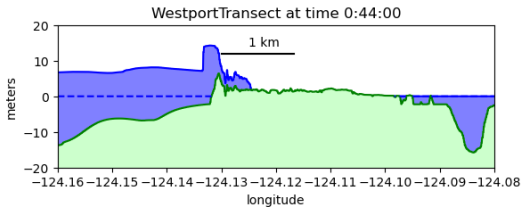
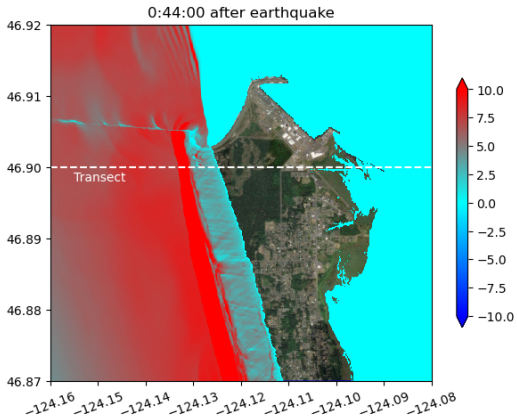
Dispersion leads to
“soliton fission” near coast.

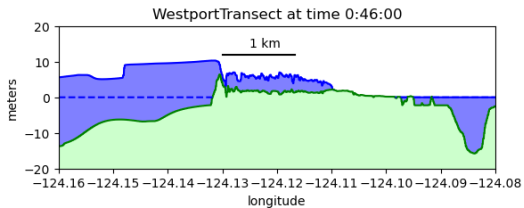
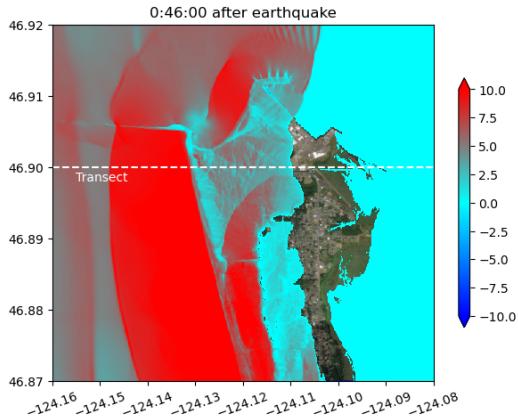


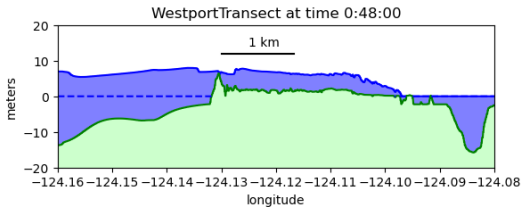
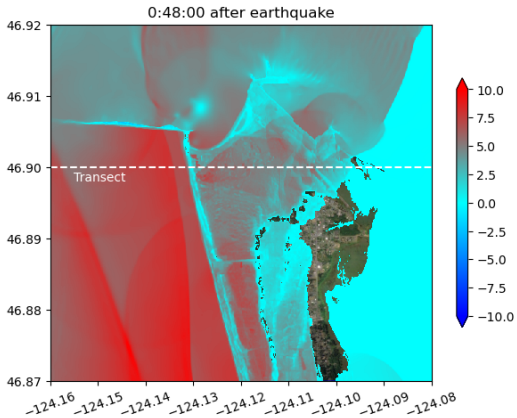
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Fractional step method

$$\begin{aligned}h_t + (hu)_x &= 0 \\(hu)_t + (hu^2)_x + gh\eta_x &= \psi\end{aligned}$$

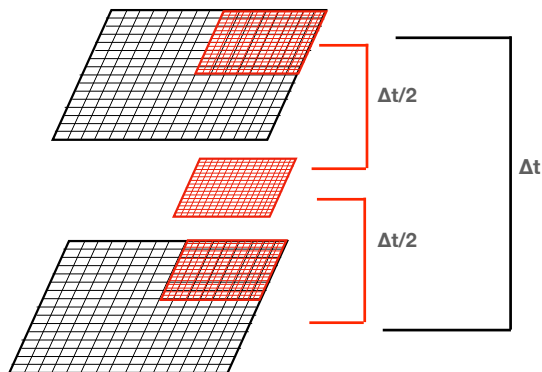
- 1 Solve elliptic equation for source term ψ :

$$[I - D_{11}]\psi = -D_{11} [(hu^2)_x + gh\eta_x] + gh_0^2 B_1 (h_0 \eta_x)_{xx}.$$

⇒ Difficulties for AMR algorithms.

- 2 Update momentum by $(hu)_t = \psi$ over time step
- 3 Take step with homogeneous SWE.

Patch-Based Adaptive Mesh Refinement



Ghost cells on border of level 2 (red grids) interpolated in space and time from level 1 (black grids), including extra variable ψ .

Conclusions and Future Work

Demonstrated: proof of concept using both Boussinesq and Shallow Water model combined with AMR.

But: cannot yet tell how much difference it makes for shoreline inundation; earlier 1D parameter studies showed significant differences

- How much does it depend on switching criteria?
 - Currently switching at 10 meter depth
 - Have not included “wave breaking” criteria yet
- Make more robust
 - Some stability problems at patch edges
- Compare with other Bouss models
 - ForestClaw + Serre-Green-Naghdi

